



A Field Perspective on Pneumatic Control and Actuation Systems

Control System Building Blocks – Part 2



Presented By:

David Sellers

Senior Engineer, Facility Dynamics Engineering

Previously

On Control System Building Blocks

*Automatically **adjust a piece of machinery** to give us what we want by comparing **what is going on** to what we want to go on and **making appropriate adjustments** to the process we want to control*

Inputs

Measure the process variable

Previously

On Control System Building Blocks

*Automatically **adjust a piece of machinery** to give us what we want by comparing **what is going on** to what we want to go on and **making appropriate adjustments** to the process we want to control*

Inputs

Outputs

Measure the process variable

Adjust the controlled variable

Previously

On Control System Building Blocks

*Automatically **adjust a piece of machinery** to give us what we want by comparing **what is going on** to what we want to go on and **making appropriate adjustments** to the process we want to control*

Inputs

Outputs

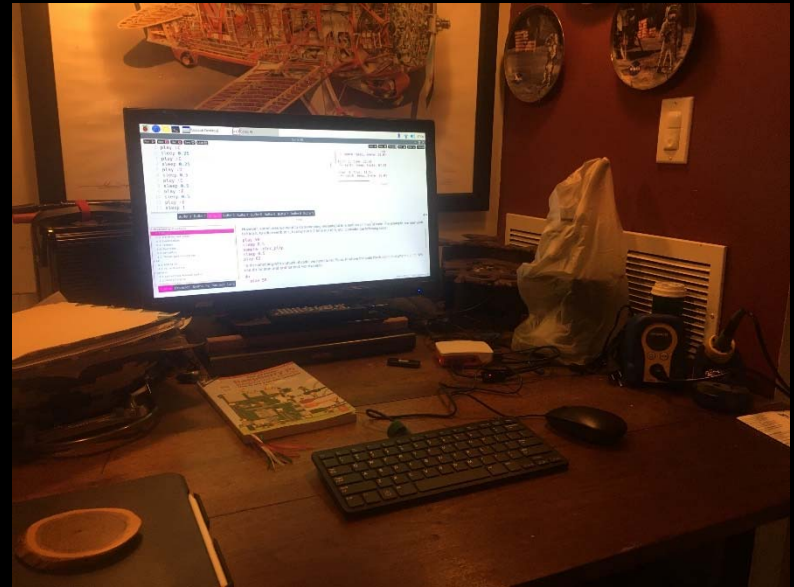
Control Process

Measure the process variable

Adjust the controlled variable

Logic and mechanisms that tries to bring the controlled variable into agreement with the set point

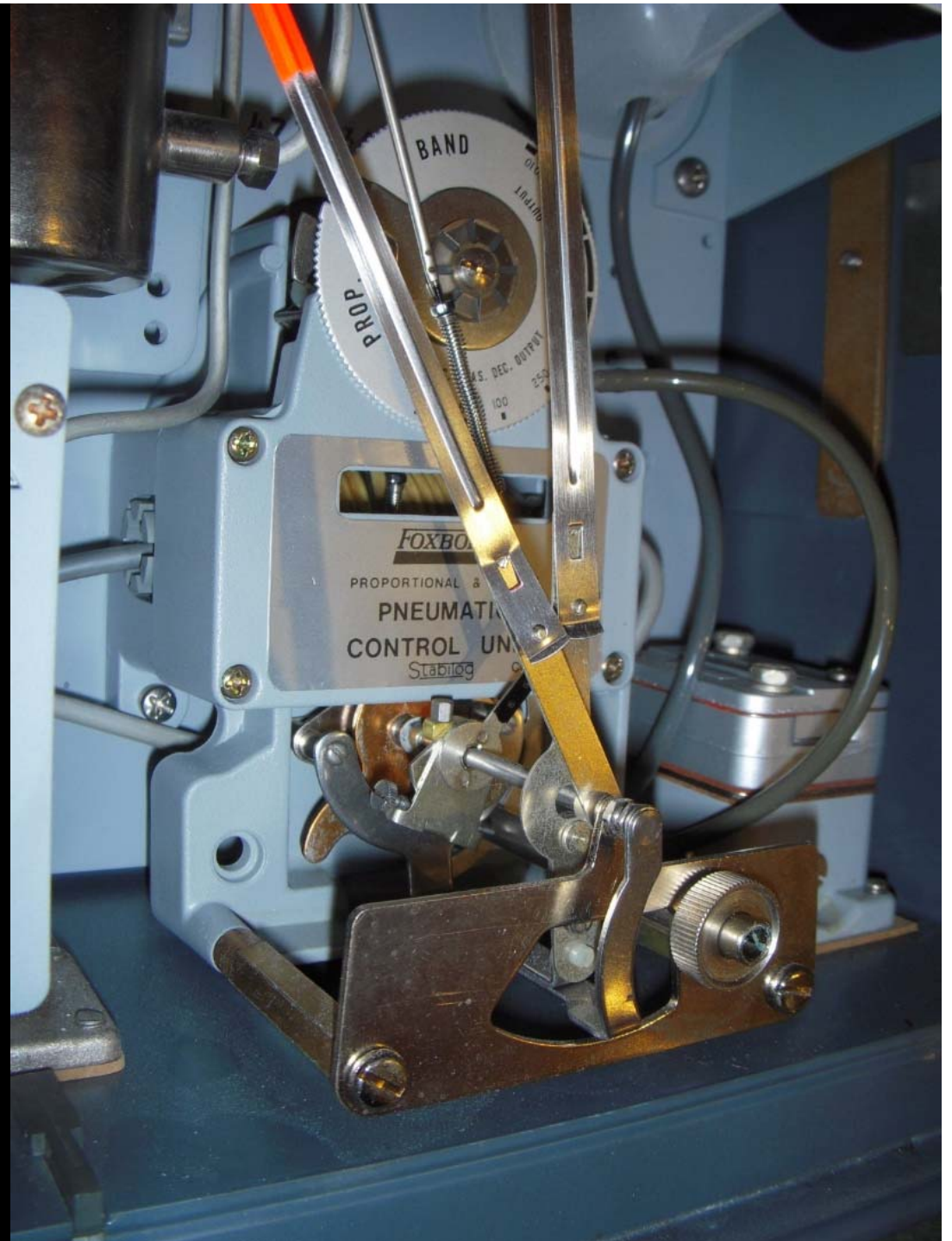
Digital Logic



Learn by doing

- <https://av8rdas.wordpress.com/2011/12/04/learning-about-relay-logic-build-your-very-own-jeopardy-game/>
- <https://av8rdas.wordpress.com/2011/12/19/making-a-jeopardy-game-board-in-powerpoint-to-supplement-your-light-and-buzzer-system-and-learning-a-bit-about-powerpoint-templates/>
- <https://www.raspberrypi.org/>

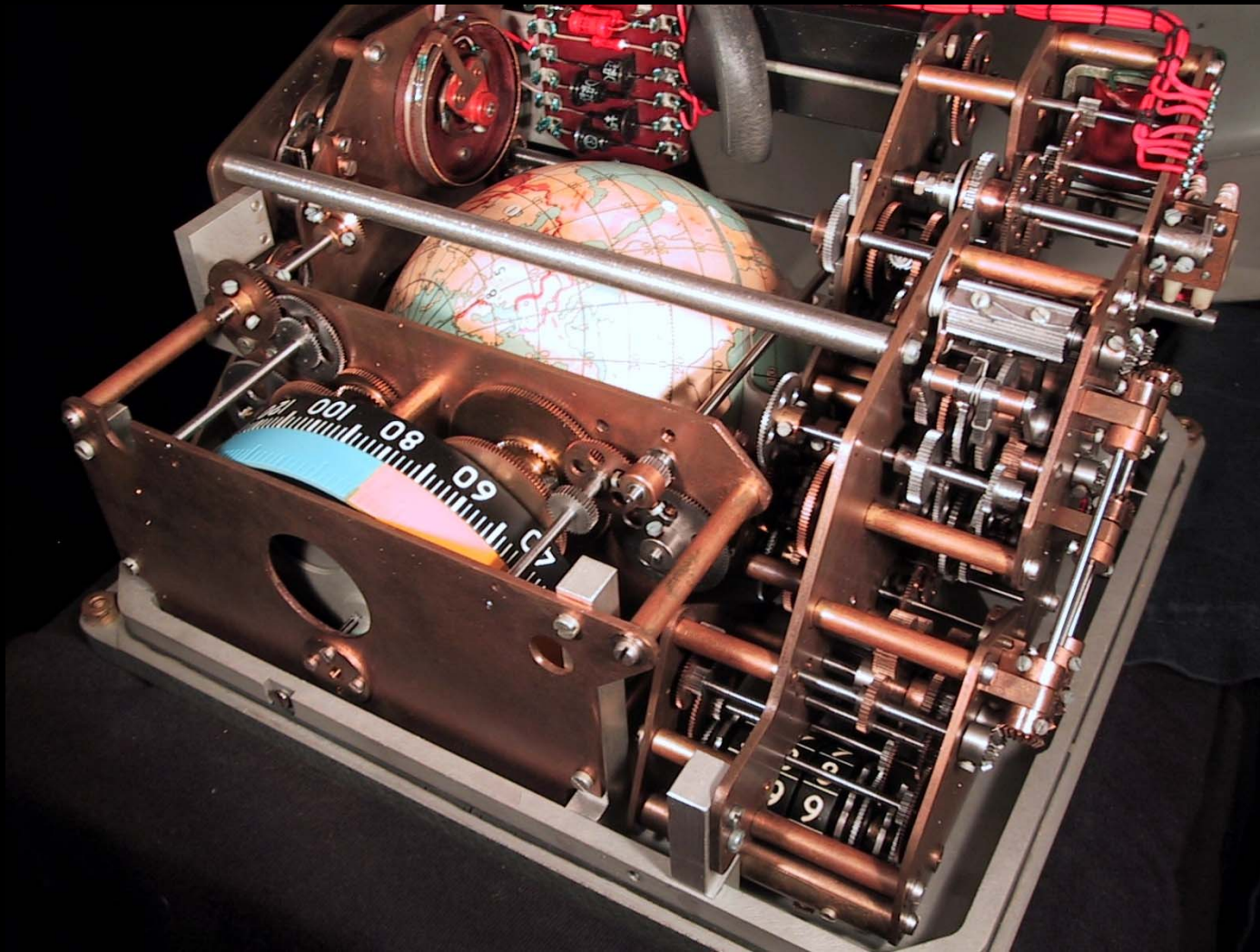
Analog Logic



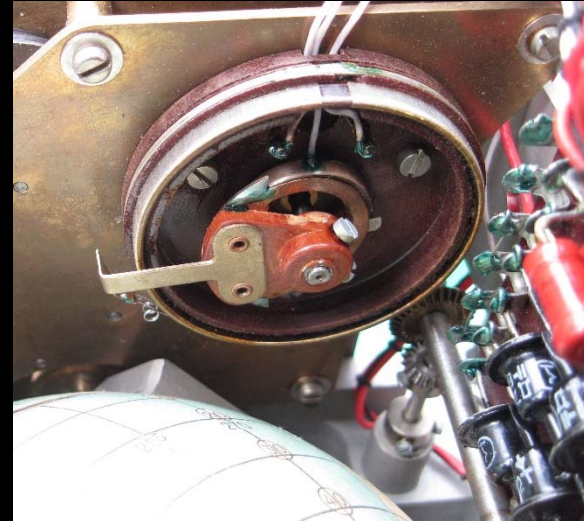
A Long, Long, Time Ago, in a Galaxy Far, Far, Away, Logic Was a Physical Thing



A Long, Long, Time Ago, in a Galaxy Far,
Far, Away, Logic Was a Physical Thing



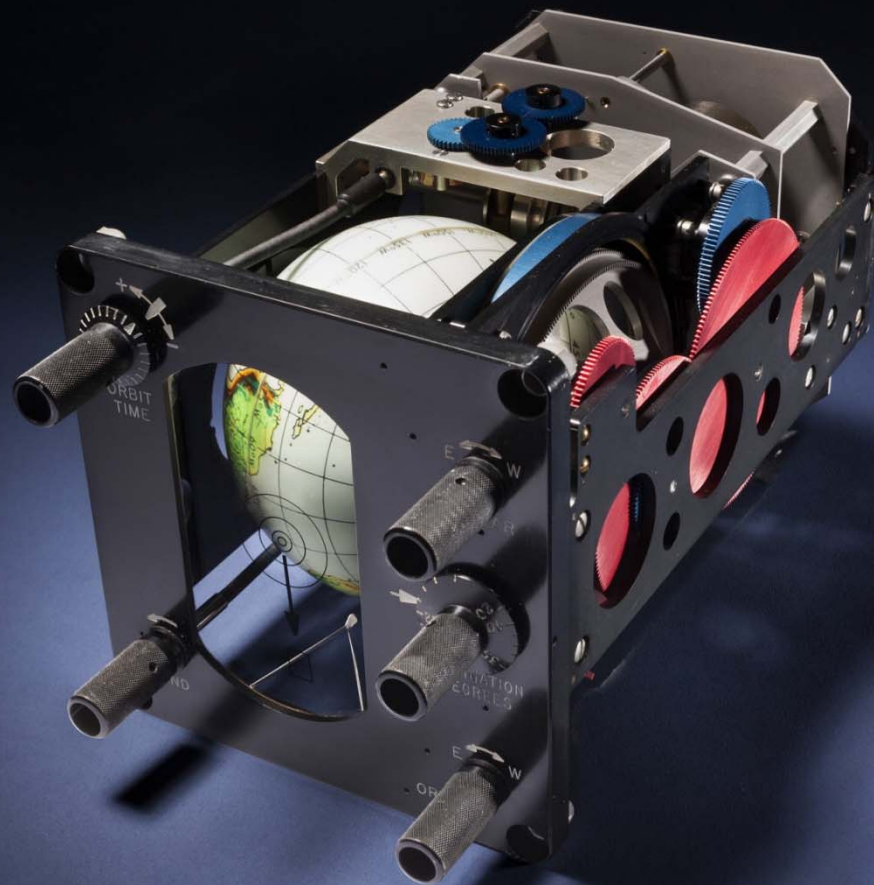
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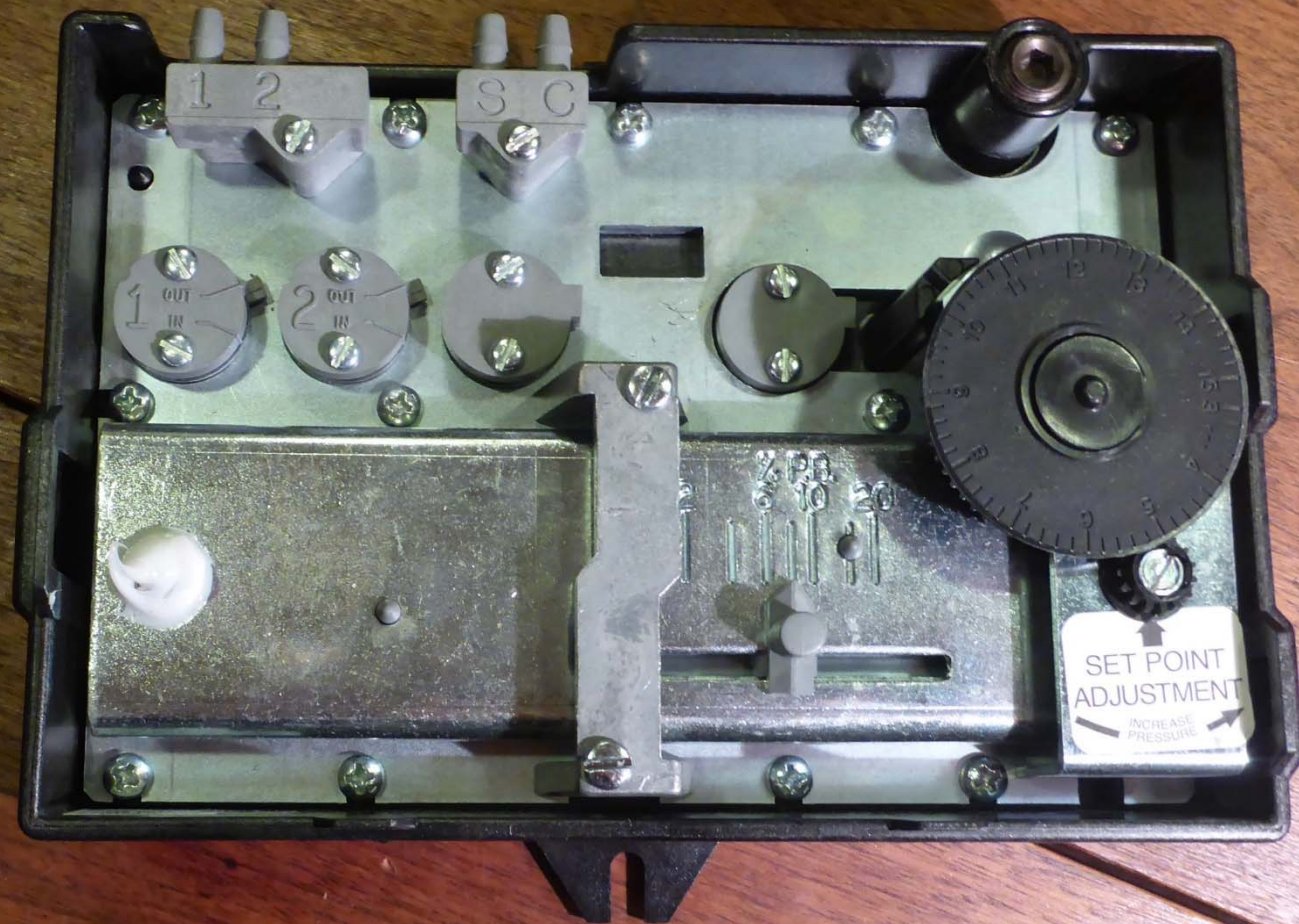


A Long, Long, Time Ago, in a Galaxy Far,
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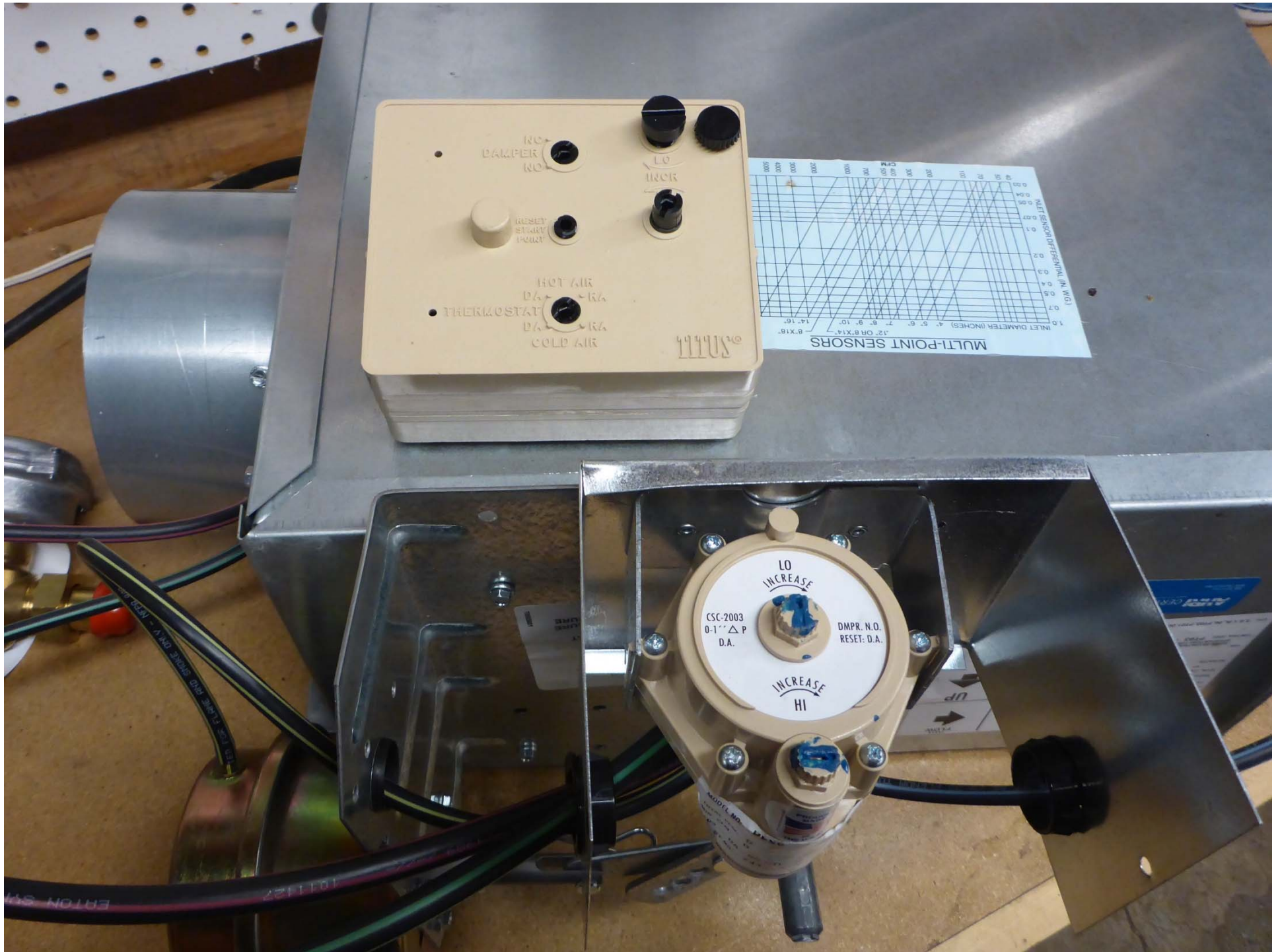
Analog Logic for Building Systems and Process Control in the Same Time Period







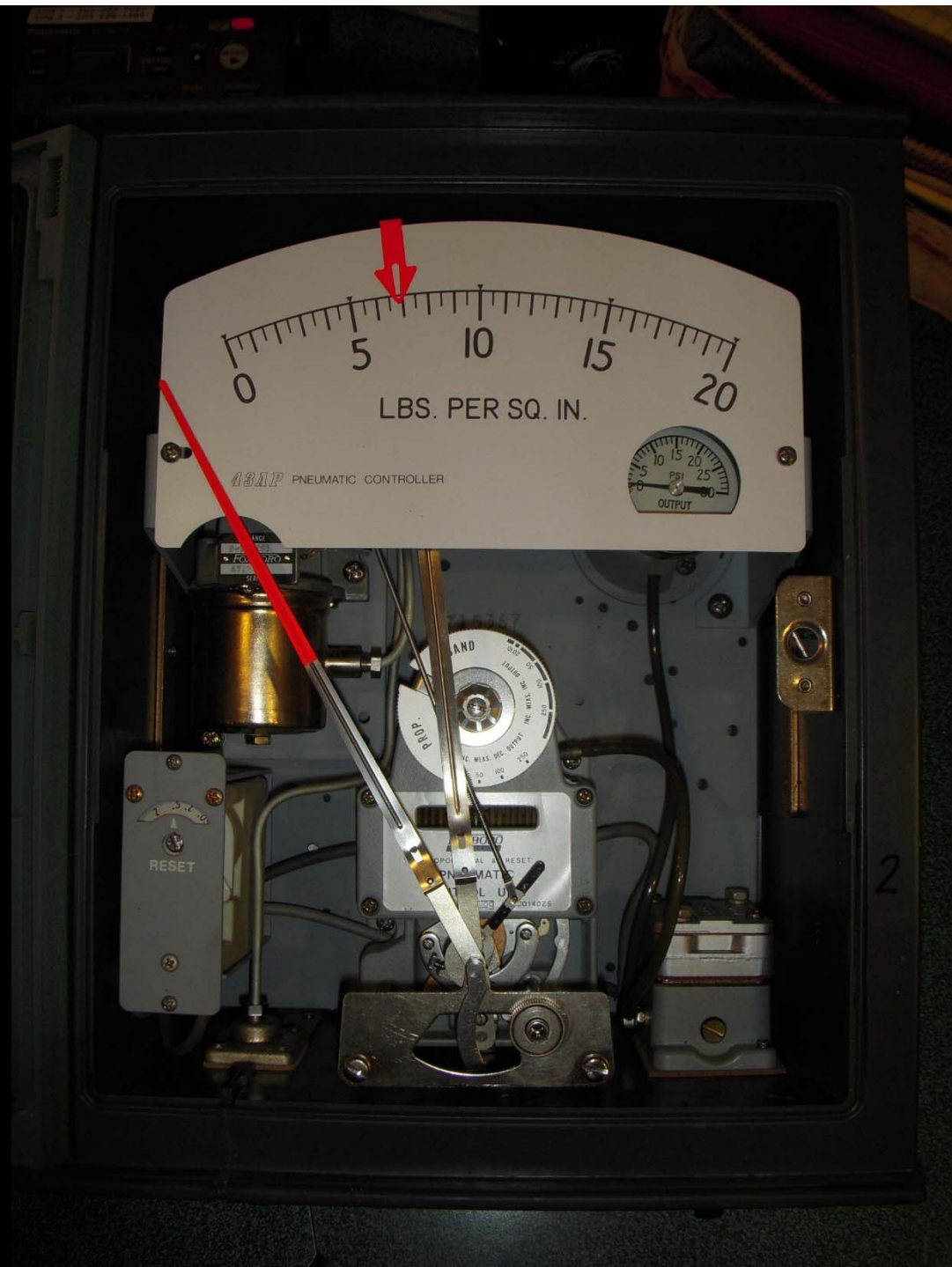


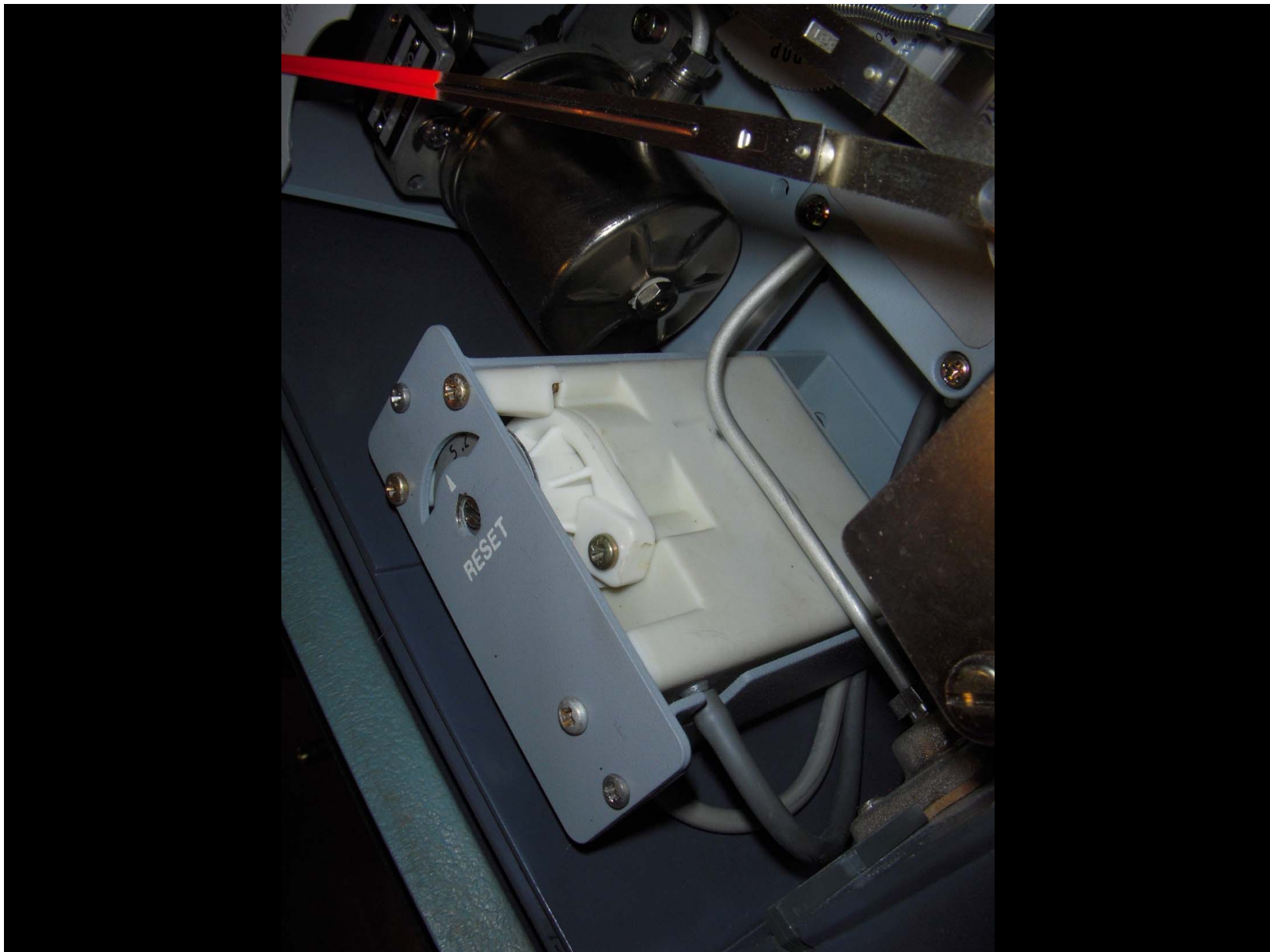


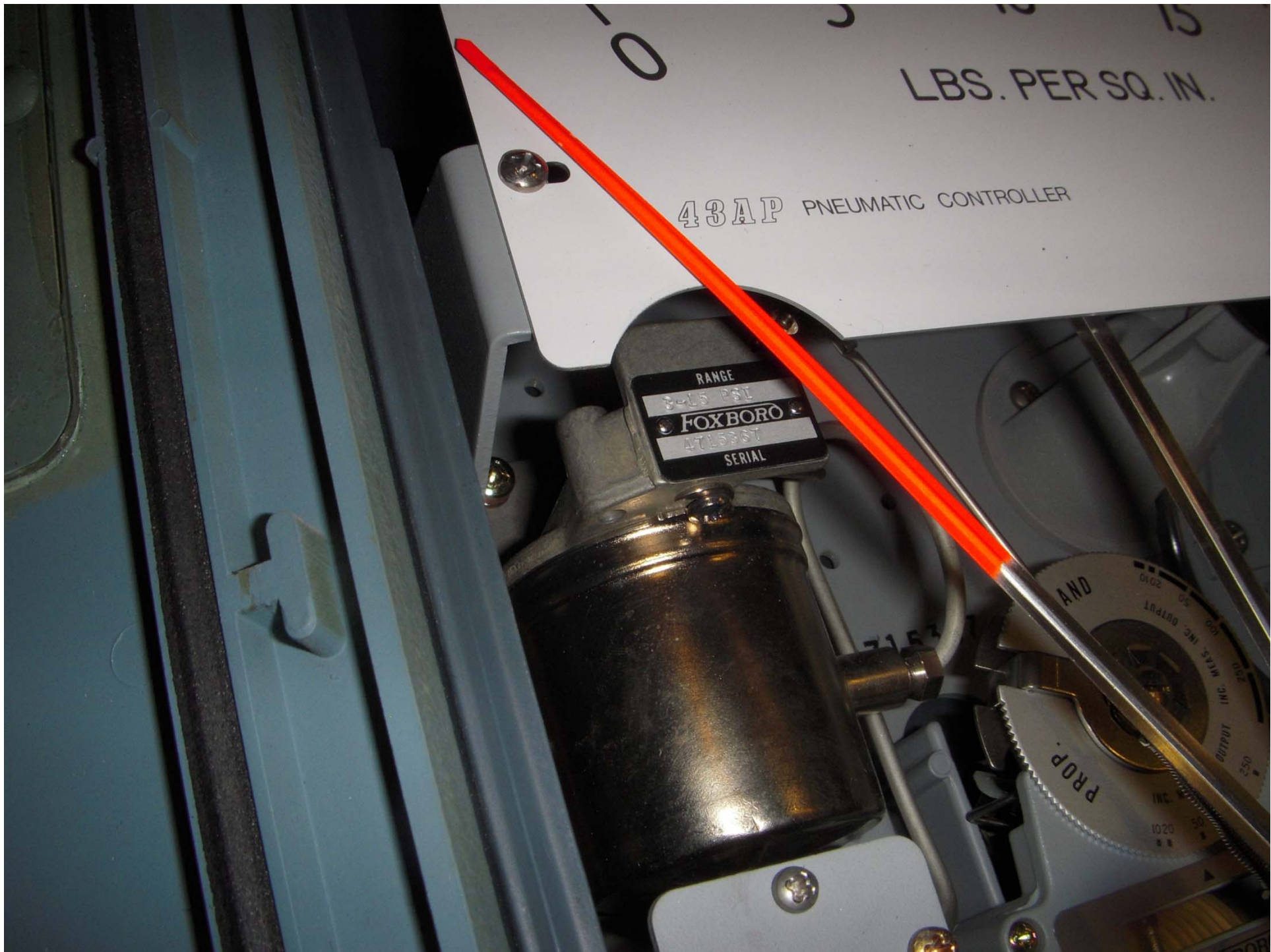
S-2



FOXBORO







LBS. PER SQ. IN.

43AP PNEUMATIC CONTROLLER

RANGE

3-15 PSI

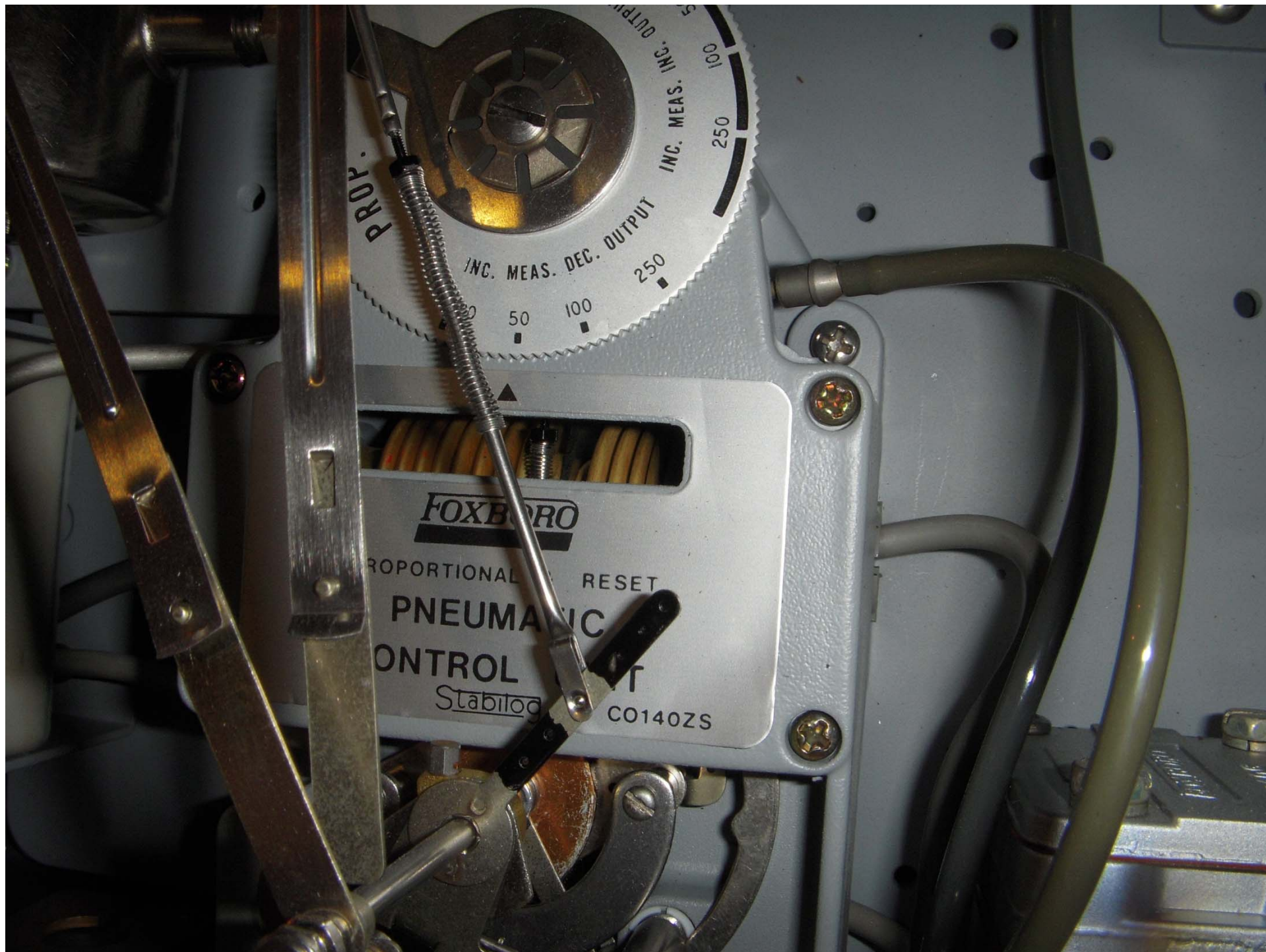
FOXBORO

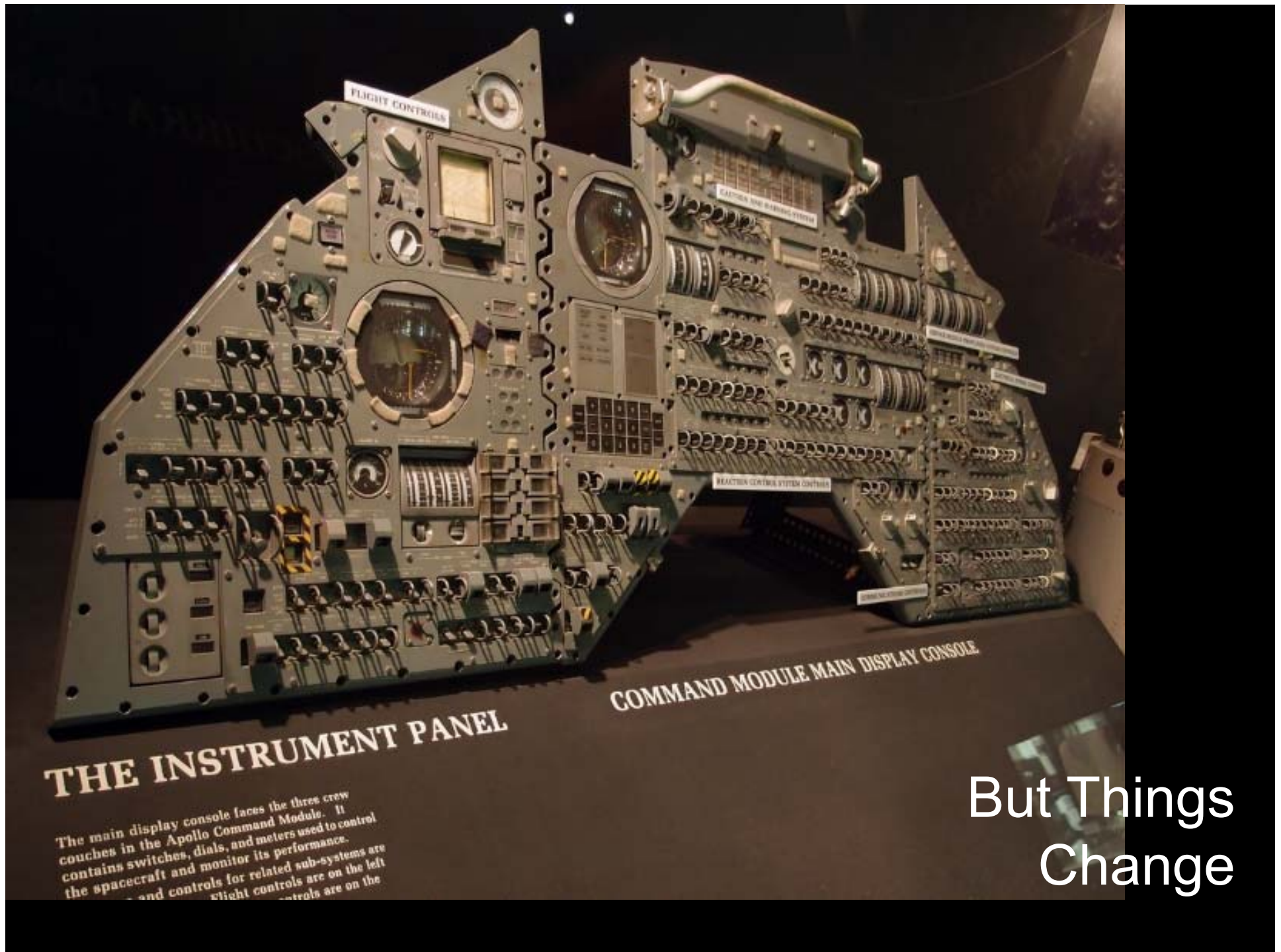
43AP

SERIAL

AND

PROP.





THE INSTRUMENT PANEL

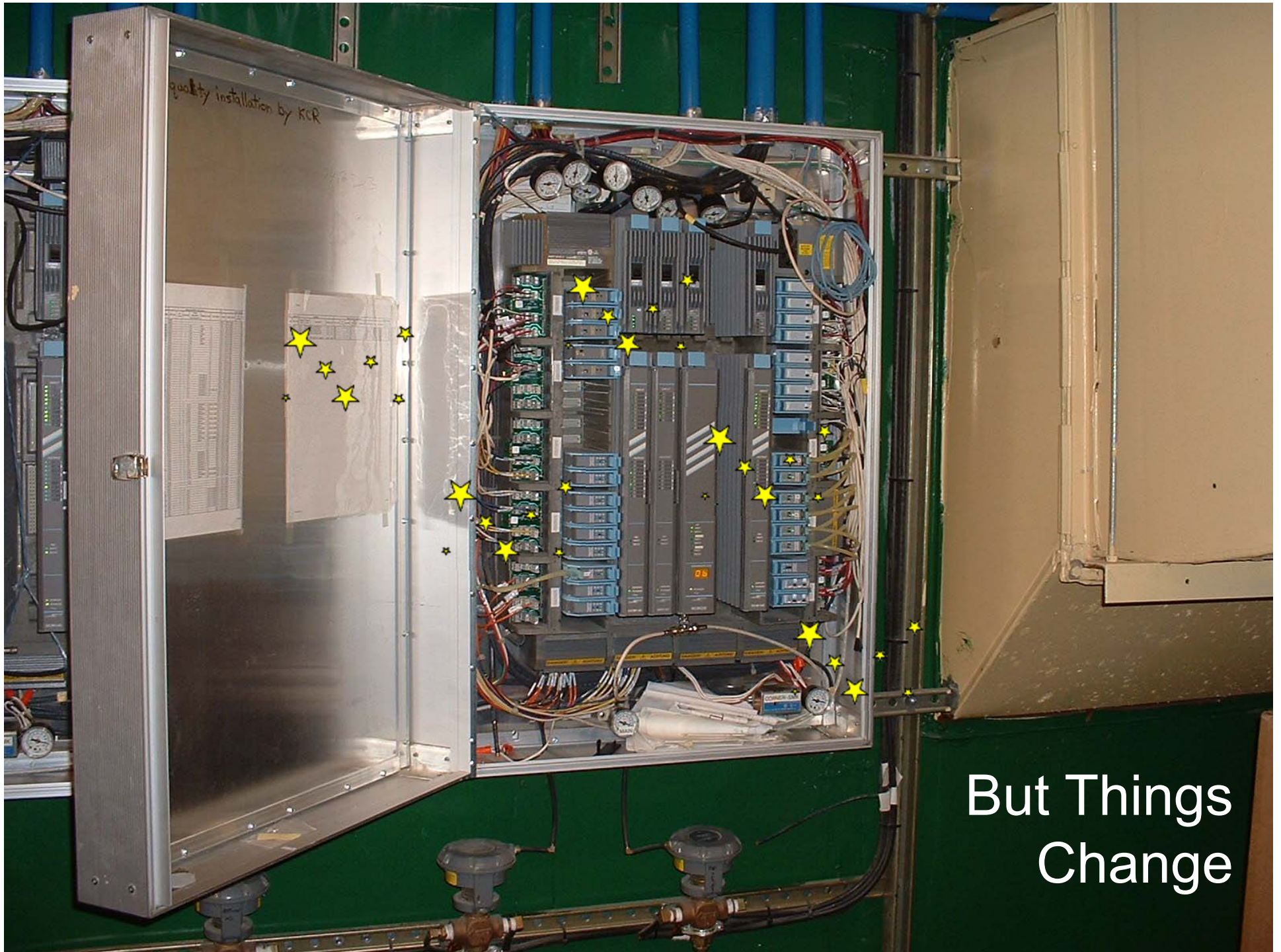
The main display console faces the three crew couches in the Apollo Command Module. It contains switches, dials, and meters used to control the spacecraft and monitor its performance. The spacecraft and controls for related sub-systems are on the left and controls for related sub-systems are on the right.

COMMAND MODULE MAIN DISPLAY CONSOLE

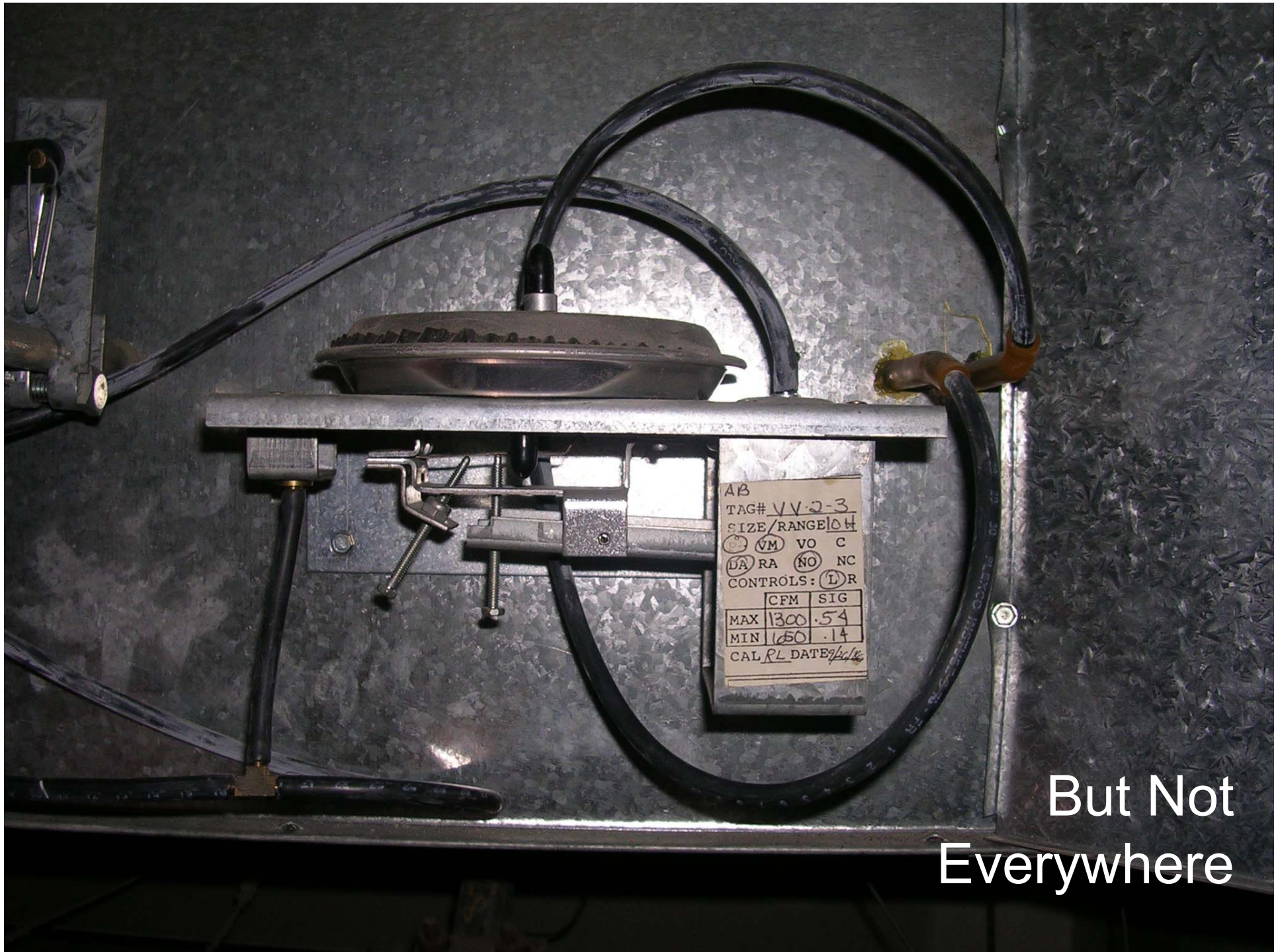
But Things
Change



But Things
Change



But Things
Change

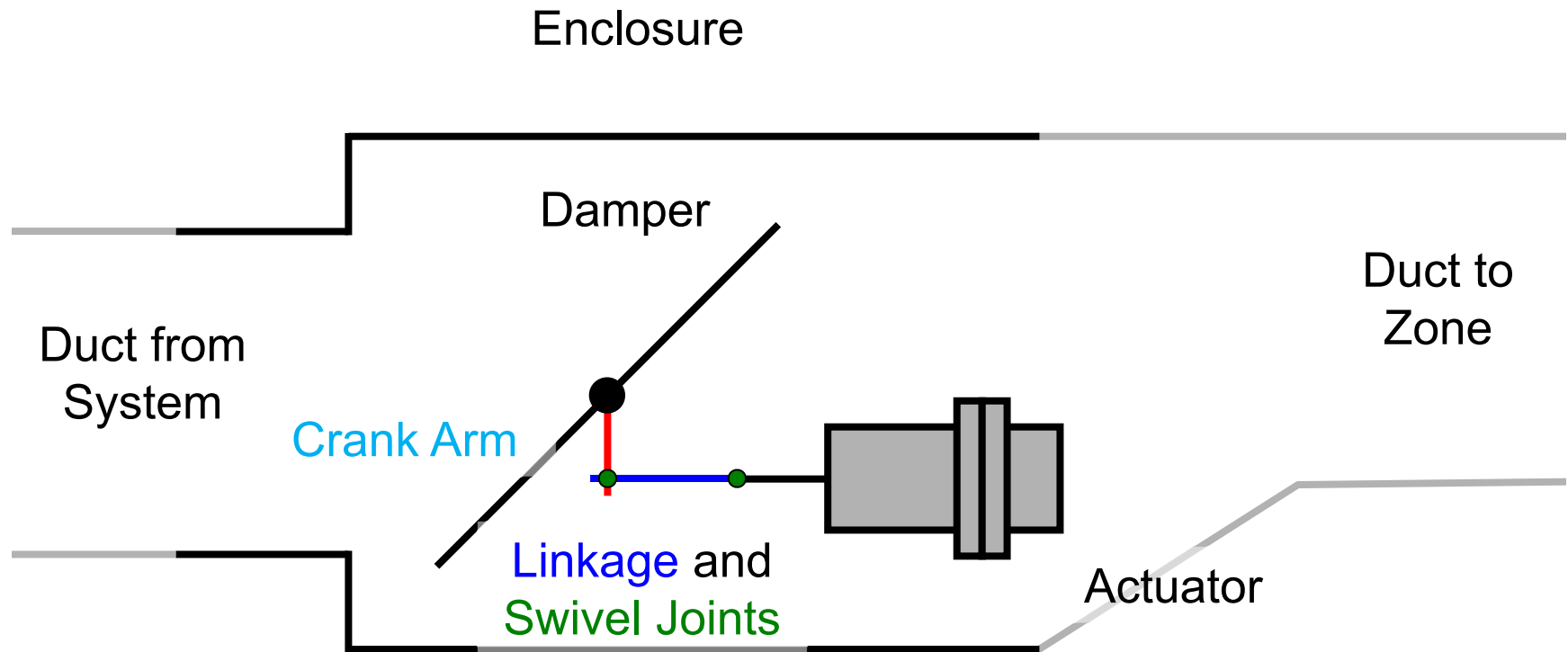


AB
TAG# VV-2-3
SIZE/RANGE 10H
☒ VM ☐ VO ☐ C
☒ RA ☒ NO ☐ NC
CONTROLS: ☒ L ☐ R

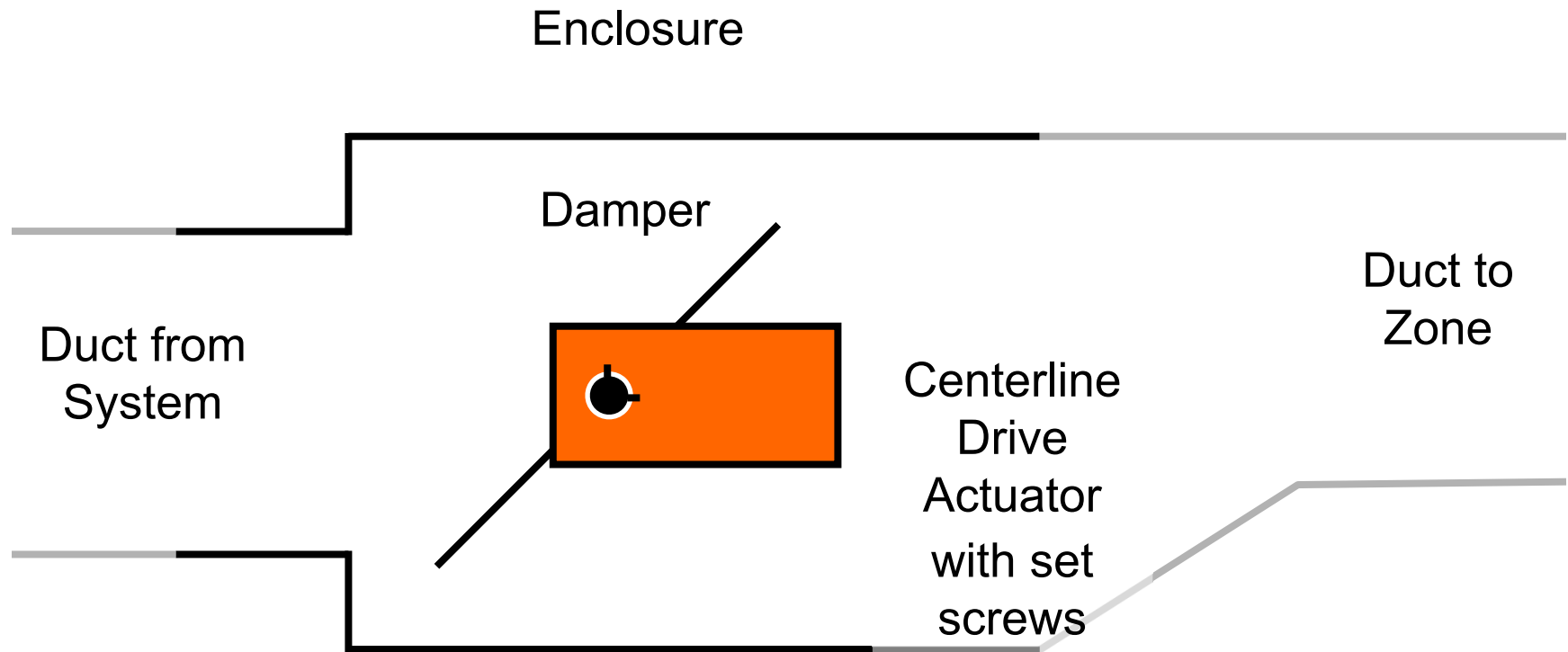
	CFM	SIG
MAX	1300	.54
MIN	100	.14
CAL <u>RL</u> DATE <u>9/26/88</u>		

But Not
Everywhere

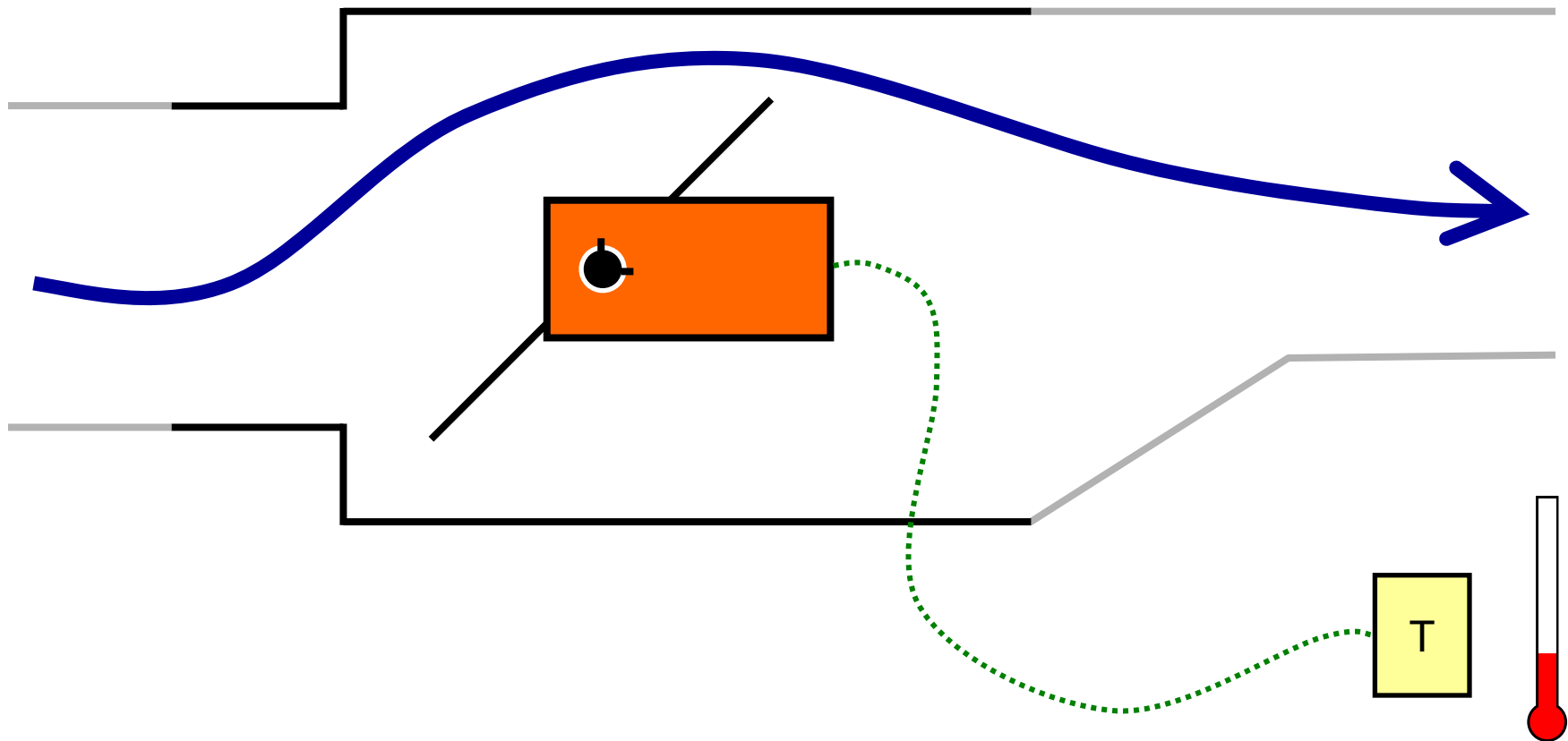
Your Basic Box



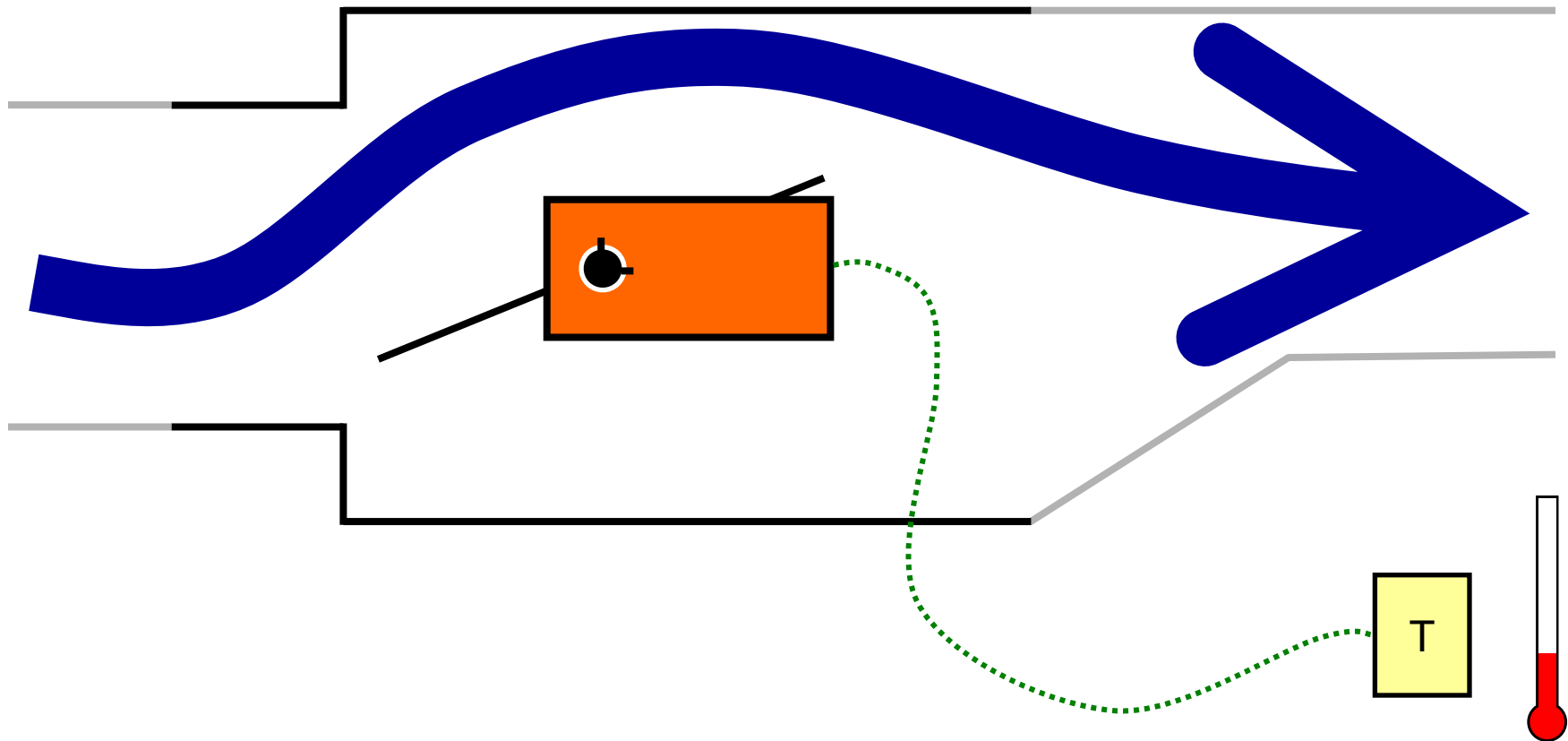
Your Basic Box



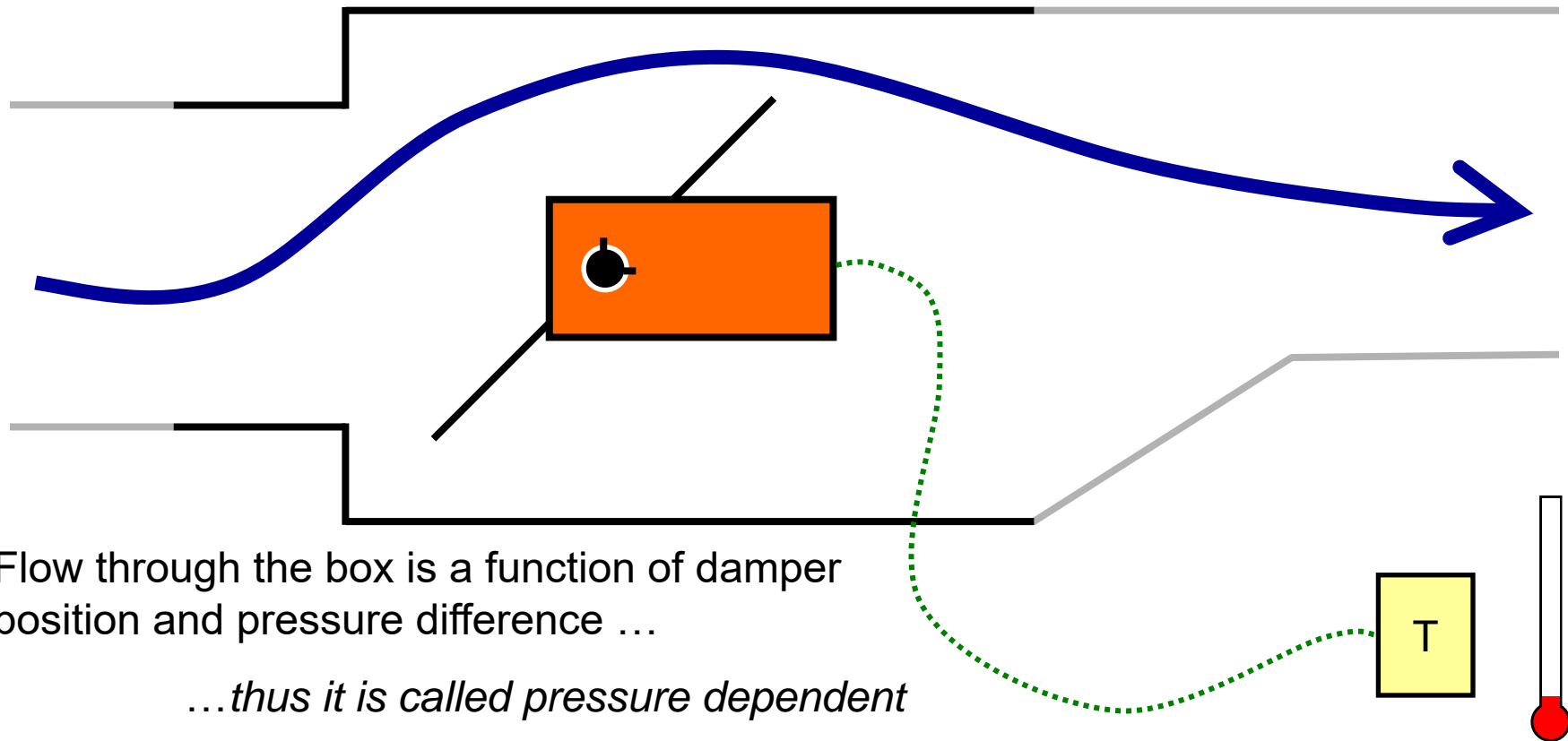
Your Basic Box



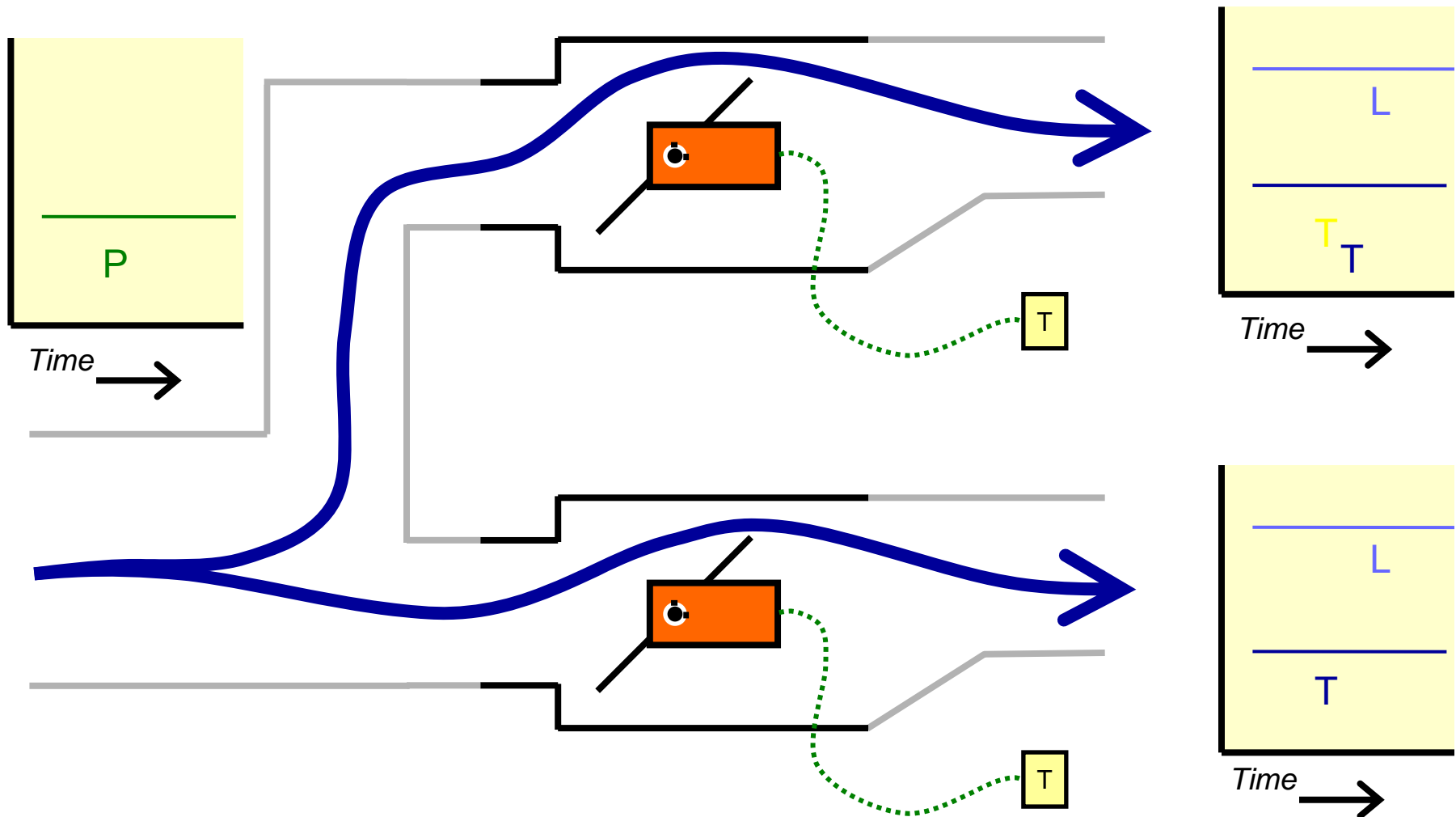
Your Basic Box



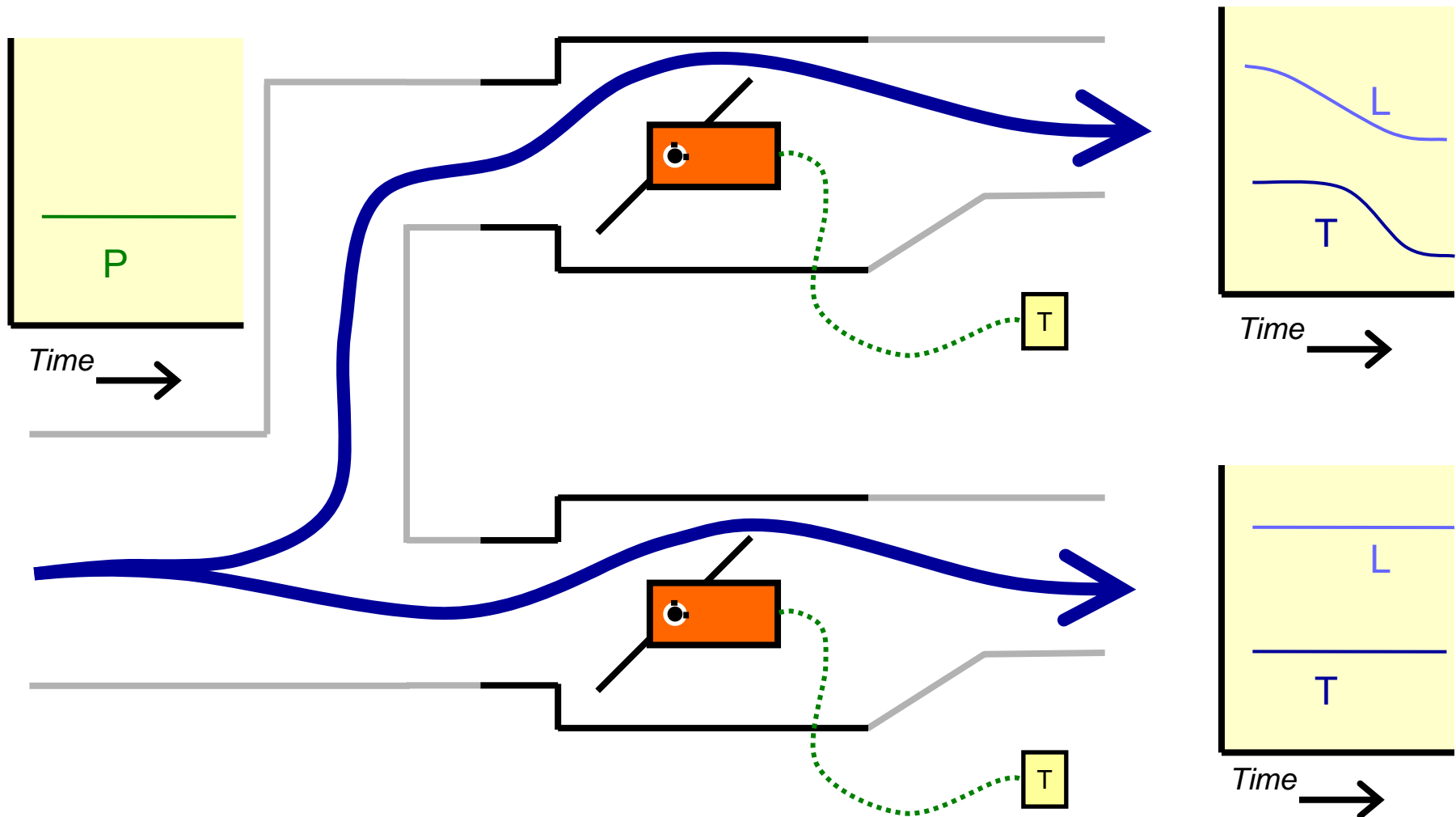
Your Basic Box



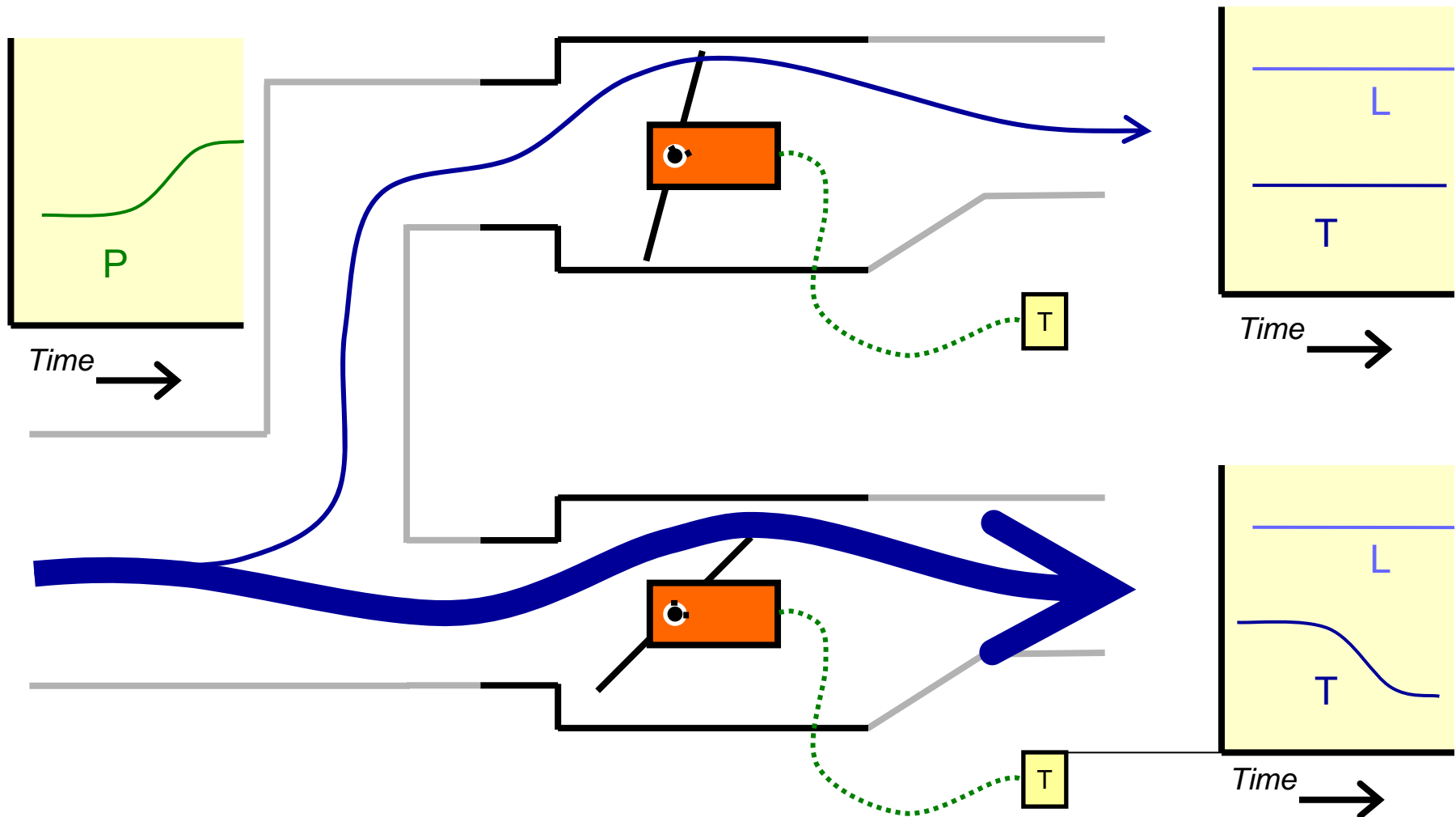
Your Basic Box



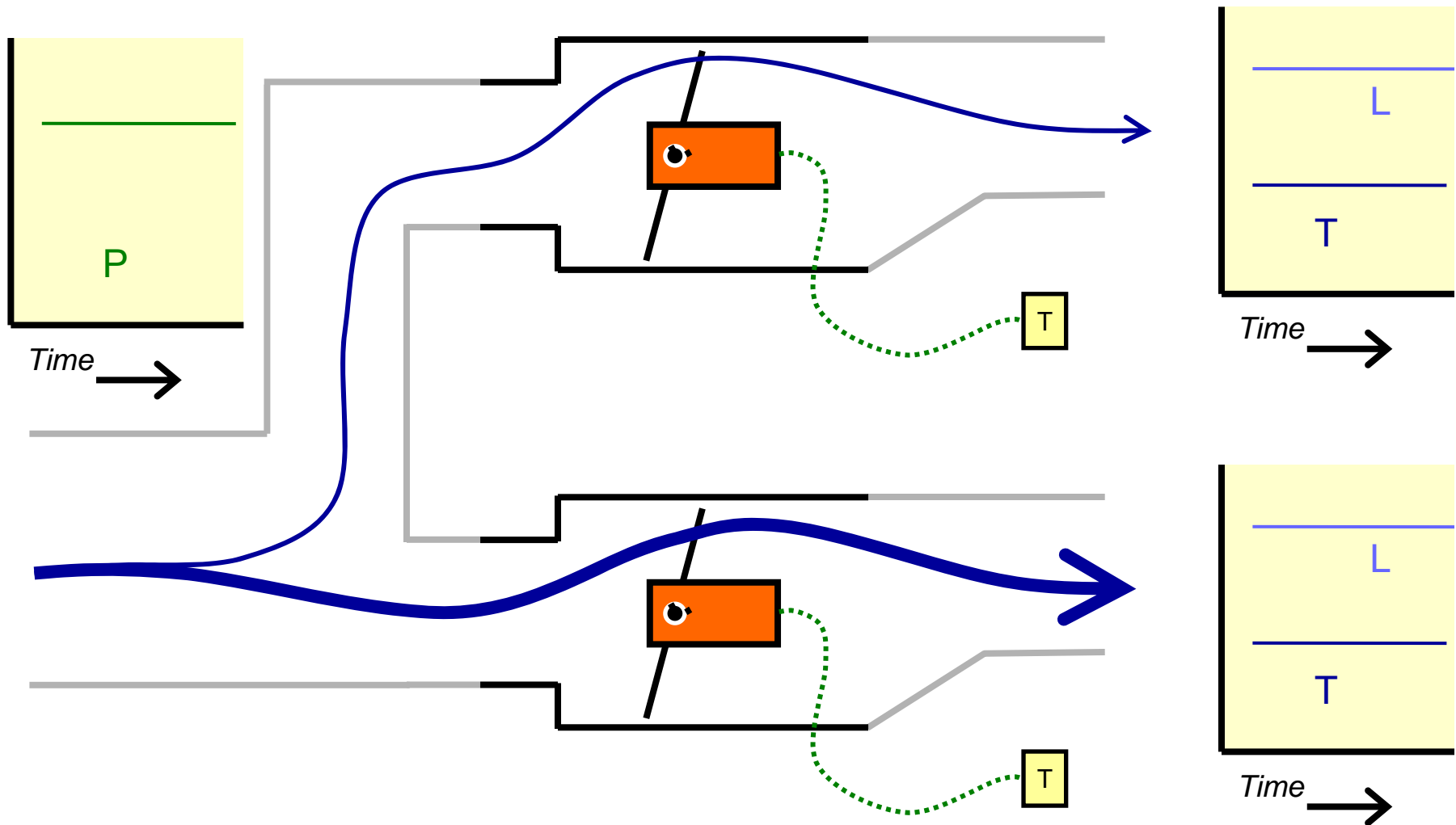
Your Basic Box



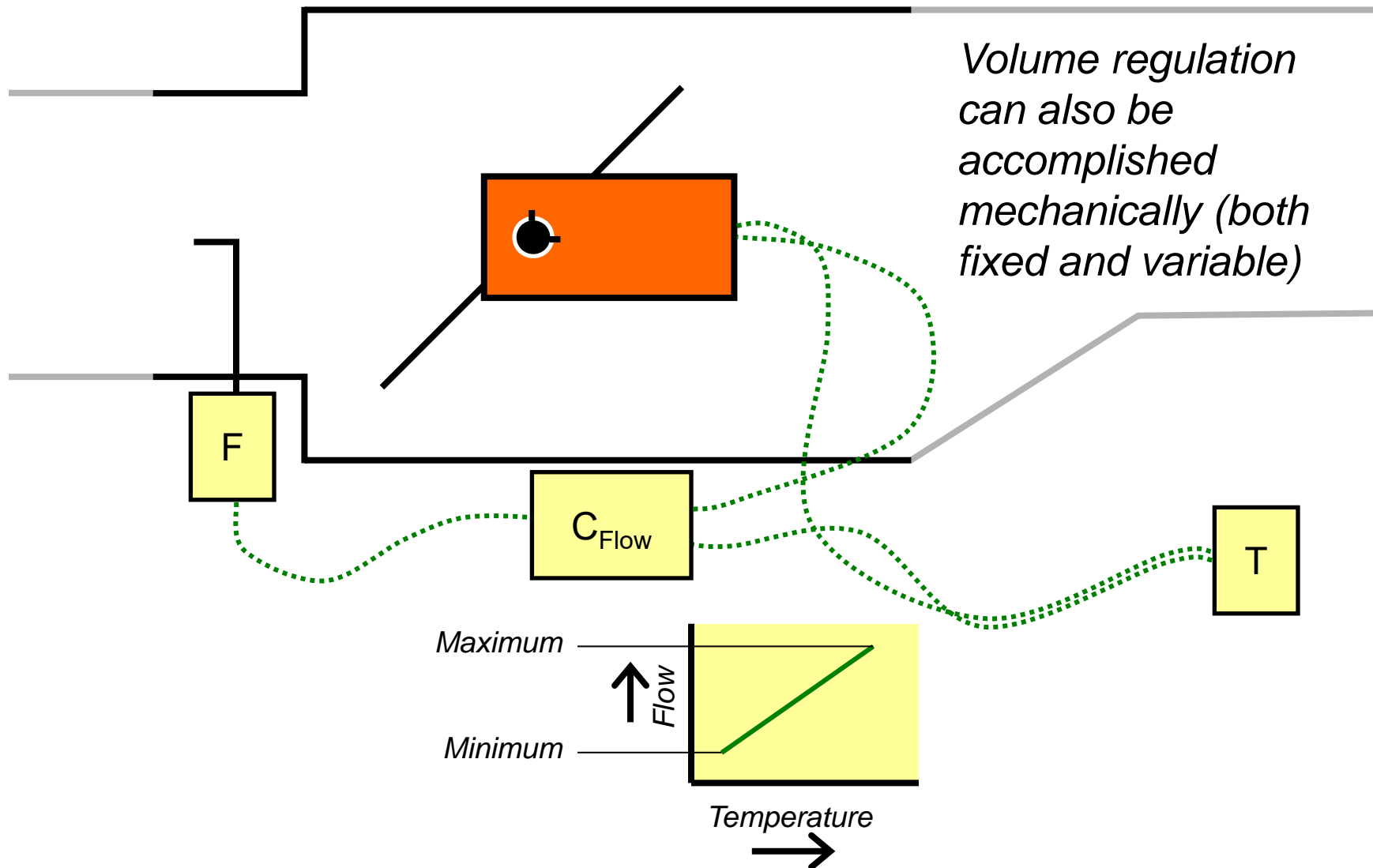
Your Basic Box



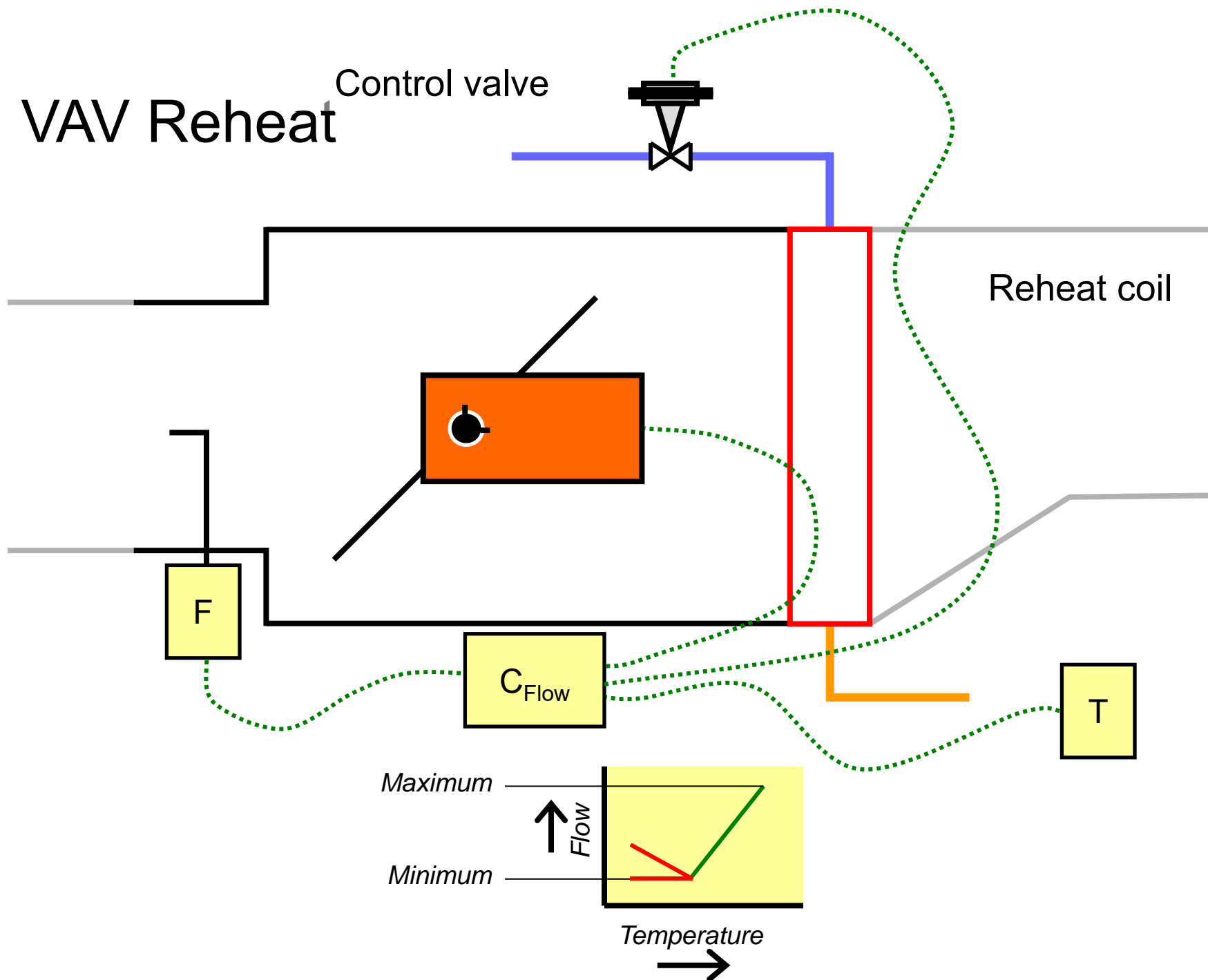
Your Basic Box



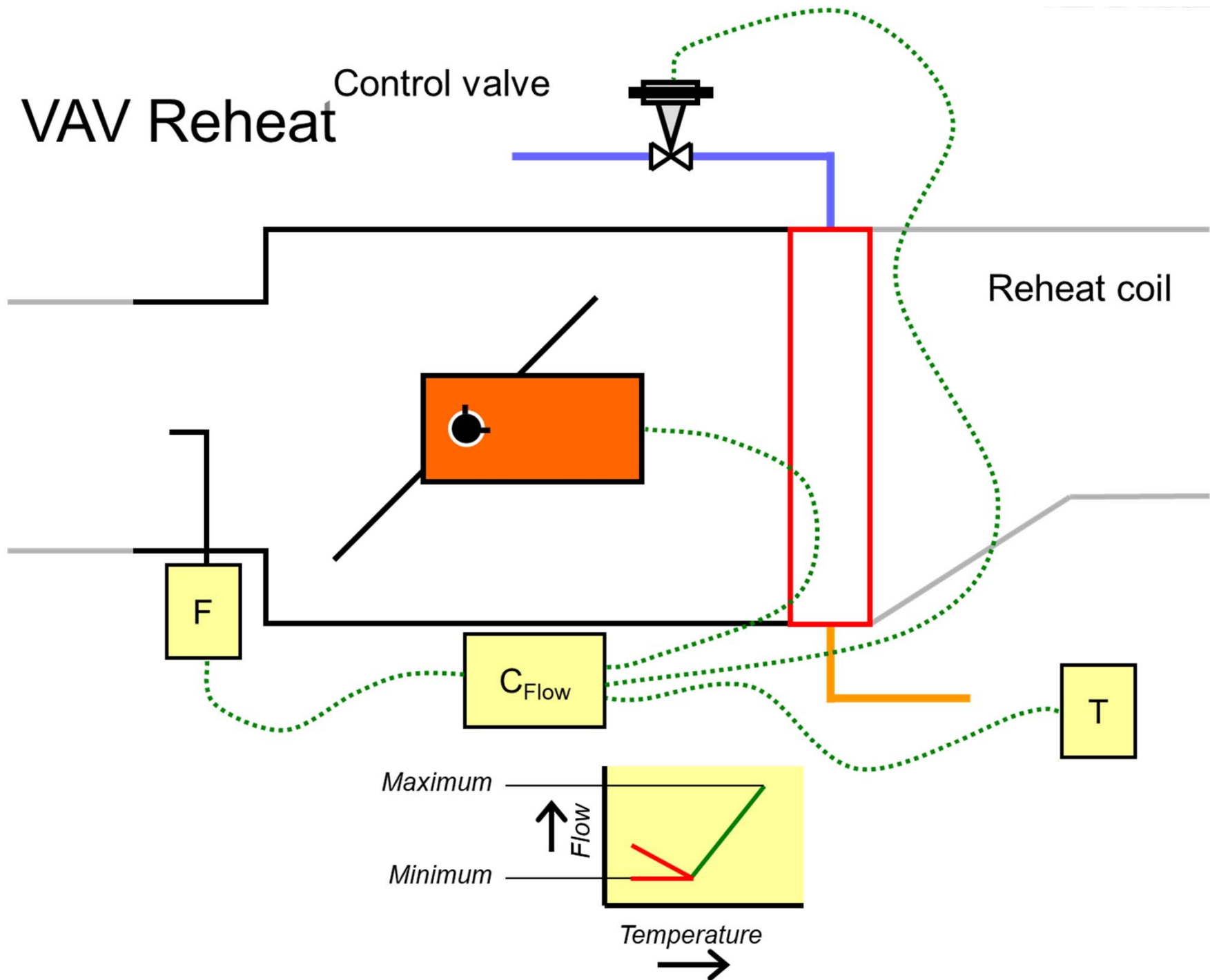
Becoming Pressure Independent

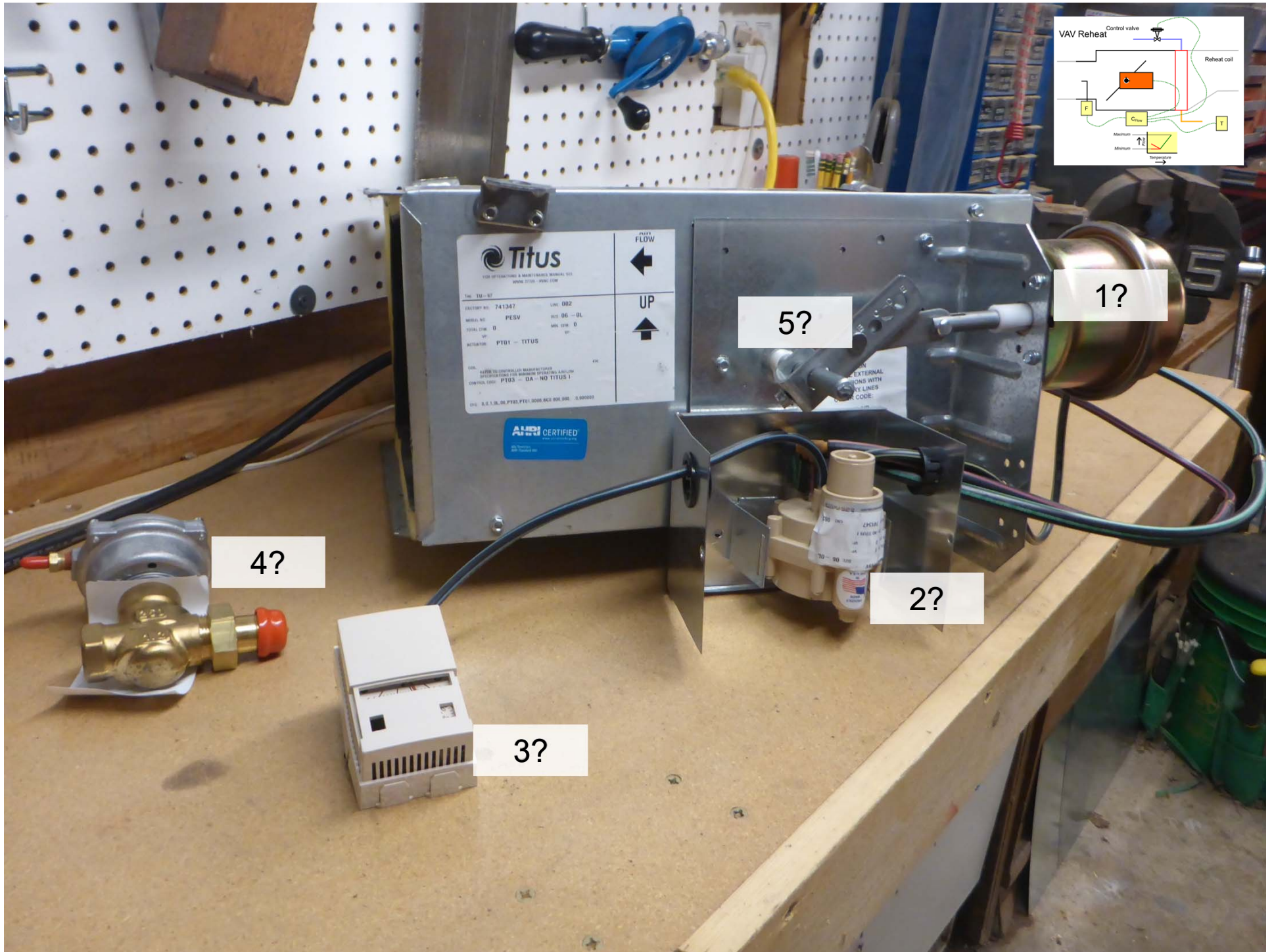


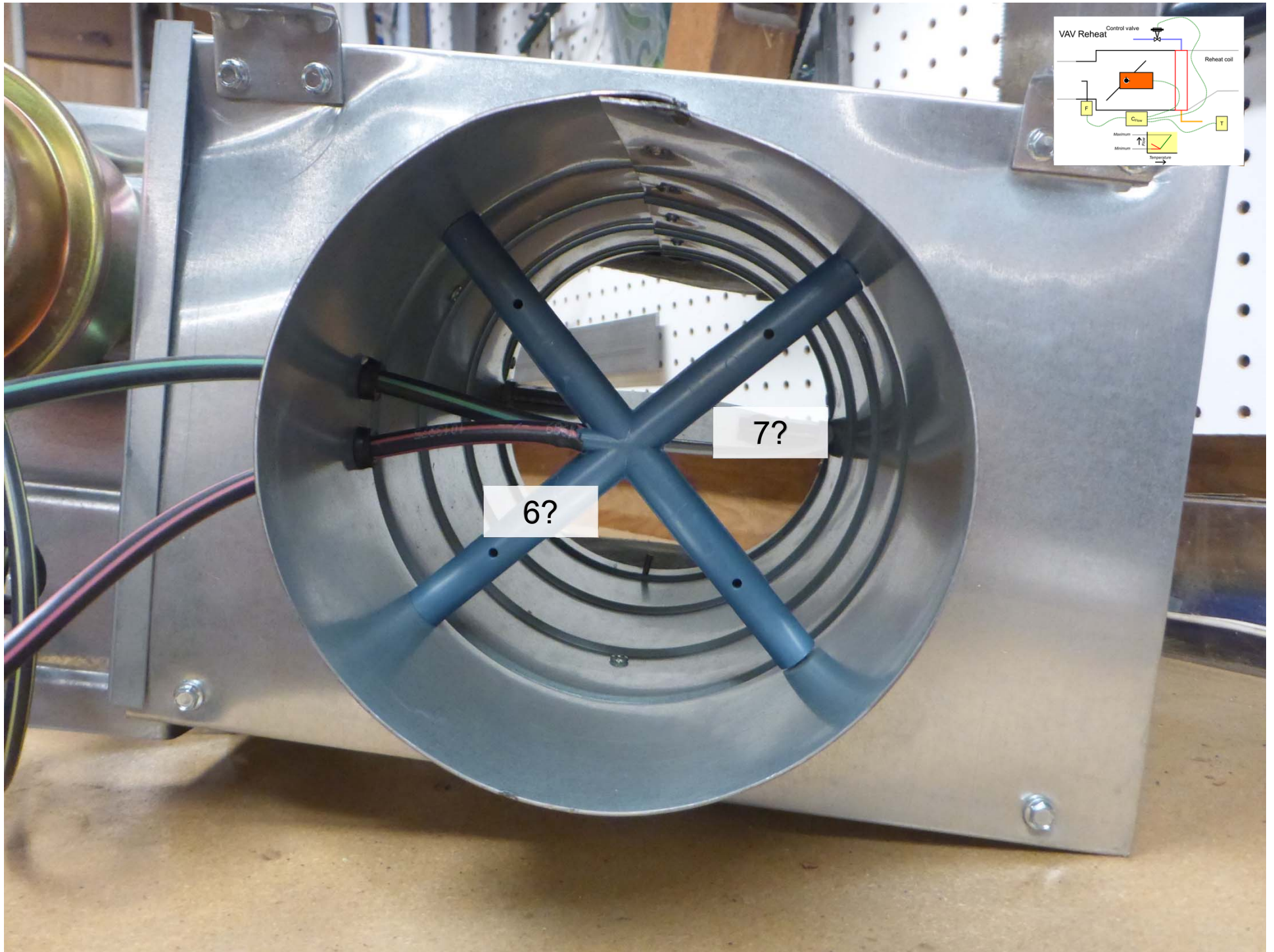
VAV Reheat

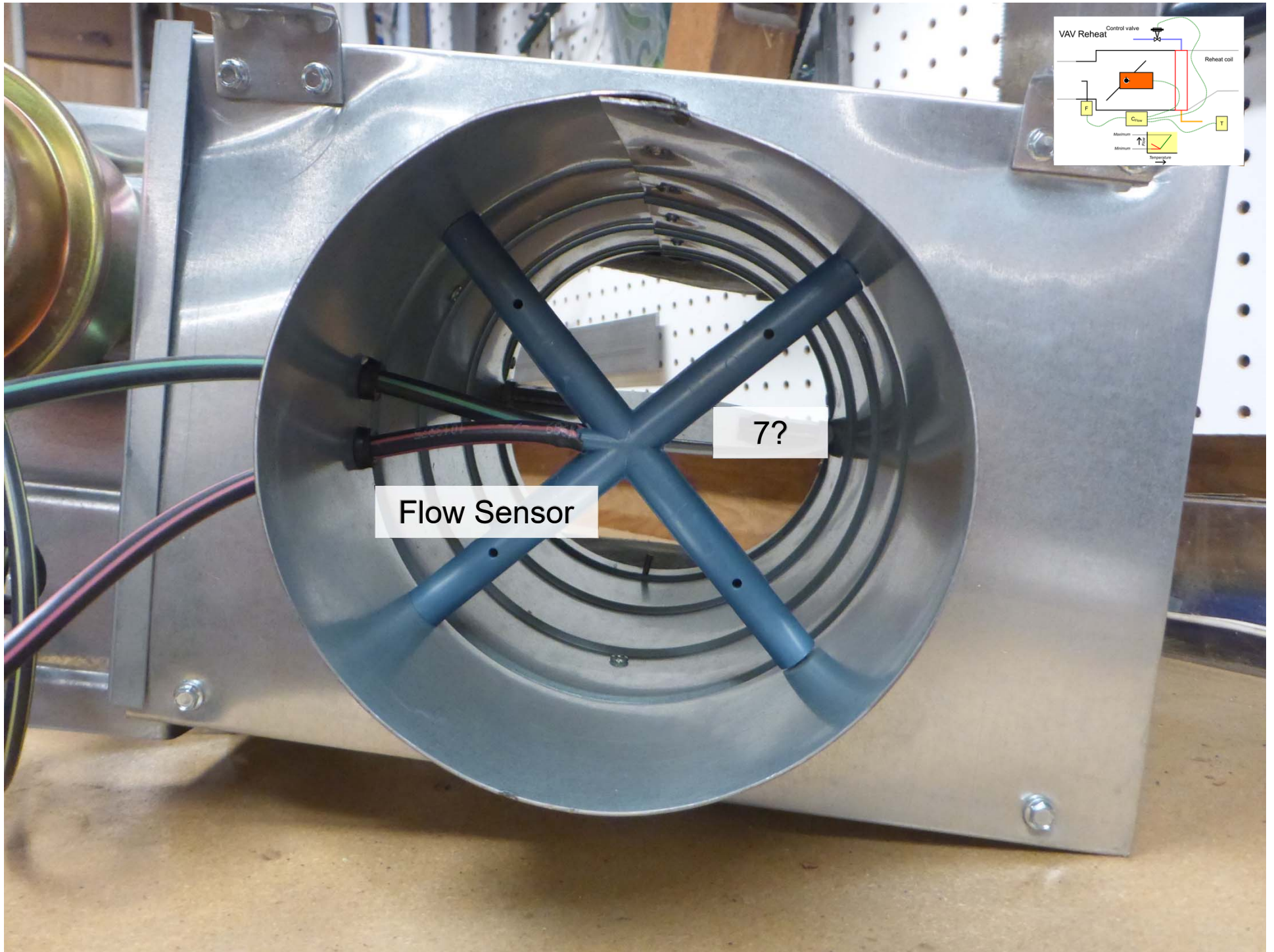


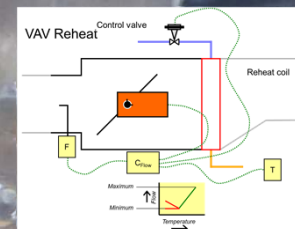
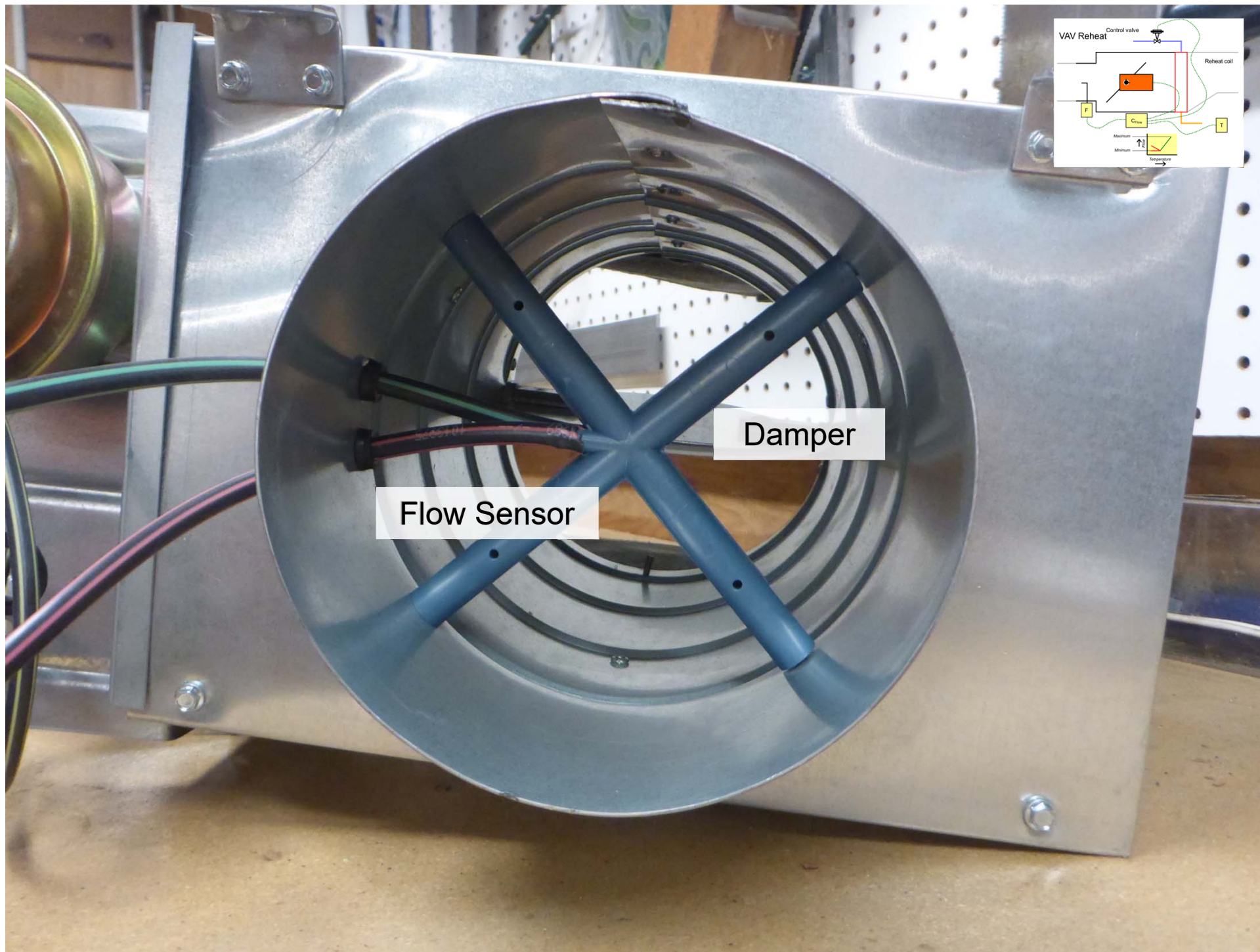
VAV Reheat





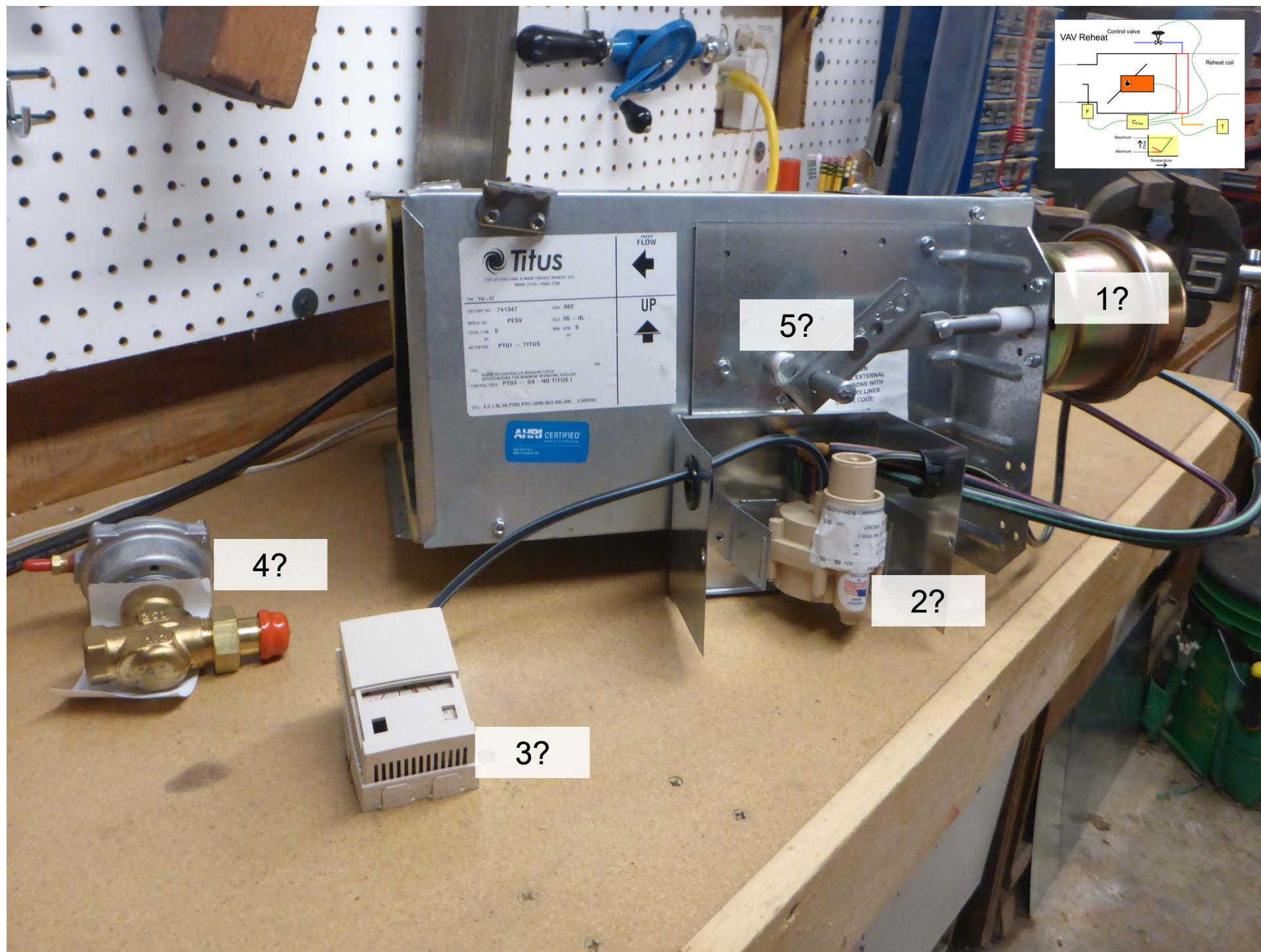
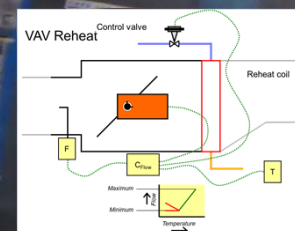


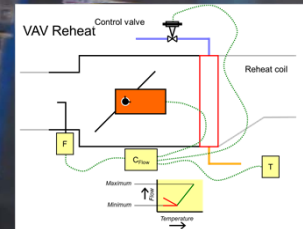
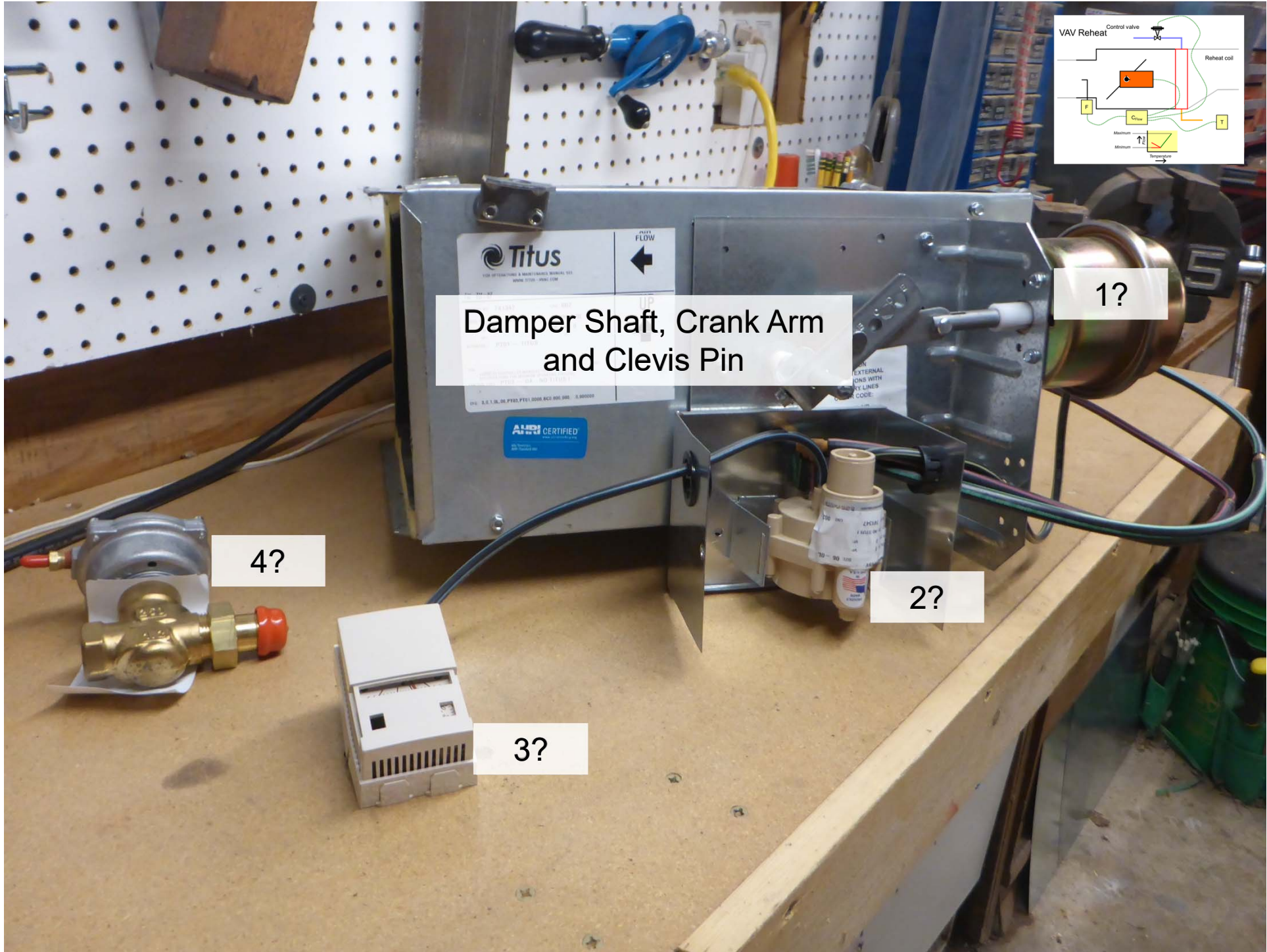




Damper

Flow Sensor





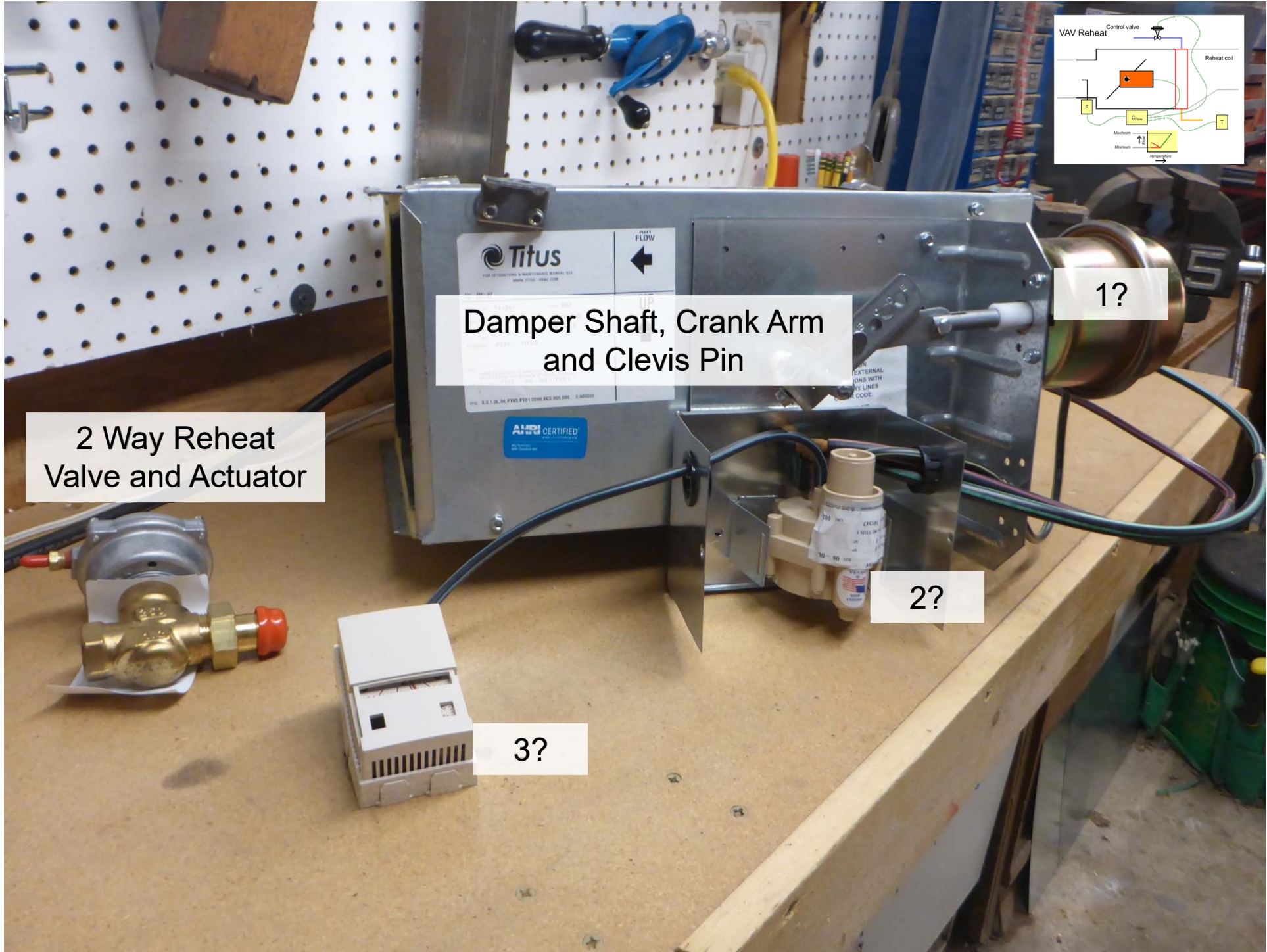
Damper Shaft, Crank Arm
and Clevis Pin

1?

4?

2?

3?



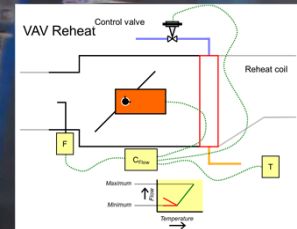
Damper Shaft, Crank Arm
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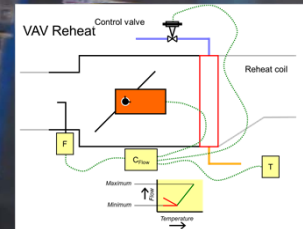
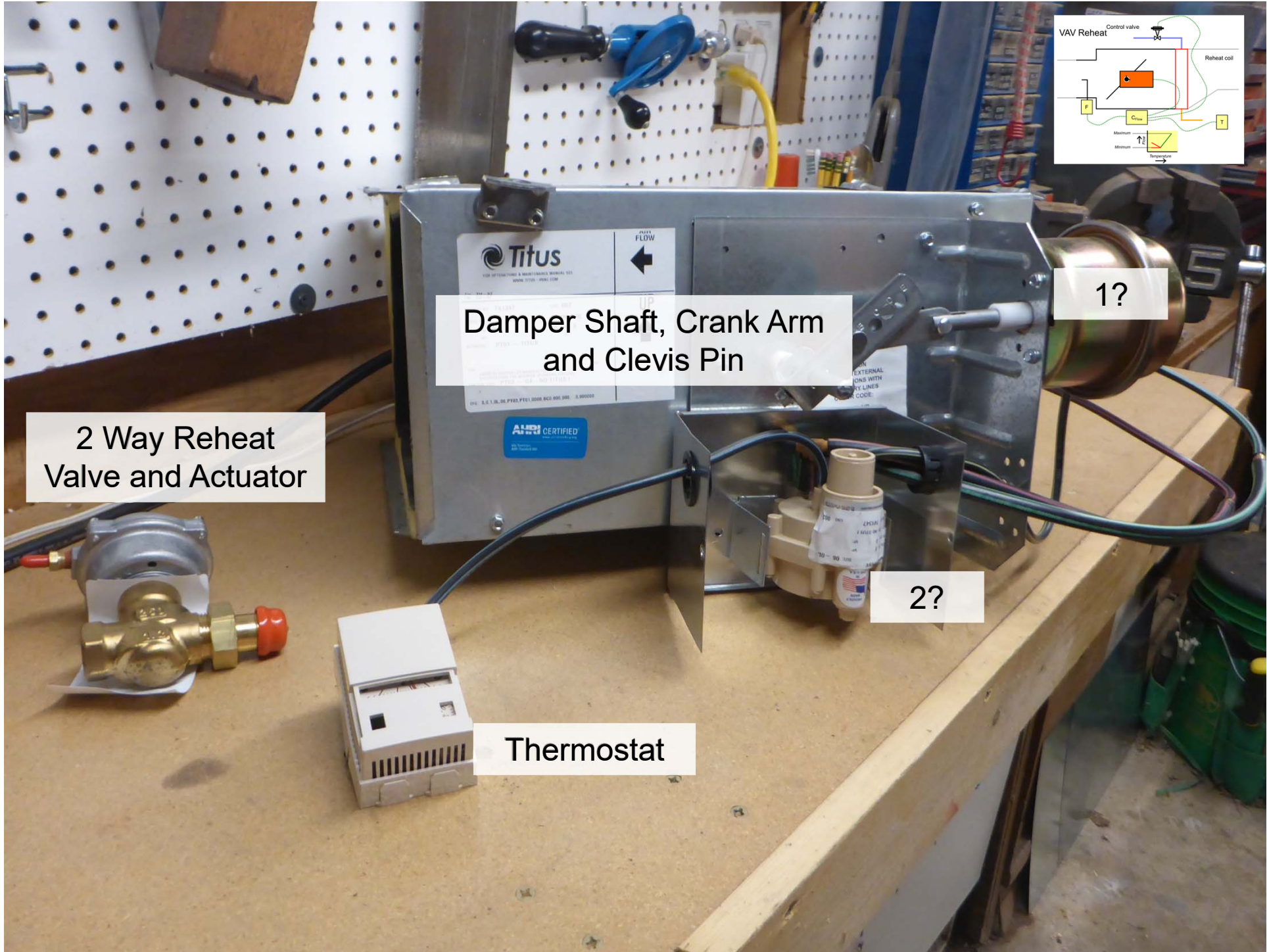
2 Way Reheat
Valve and Actuator

1?

2?

3?





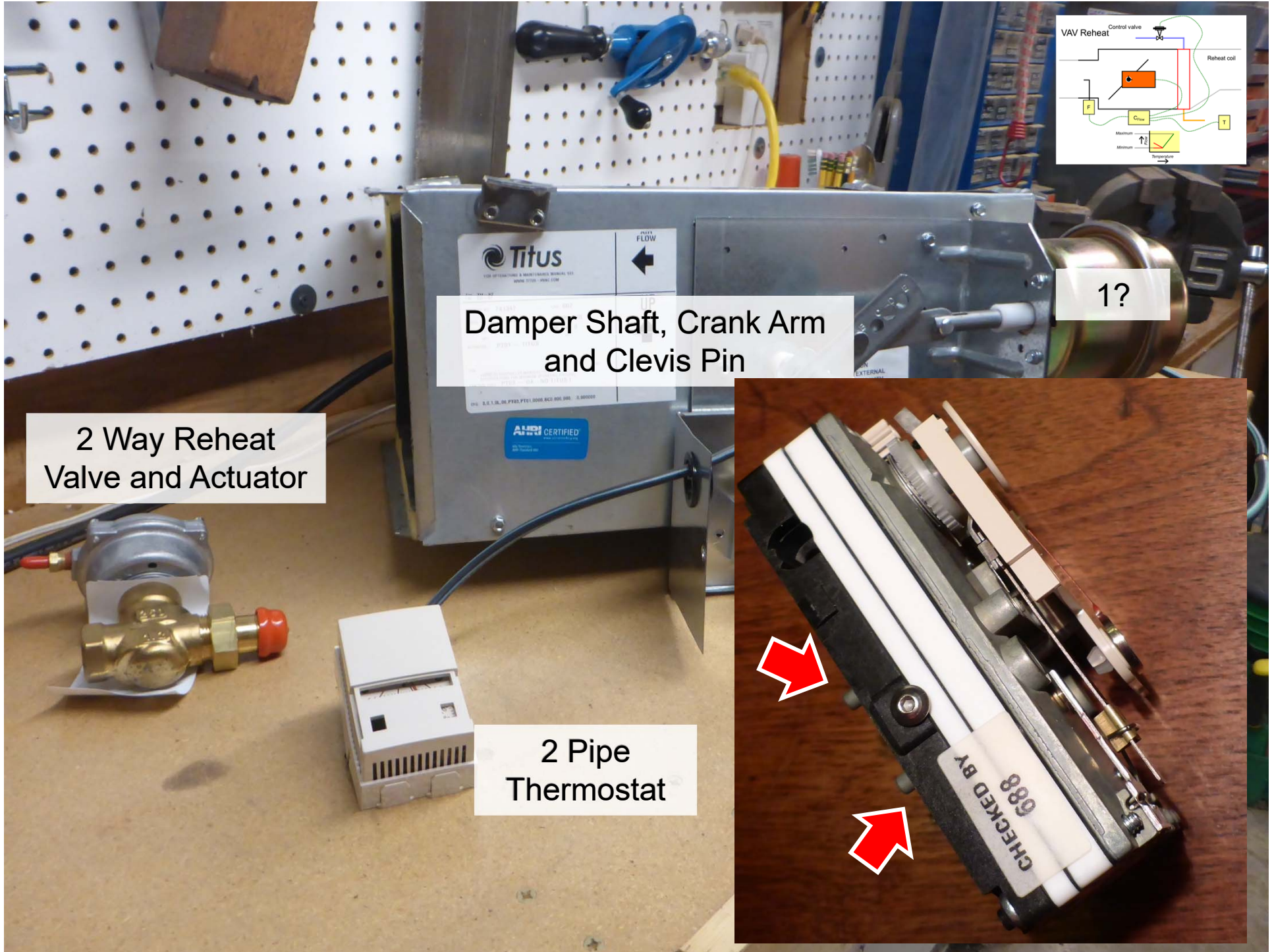
Dampers Shaft, Crank Arm
and Clevis Pin

2 Way Reheat
Valve and Actuator

1?

2?

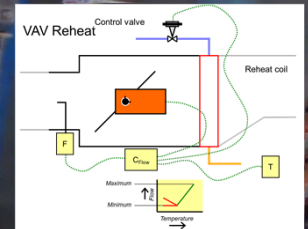
Thermostat



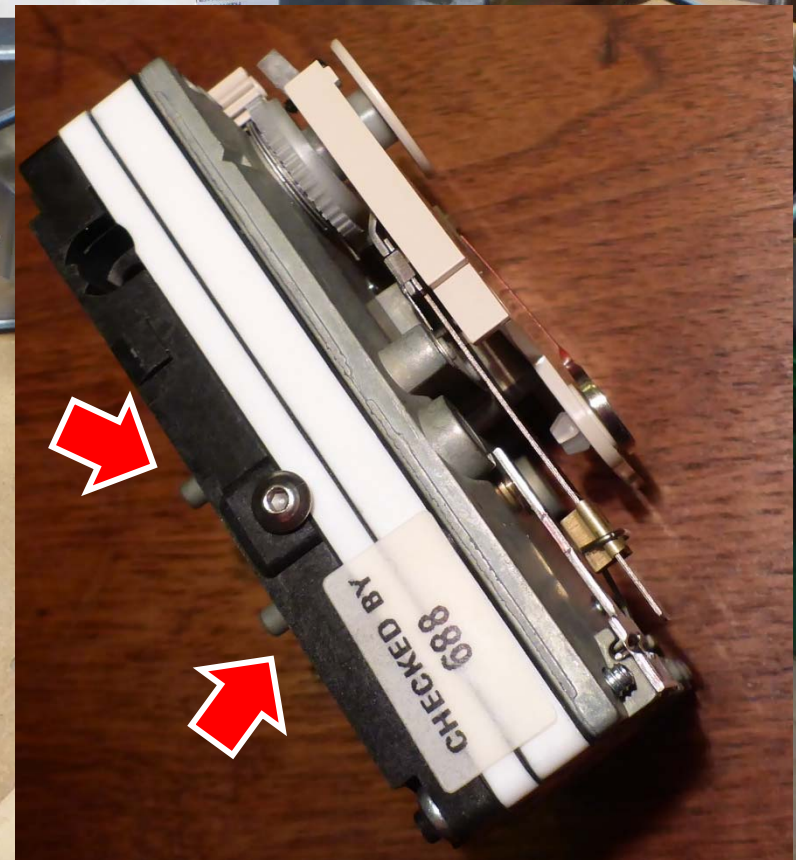
Dampers Shaft, Crank Arm
and Clevis Pin

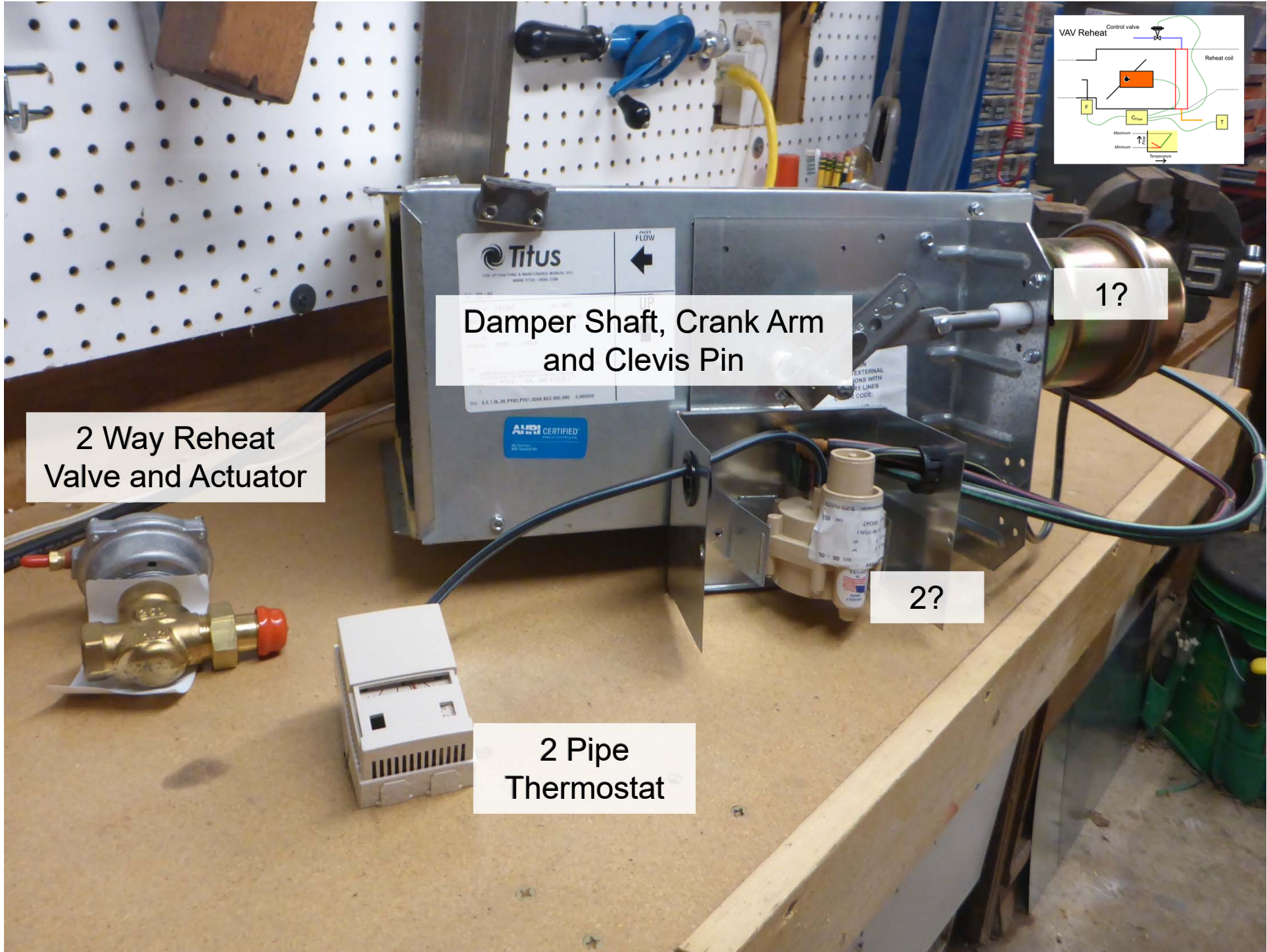
2 Way Reheat
Valve and Actuator

2 Pipe
Thermostat



1?





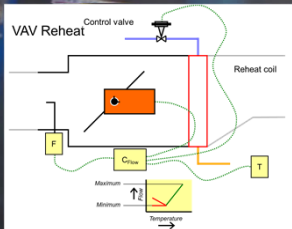
Damper Shaft, Crank Arm
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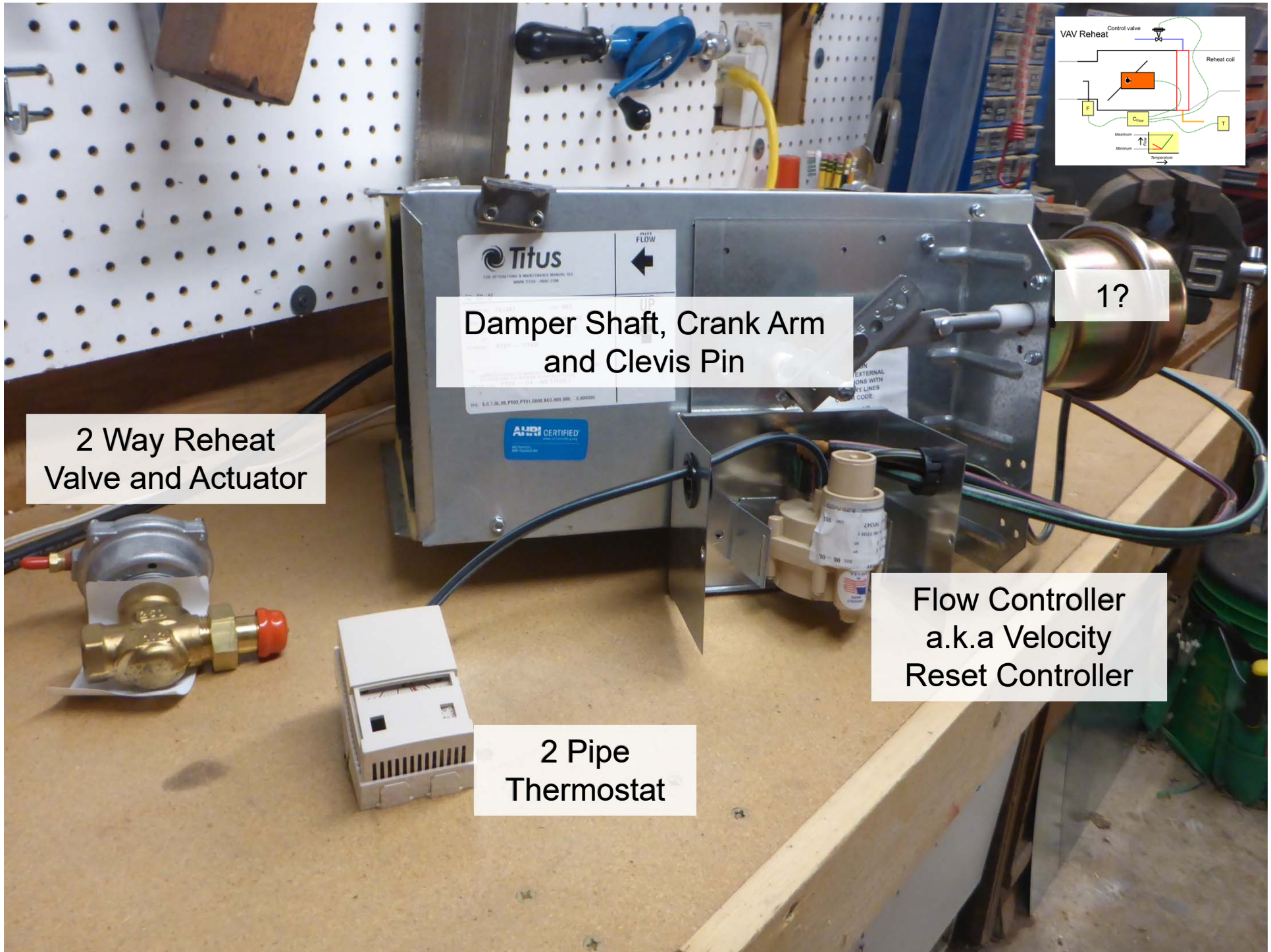
2 Way Reheat
Valve and Actuator

2 Pipe
Thermostat

1?

2?





Damper Shaft, Crank Arm
and Clevis Pin

2 Way Reheat
Valve and Actuator

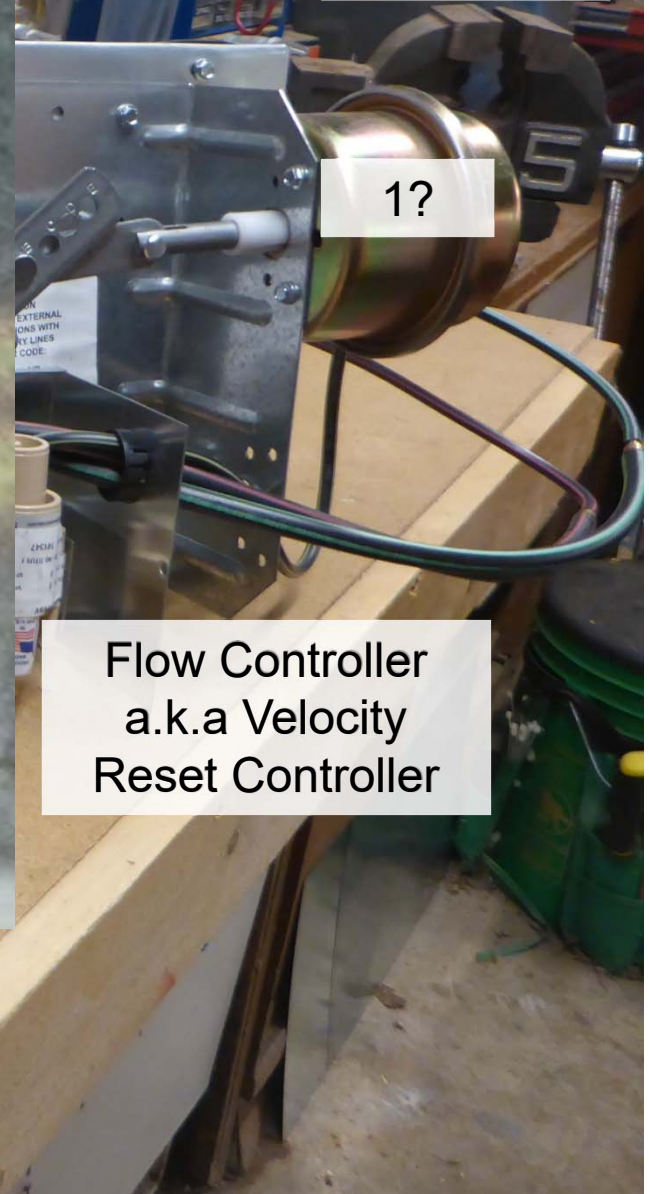
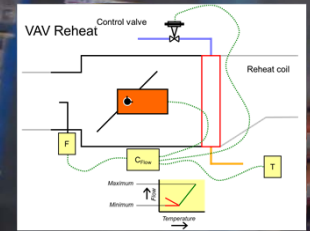
Flow Controller
a.k.a Velocity
Reset Controller

2 Pipe
Thermostat

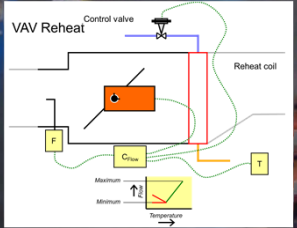
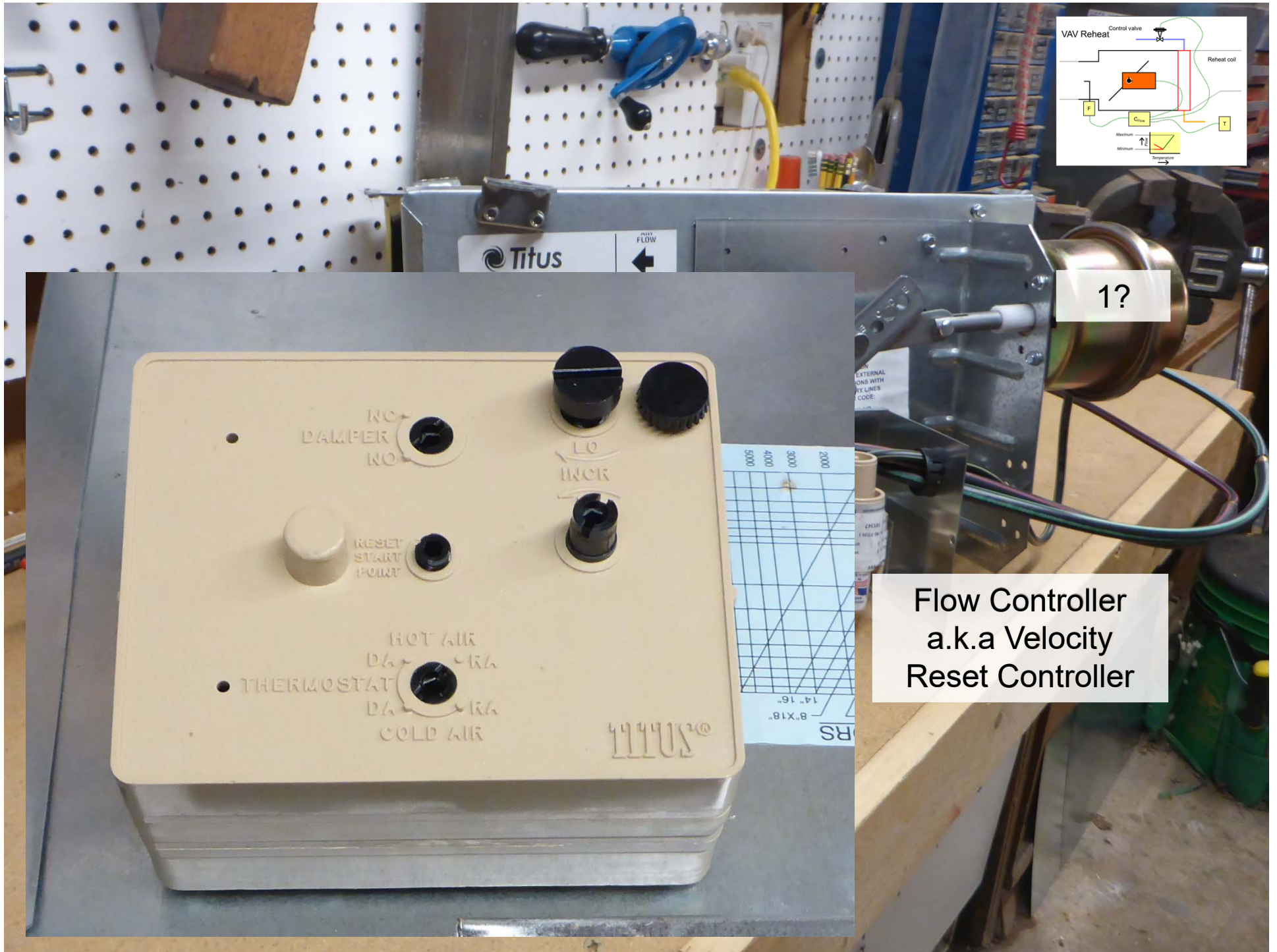
1?



Thermostat

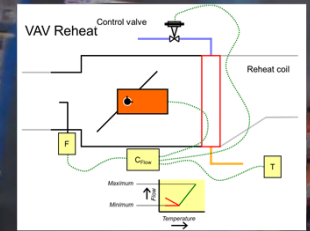
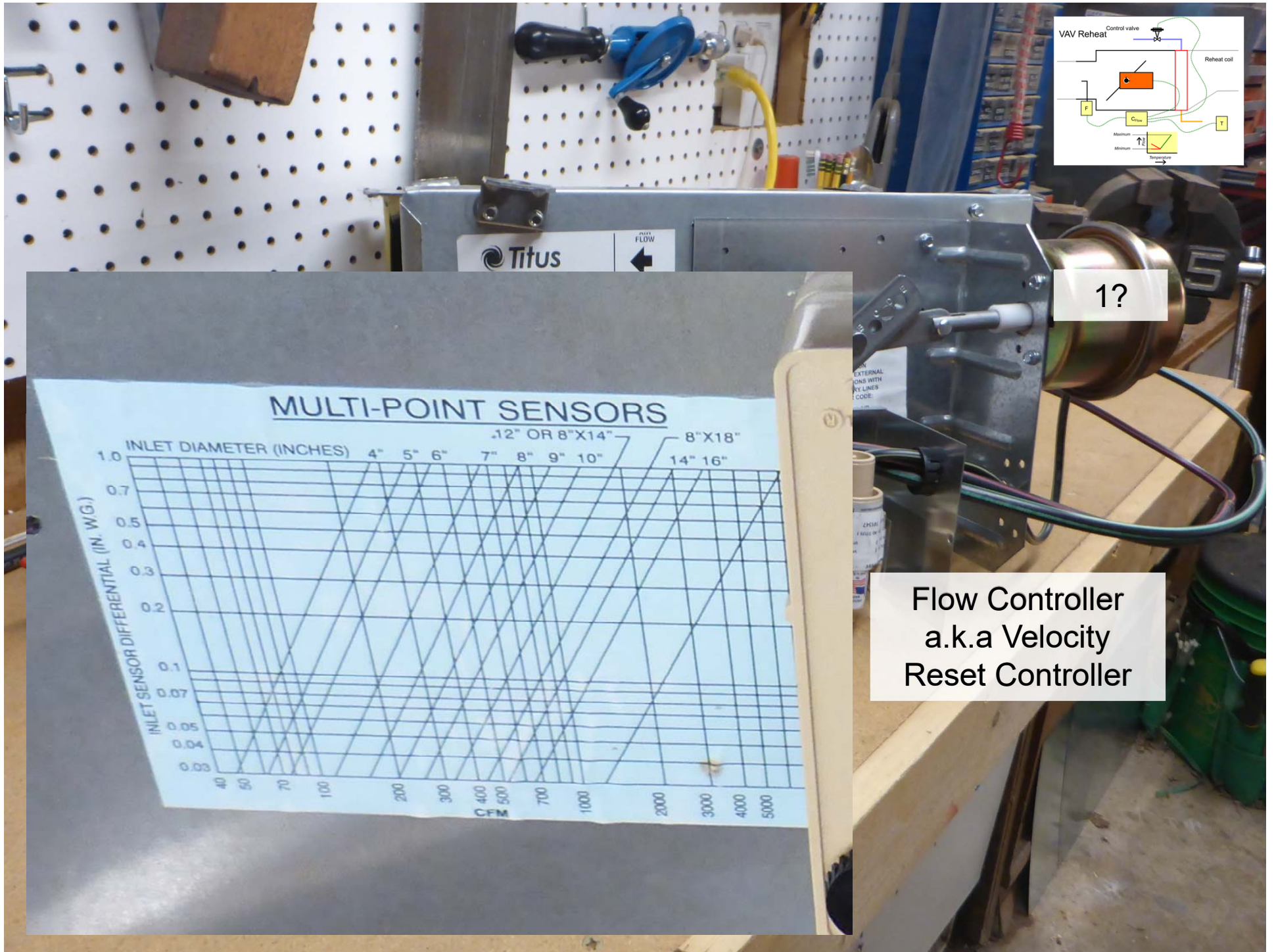


Flow Controller
a.k.a Velocity
Reset Controller



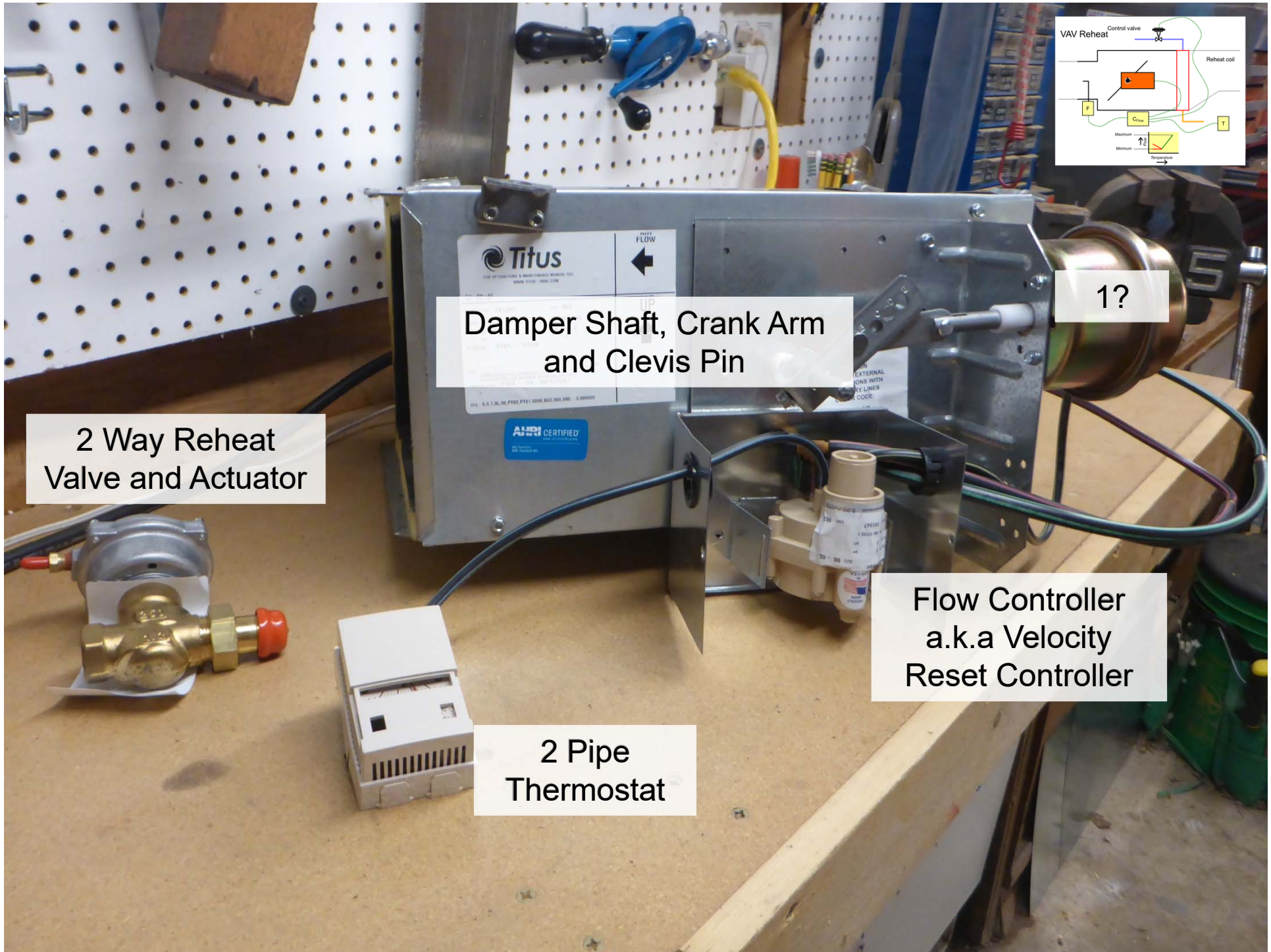
1?

Flow Controller
a.k.a Velocity
Reset Controller



1?

Flow Controller
a.k.a Velocity
Reset Controller



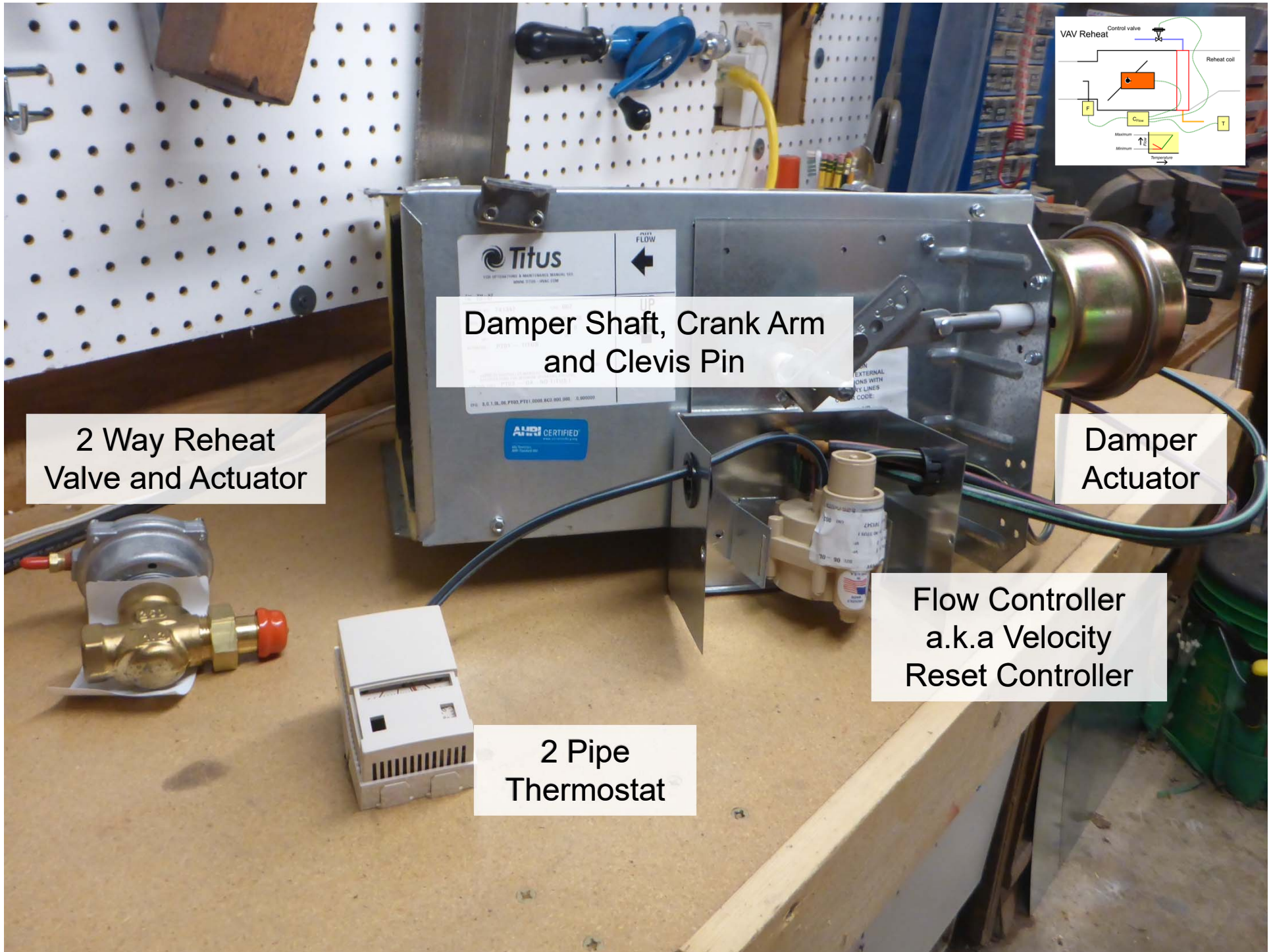
Damper Shaft, Crank Arm
and Clevis Pin

2 Way Reheat
Valve and Actuator

Flow Controller
a.k.a Velocity
Reset Controller

2 Pipe
Thermostat

1?



Damper Shaft, Crank Arm
and Clevis Pin

2 Way Reheat
Valve and Actuator

Damper
Actuator

Flow Controller
a.k.a Velocity
Reset Controller

2 Pipe
Thermostat

Bottom Line

A pressure independent VAV box control process is a flow control process that is:

- Reset between a minimum and maximum flow based on the deviation of space temperature from set point
- Sequences reheat and heat as needed once the terminal unit is at its minimum flow condition
- May increase the flow again during the heating/reheating cycle
 - More common with DDC systems
 - Not as good a plan as it may seem

Heating vs. Reheat

Definitions

- Heating

A process that adds energy. For a space, this is often accomplished by circulating air through it at a temperature above the required set point. For an airstream, this is often accomplished by passing it over a surface that is above the required supply temperature.

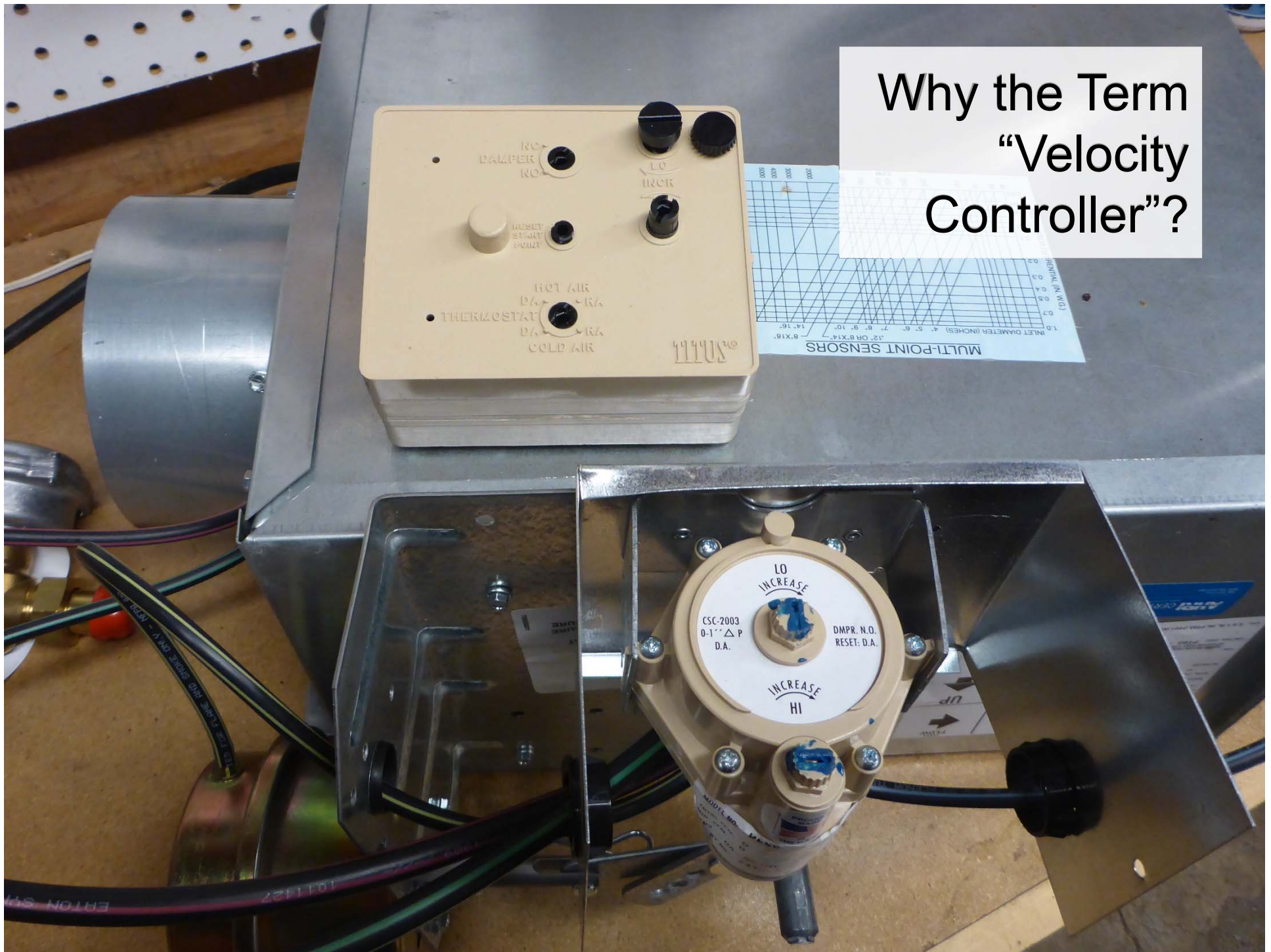
Heating vs. Reheat

Definitions

- Reheat

A process that uses heat to warm air being delivered to a zone to prevent over cooling. The temperature of the air was set by the need to hit a dehumidification target or by the requirements of another zone, so it can not be raised at the central system. The volume can not be reduced because it has been set to assure proper ventilation (contaminant control). In the limit, reheat will raise the supply temperature to the zone temperature but not above it.

Why the Term “Velocity Controller”?



The Relationship Between Flow and Velocity

$$Q = VA$$

Where :

Q = Flow rate in cubic feet per minute

V = Velocity in feet per minute

A = Cross sectional area in square feet

The Relationship Between Velocity and Velocity Pressure

$$V = 4,005 \sqrt{VP}$$

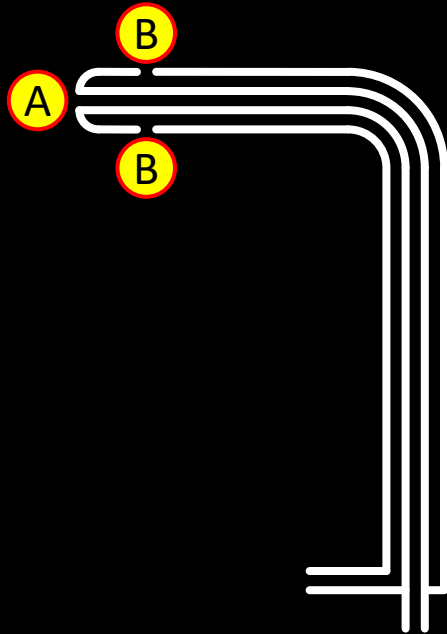
Where :

V = Velocity in feet per minute

4,005 = A units conversion constant

VP = Velocity pressure in inches w.c.

Flow Sensors are Typically a Form of Pitot Tube



Pitot tubes are designed to measure velocity pressure

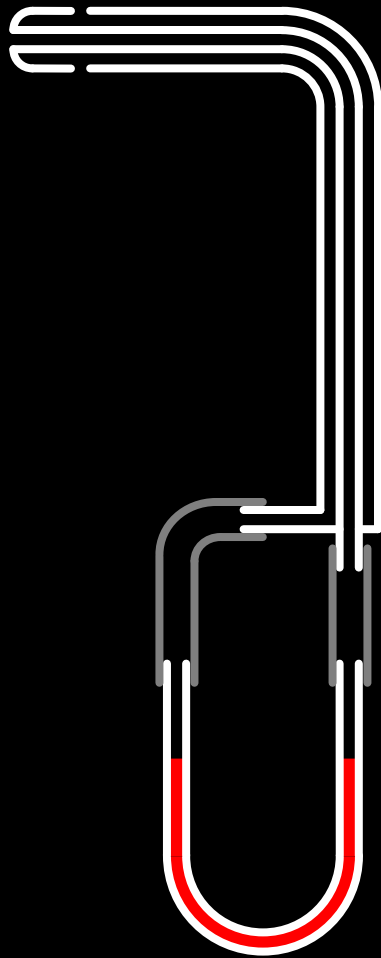
A tube inside a tube

- Inner tube open at the tip (A)
- Outer tube open through ports on the side (B)

In a moving air stream:

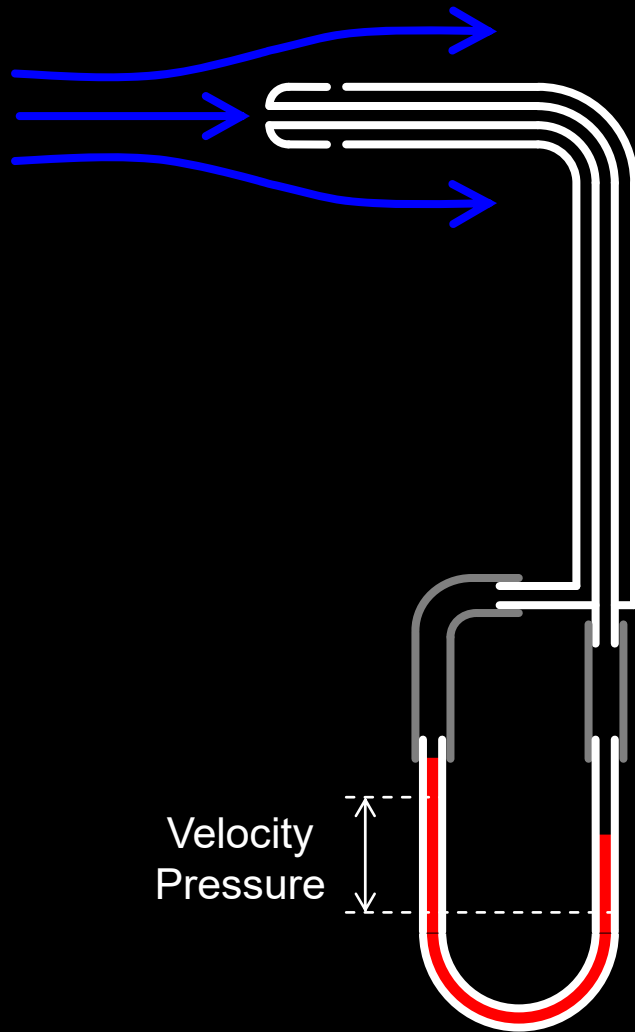
- The ports on the side (B) are exposed to only the ambient static pressure
- The port on the tip (A) is exposed to both the static pressure and the pressure created by the air being stopped; a.k.a. total pressure.
- The air is stopped because the tube dead ends on the measurement device
- The pressure associated with the moving air is called velocity pressure

Flow Sensors are Typically a Form of Pitot Tube



Connecting a U shaped glass tube filled with a liquid like oil or water – called a manometer – to the pitot tube allows velocity pressure to be measured

Flow Sensors are Typically a Form of Pitot Tube



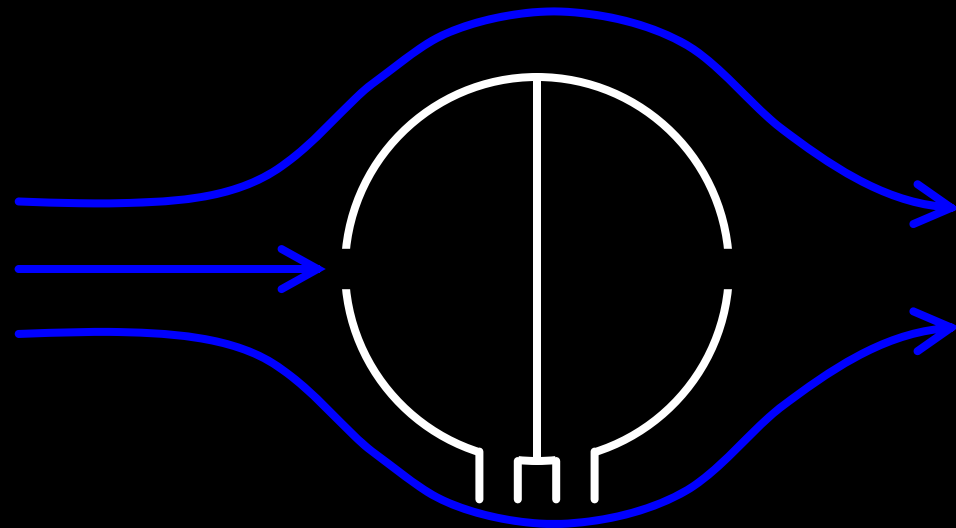
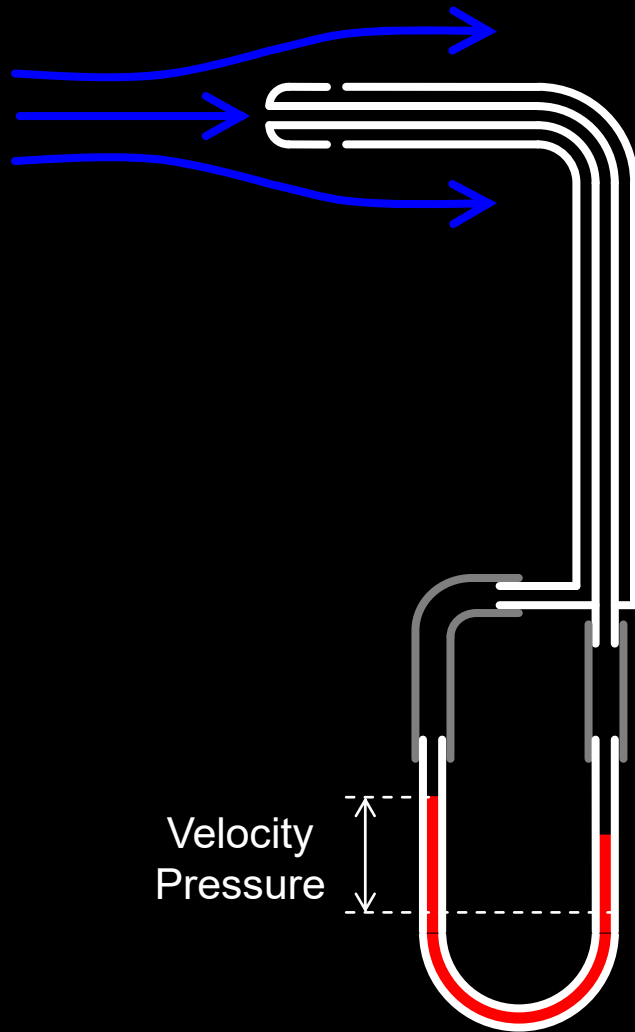
With no air flow, the pressure at both ports is the same and the level in each “leg” of the U tube is the same.

In a moving air stream, the total pressure port pushes the manometer liquid down in the tube it is connected to

But the static pressure pushes back, canceling out the static pressure portion of the total pressure signal

The resulting level difference is a measure of the velocity pressure

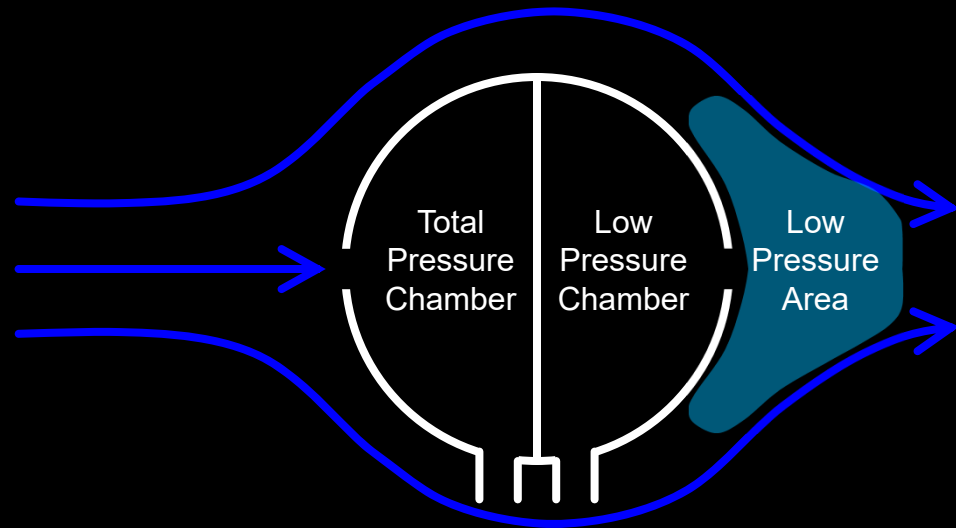
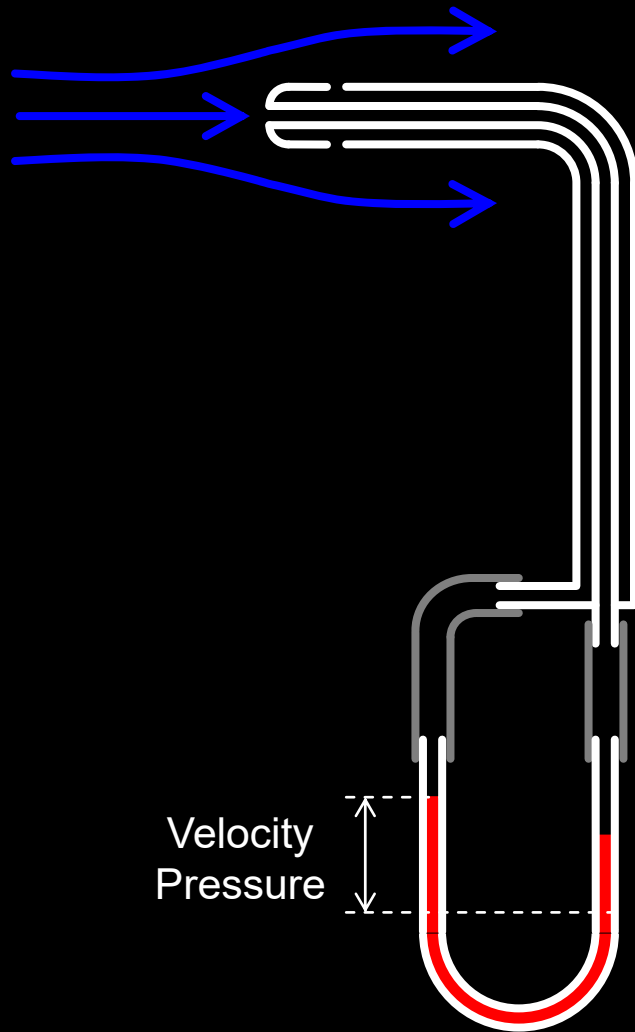
Flow Sensors are Typically a Form of Pitot Tube



Terminal unit flow sensors are typically tubes that are divided down the center, creating two chambers

- One chamber has a port facing into the air flow
- The other has a port facing away from the air flow

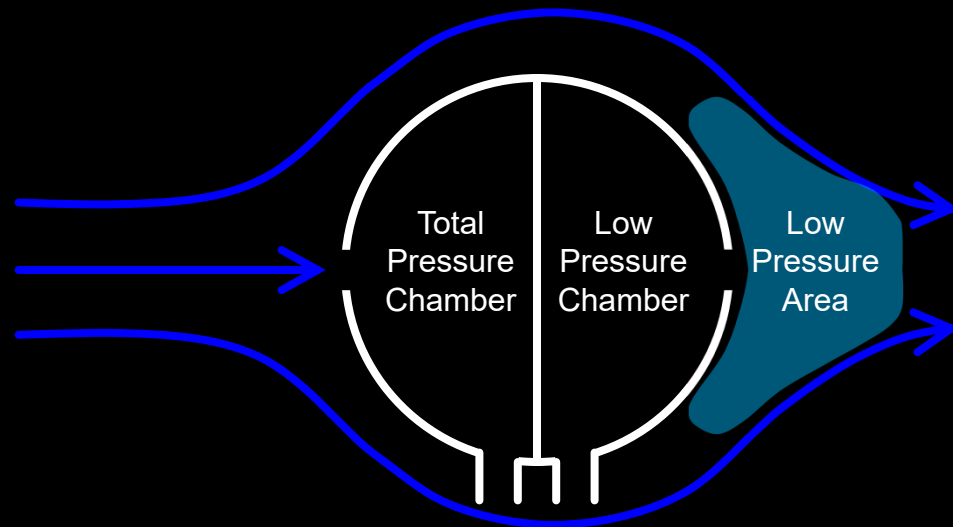
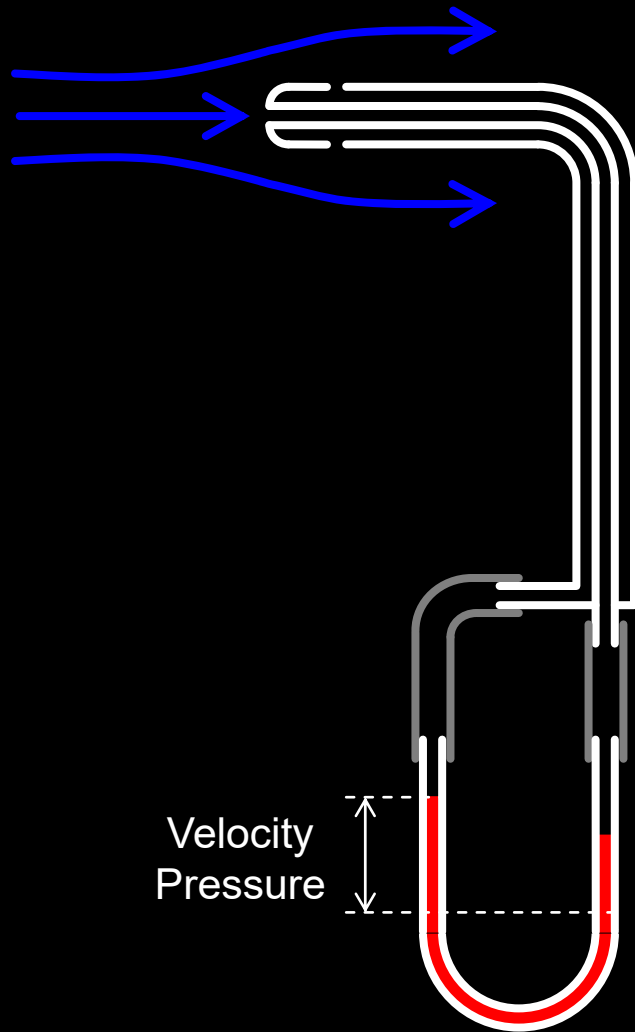
Flow Sensors are Typically a Form of Pitot Tube



The chamber facing the air flow sees total pressure

The chamber facing away from the air flow sees a **low pressure area** in the wake of the flow around the tube

Flow Sensors are Typically a Form of Pitot Tube



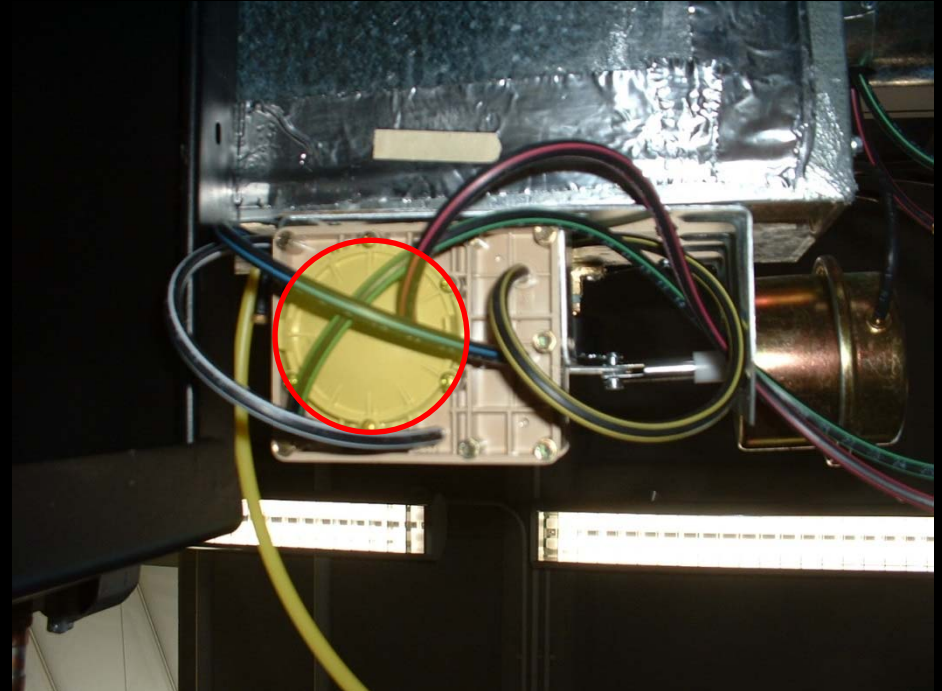
The difference between the two pressures is an “amplified velocity” pressure signal

The “amplification” allows the VAV box controller to work at lower flows than would be possible if actual velocity pressure were sensed

The Relationship Between Velocity and Velocity Pressure

12 inch VAV Box

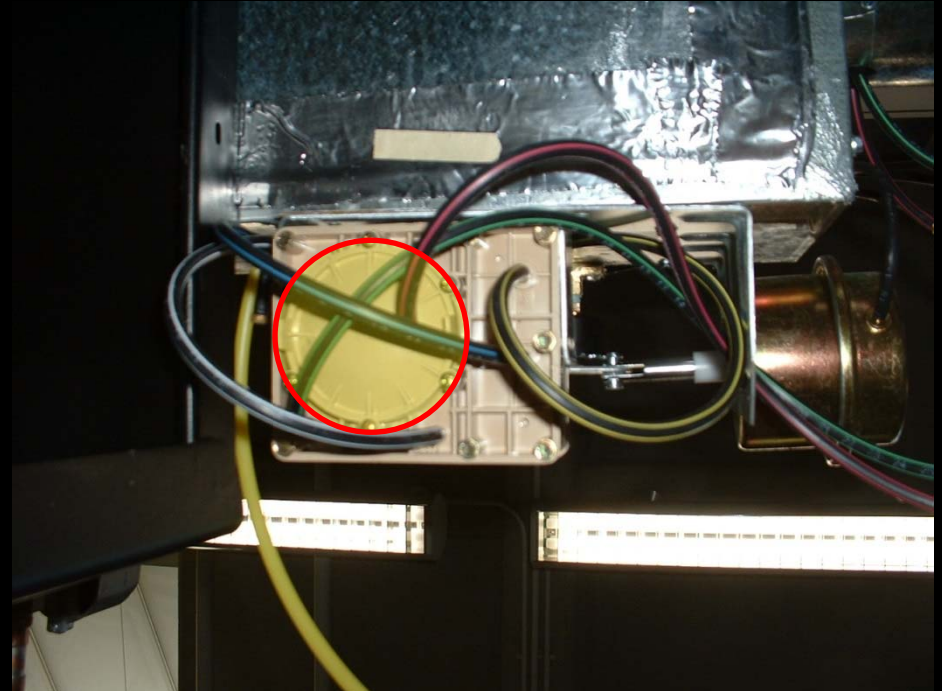
- Maximum flow
 - 2,000 cfm
 - $VP = 0.2494 \text{ in.w.c.}$
- Minimum flow
 - 325 cfm
 - $VP = 0.0066 \text{ in.w.c.}$



The Relationship Between Velocity and Velocity Pressure

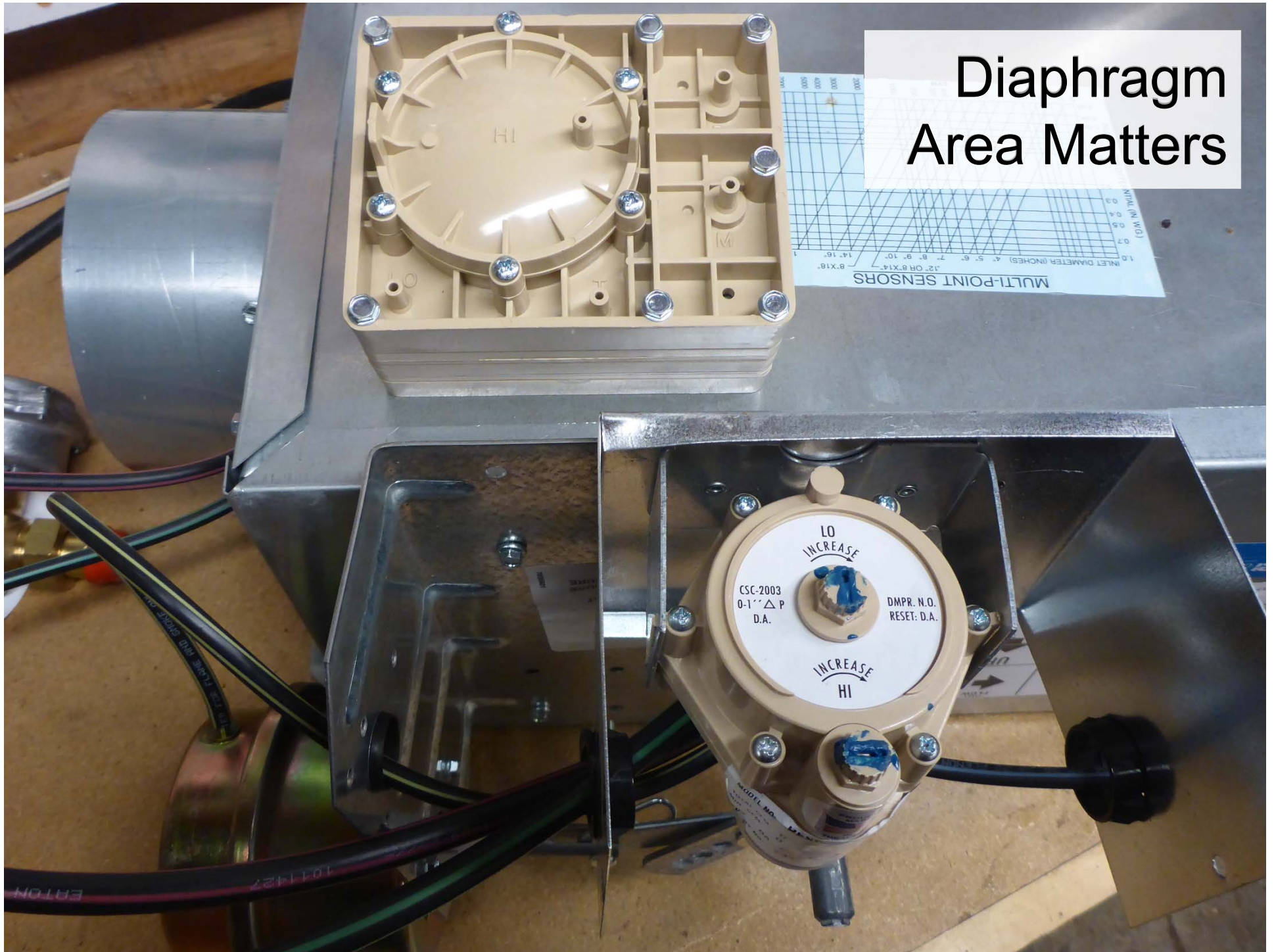
12 inch VAV Box

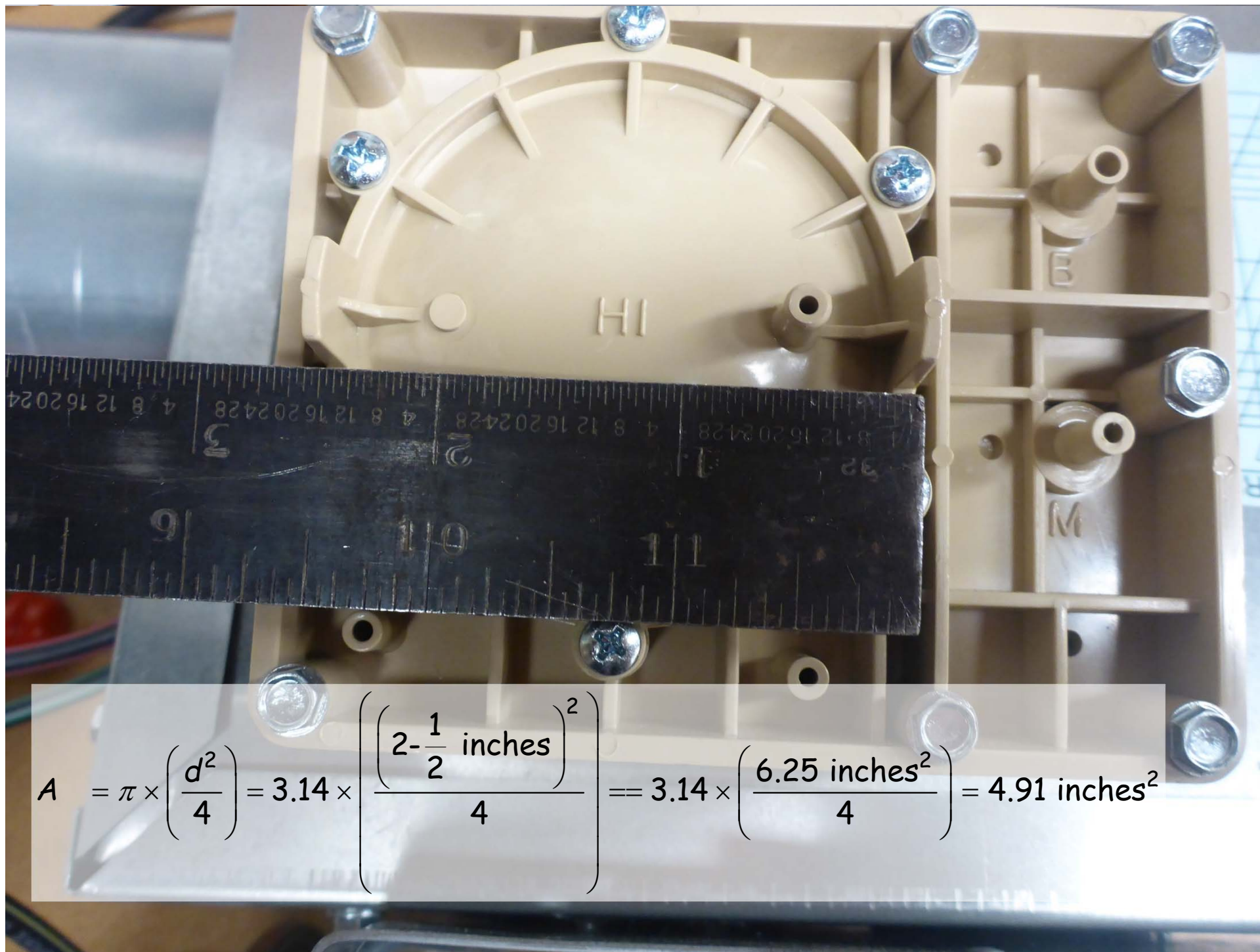
- Maximum flow
 - 2,000 cfm
 - $VP = 0.2494 \text{ in.w.c.}$
 - Force = 0.0442 lb
 - Force = 0.7066 oz
- Minimum flow
 - 325 cfm
 - $VP = 0.0066 \text{ in.w.c.}$
 - Force = 0.0012 lb
 - Force = 0.0187 oz



Frame of reference; a letter in an envelop weighs about 1 oz.

Diaphragm Area Matters





$$A = \pi \times \left(\frac{d^2}{4} \right) = 3.14 \times \left(\frac{\left(2 - \frac{1}{2} \text{ inches} \right)^2}{4} \right) = 3.14 \times \left(\frac{6.25 \text{ inches}^2}{4} \right) = 4.91 \text{ inches}^2$$

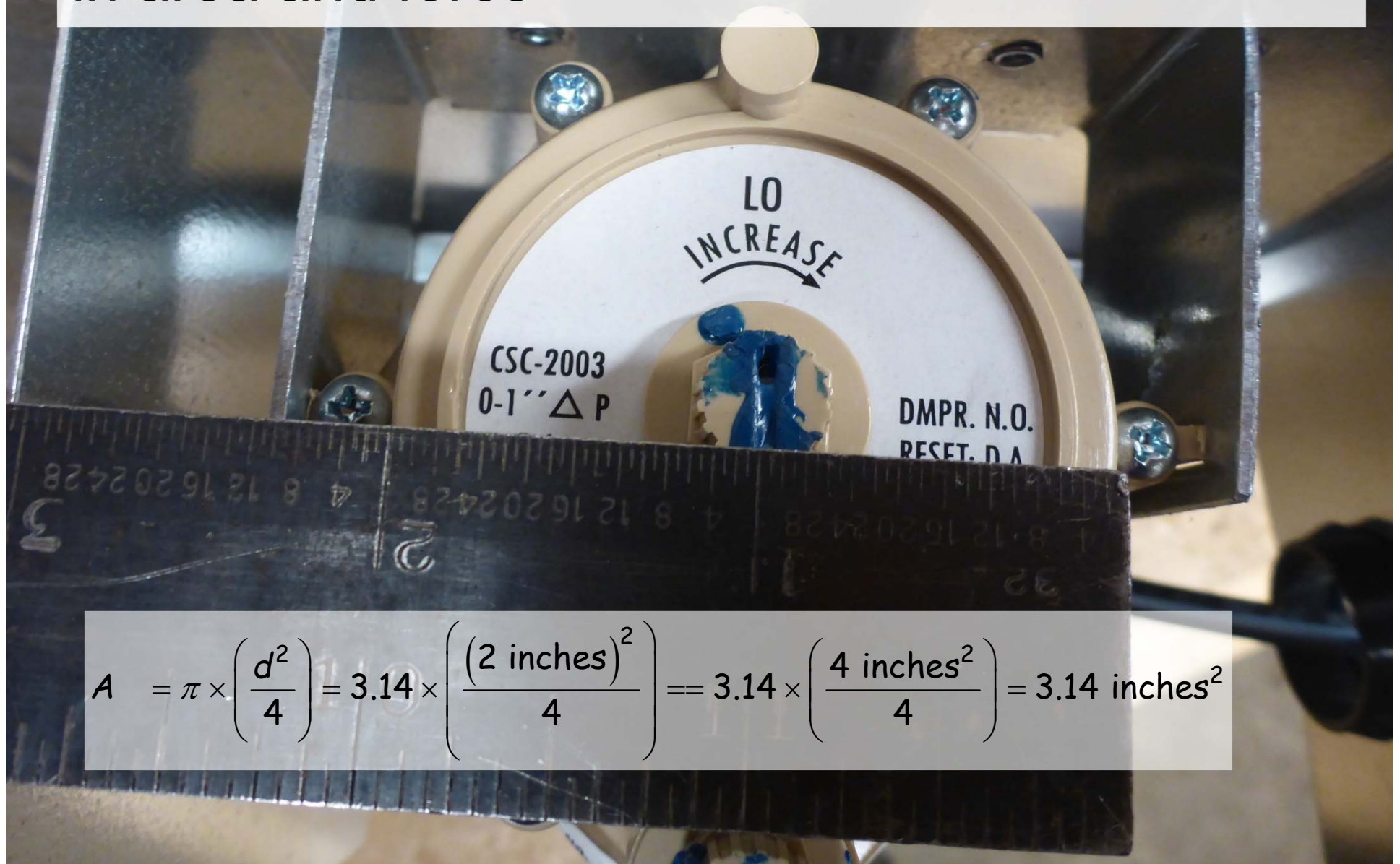
LO
INCREASE

CSC-2003
0-1" Δ P

DMPR. N.O.
RESET. D.A.

$$A = \pi \times \left(\frac{d^2}{4} \right) = 3.14 \times \left(\frac{(2 \text{ inches})^2}{4} \right) = 3.14 \times \left(\frac{4 \text{ inches}^2}{4} \right) = 3.14 \text{ inches}^2$$

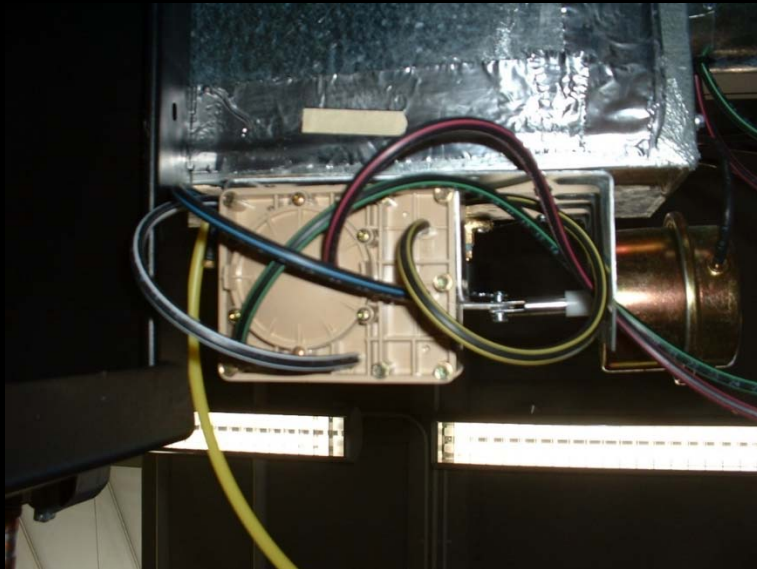
A 20% reduction in diameter = 36% reduction in area and force



$$A = \pi \times \left(\frac{d^2}{4} \right) = 3.14 \times \left(\frac{(2 \text{ inches})^2}{4} \right) = 3.14 \times \left(\frac{4 \text{ inches}^2}{4} \right) = 3.14 \text{ inches}^2$$

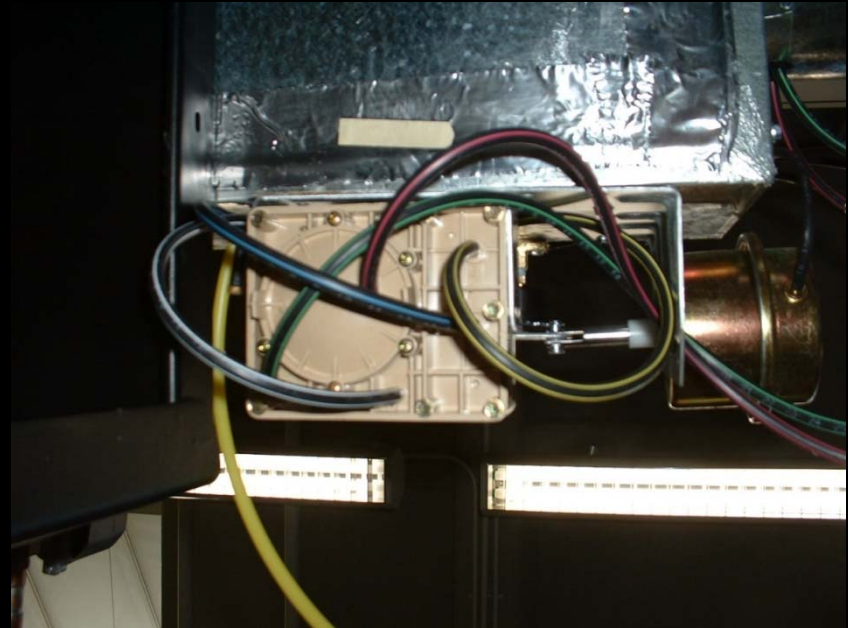
Pneumatic Terminal Failure Modes

- Flow set points drift up
- Recent experience
 - Sample 10 of 45 pneumatic zones
 - Three years since last service effort
- Many of the controllers worked
- Many thermostats were out of calibration
- 0 (zero) zones were regulating at the required flow
- Many zones were wide open
- Some reheat valves were leaking through



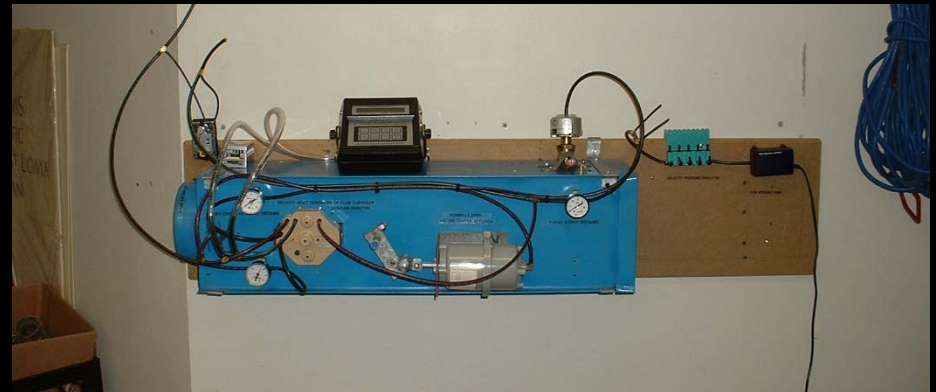
Pneumatic Terminal Bottom Lines

- Pneumatic terminals are common in existing buildings
- Pneumatic terminals are still being installed in “match existing” tenant improvement projects

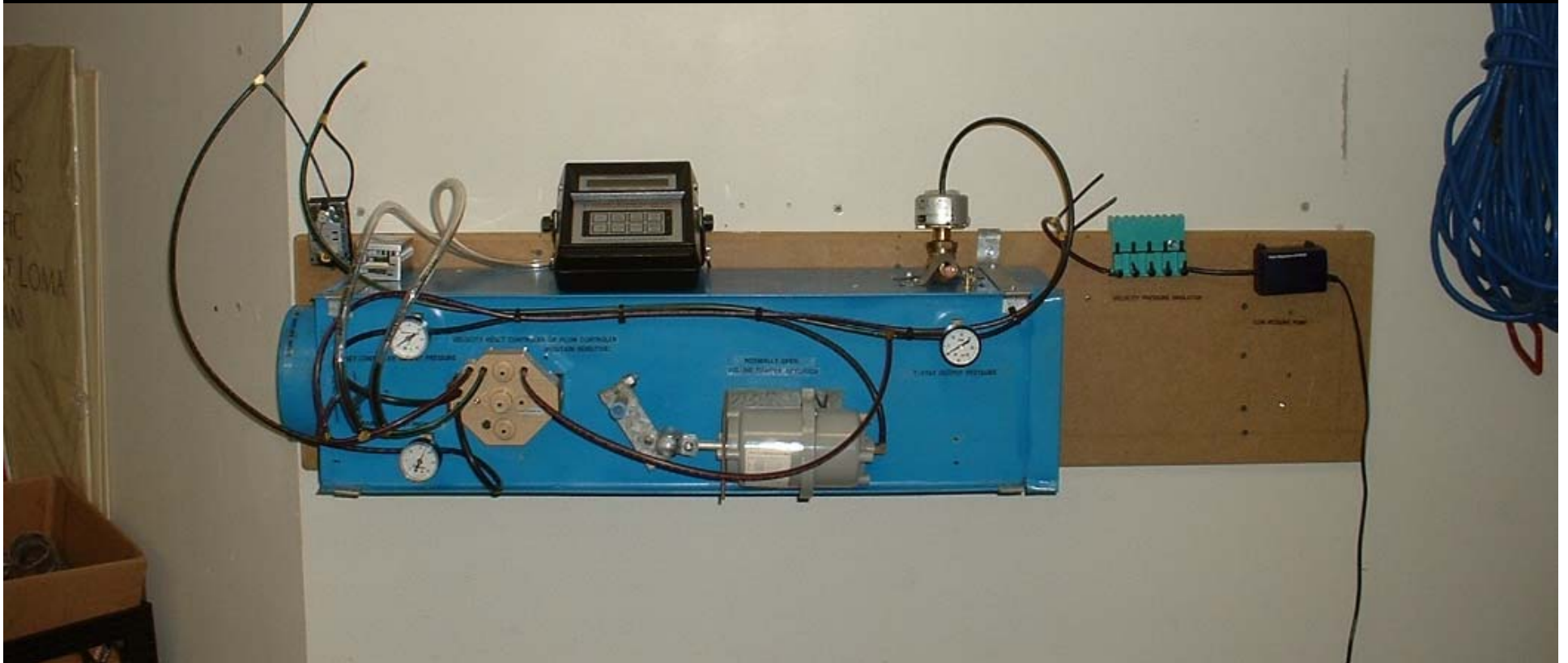


Pneumatic Terminal Bottom Lines

- Pneumatic terminals are common in existing buildings
- Pneumatic terminals are still being installed in “match existing” tenant improvement projects
- Pneumatic terminals represent an opportunity for mechanically minded folks to make a big impact on building performance and efficiency



The Real Challenge: Creating an in.w.c. test signal



The Real Challenge: Creating an in.w.c. test signal

Elegant but Expensive



The Real Challenge: Creating an in.w.c. test signal

Less Elegant, but Less
Expensive (and Kind of
Clever)



The Real Challenge:

Creating an in.w.c. test signal

Elegant but Expensive



Less Elegant, but Less Expensive (and Kind of Clever)



Instructions at:
<https://av8rdas.wordpress.com/2013/10/14/simulating-small-pressures-my-inch-water-column-simulator/>



Proportional Control

A Fundamental Pneumatic Control System Principle

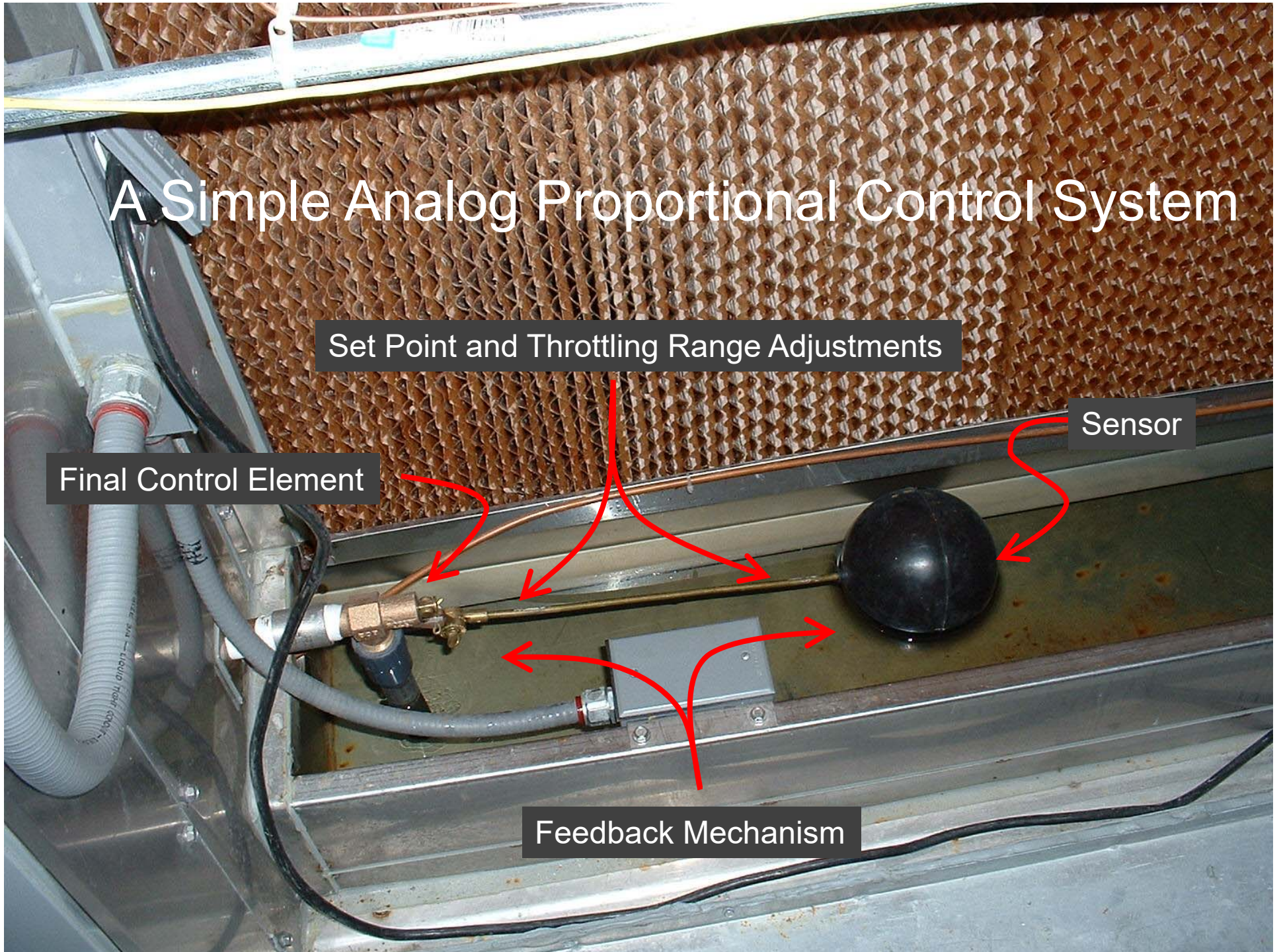
A Simple Analog Proportional Control System

Set Point and Throttling Range Adjustments

Final Control Element

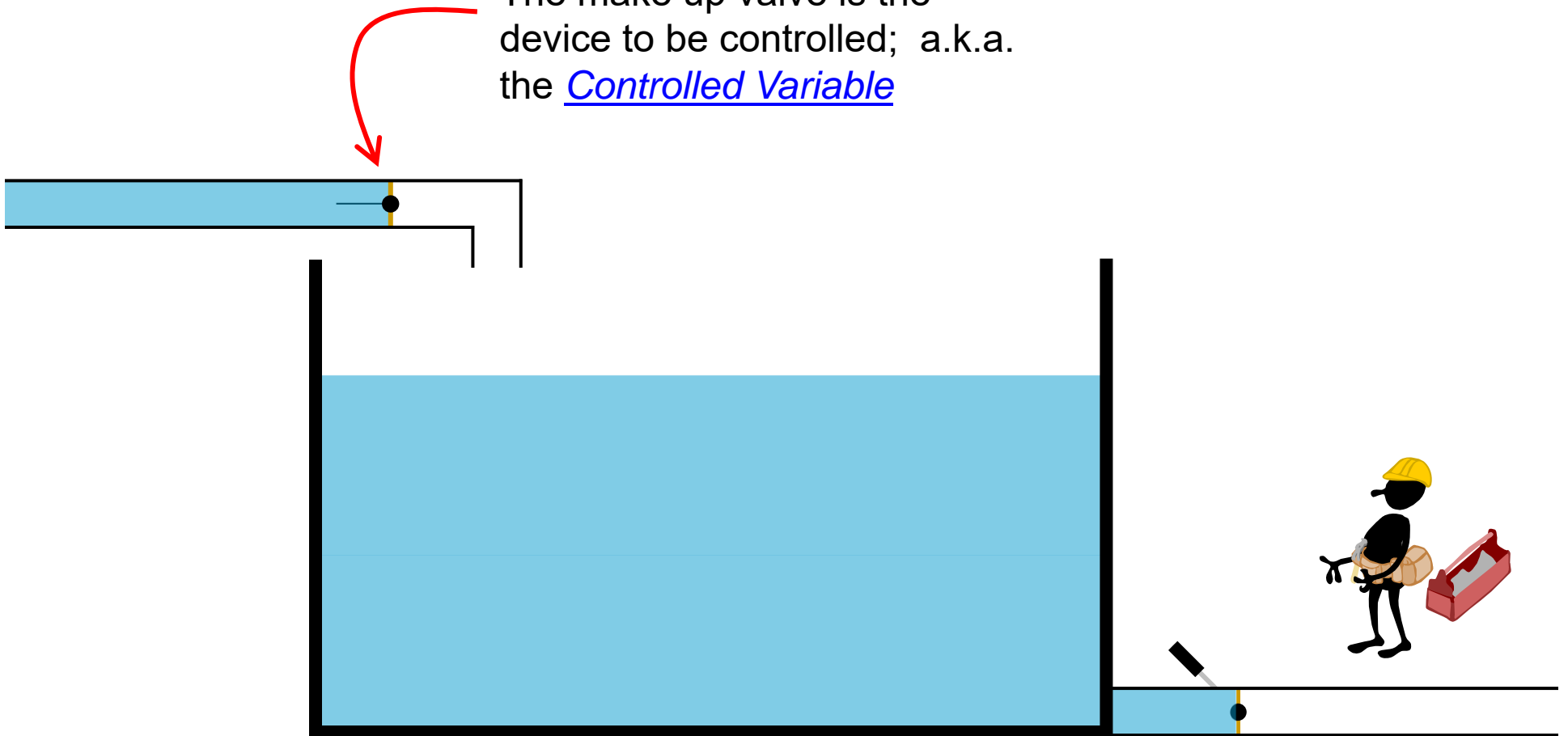
Sensor

Feedback Mechanism

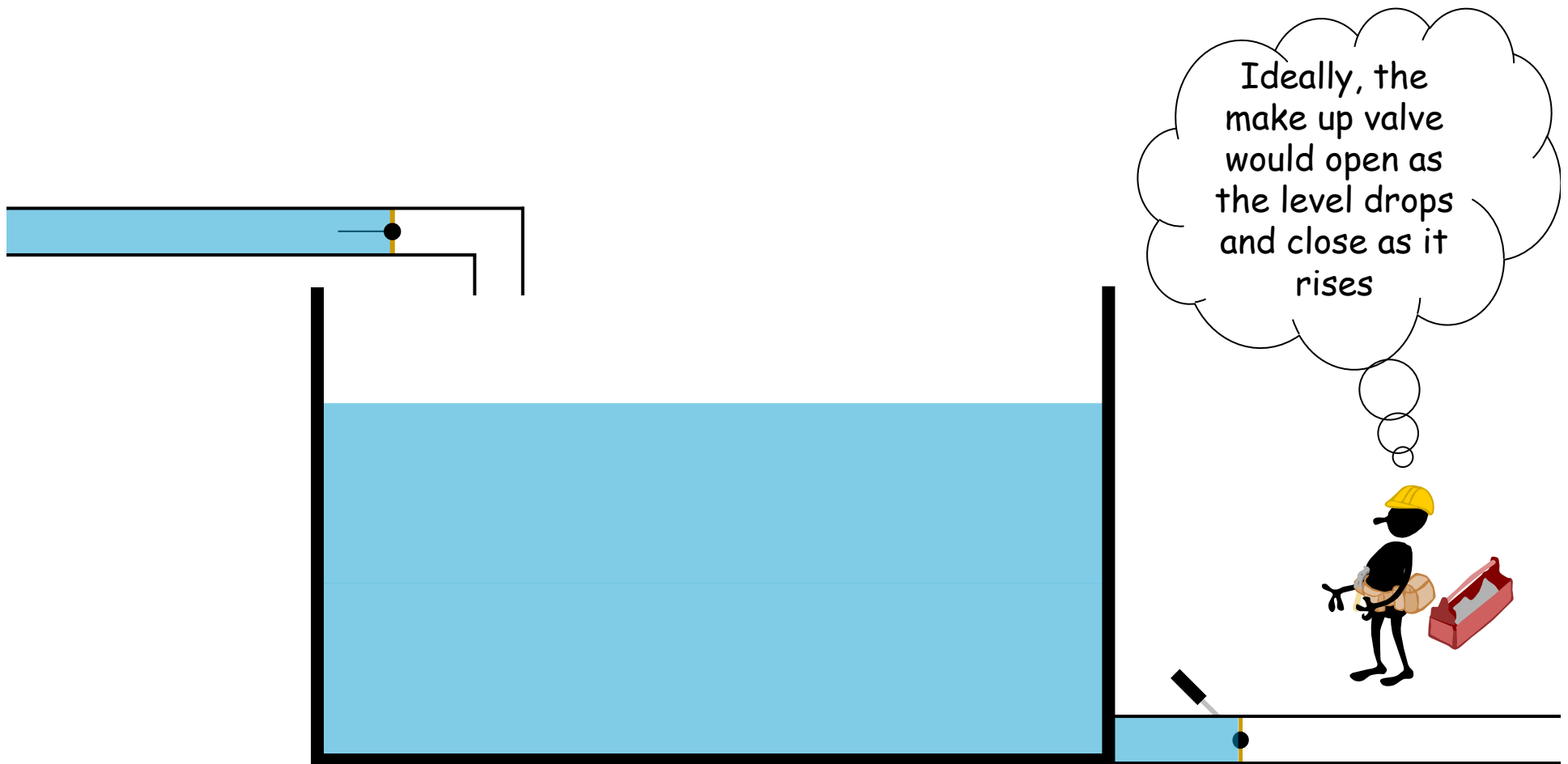


A Simple Control System

The make up valve is the device to be controlled; a.k.a. the Controlled Variable



A Simple Control System

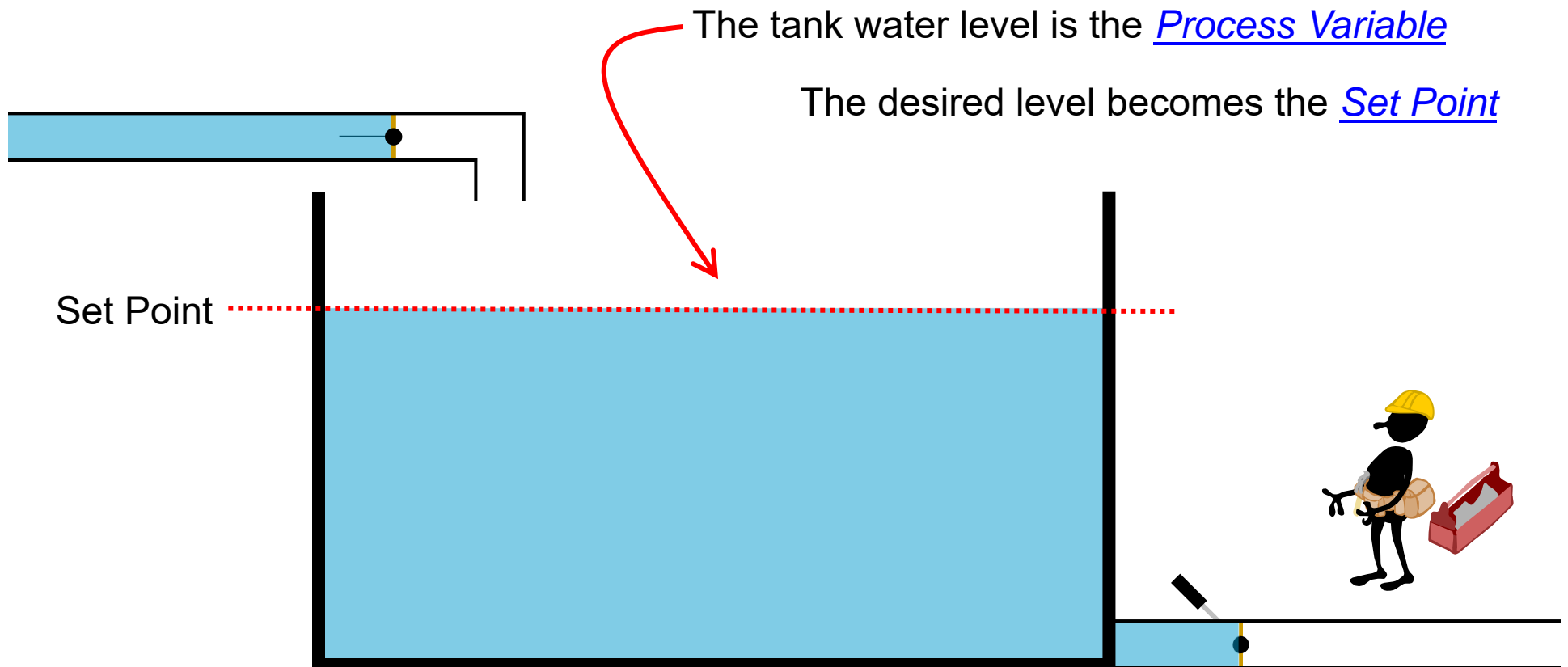


A Simple Control System

Monitoring the tank water level will allow us to gauge how much make up we need to add as demand picks up

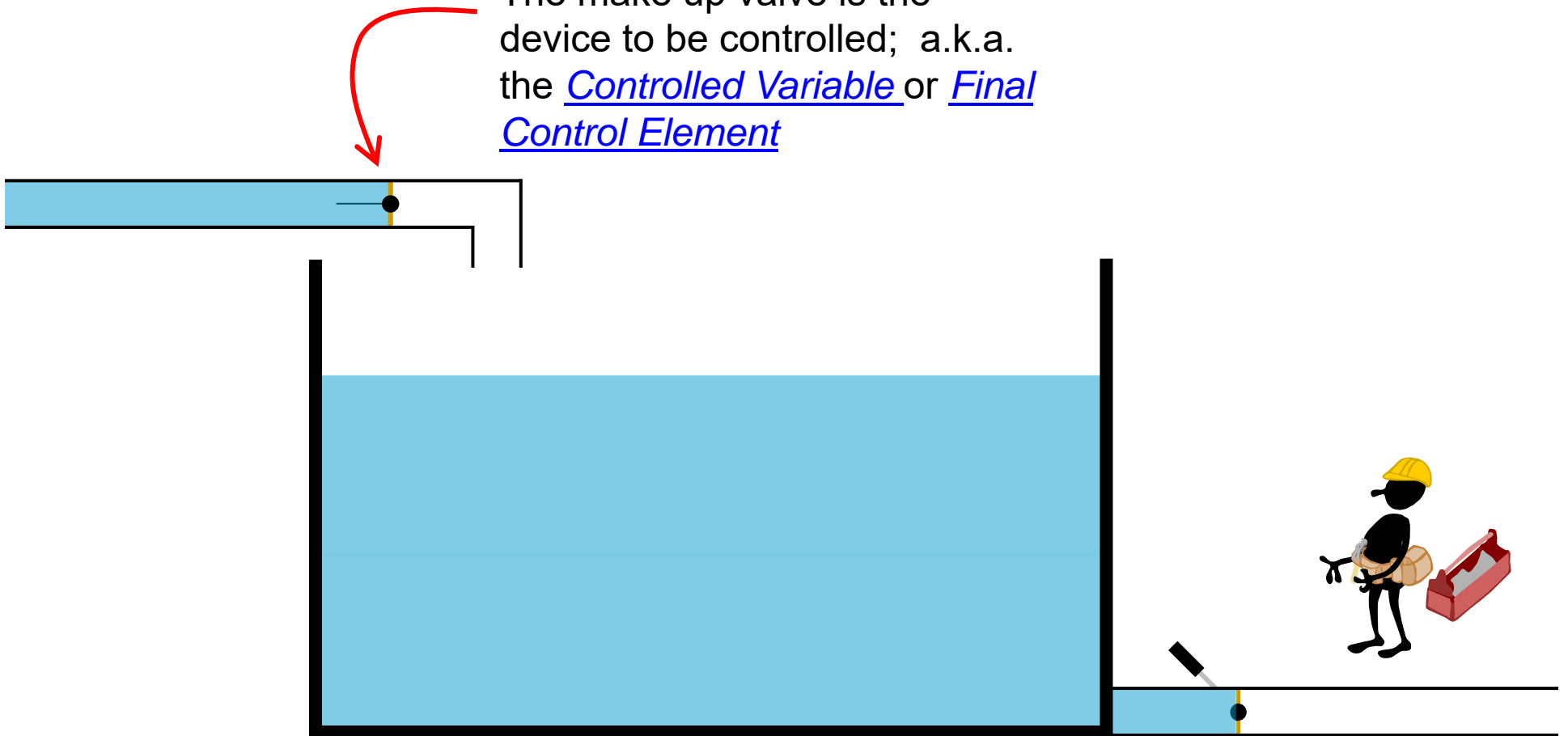


A Simple Control System

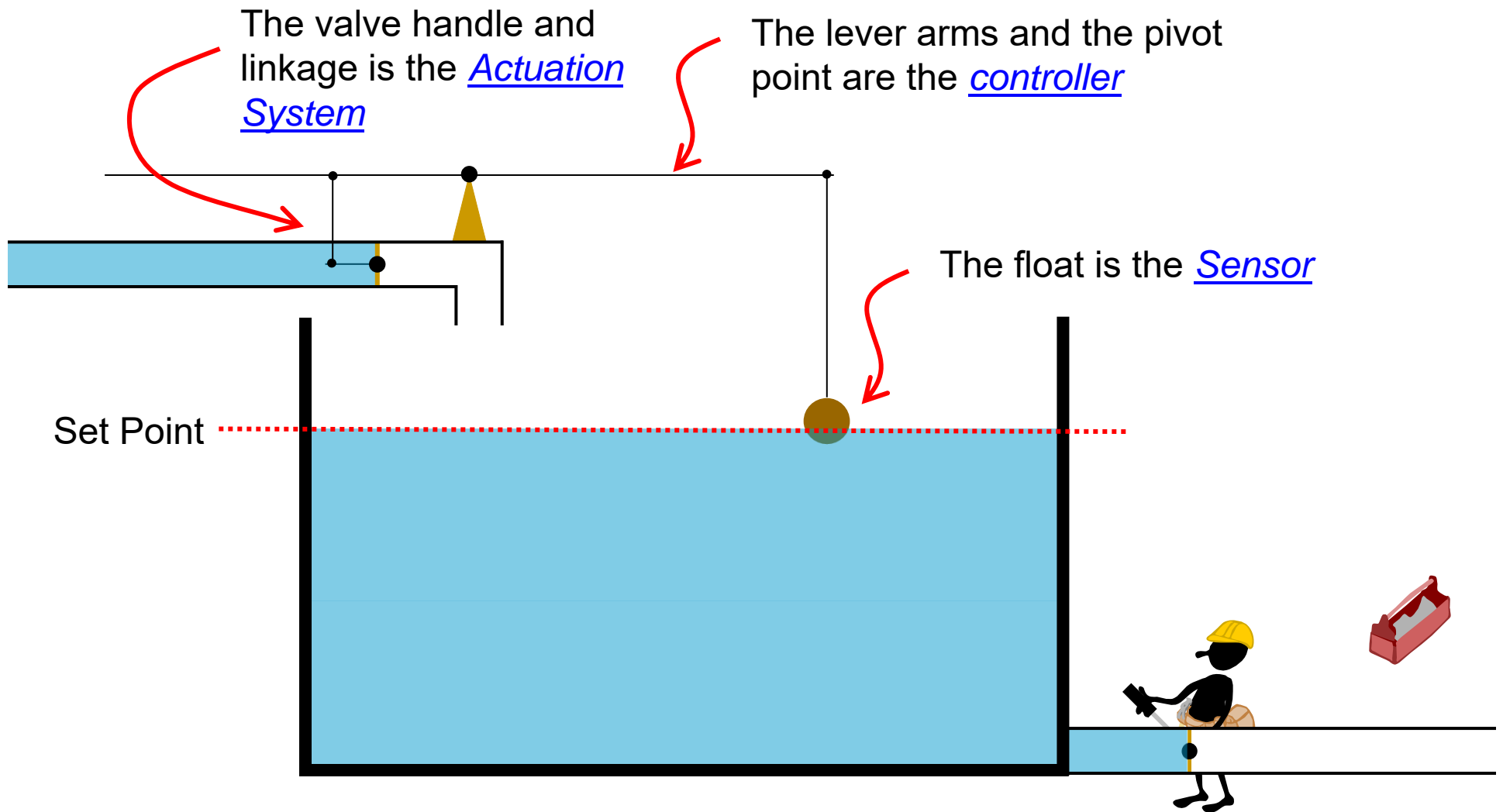


A Simple Control Requirement

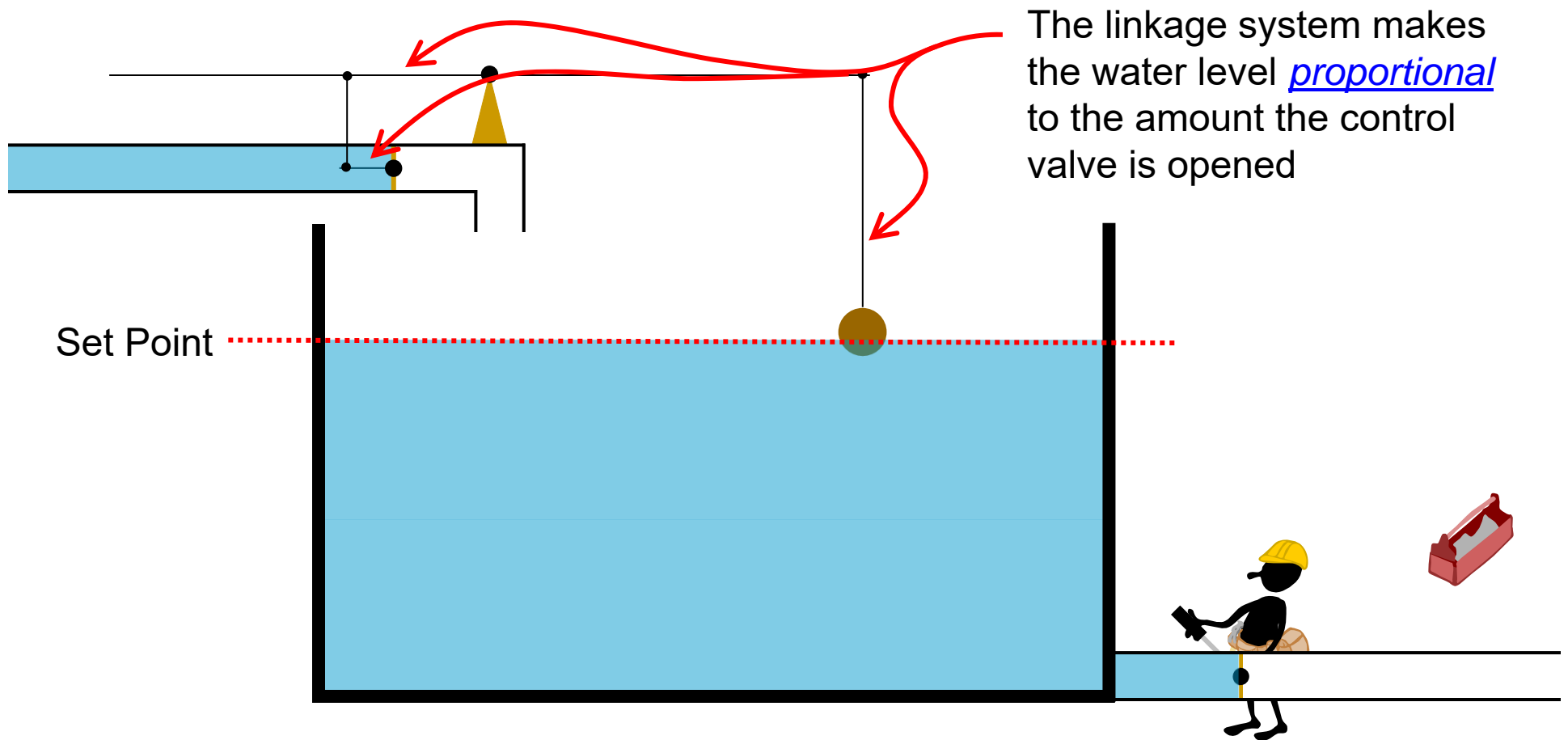
The make up valve is the device to be controlled; a.k.a. the Controlled Variable or Final Control Element



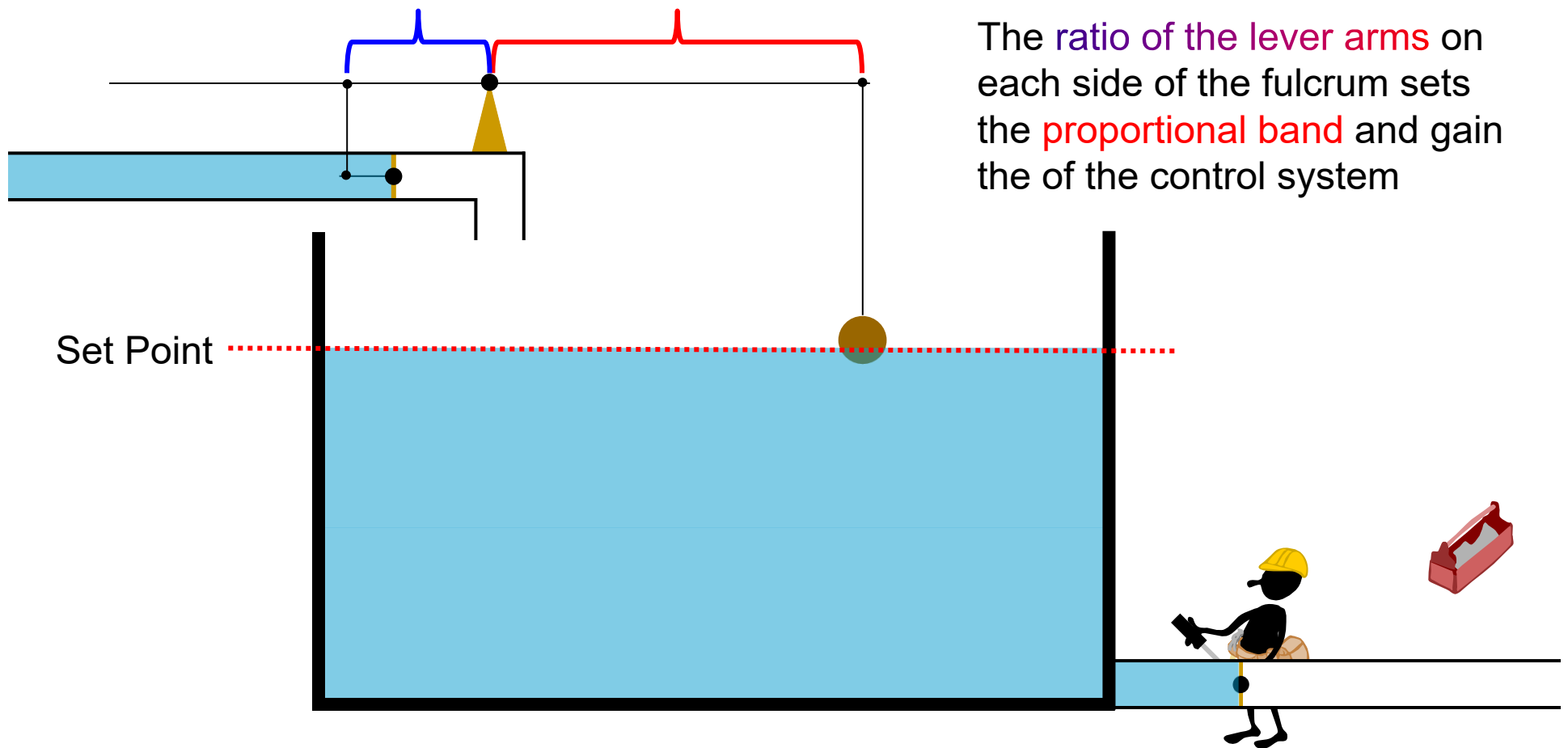
A Simple Proportional Control System



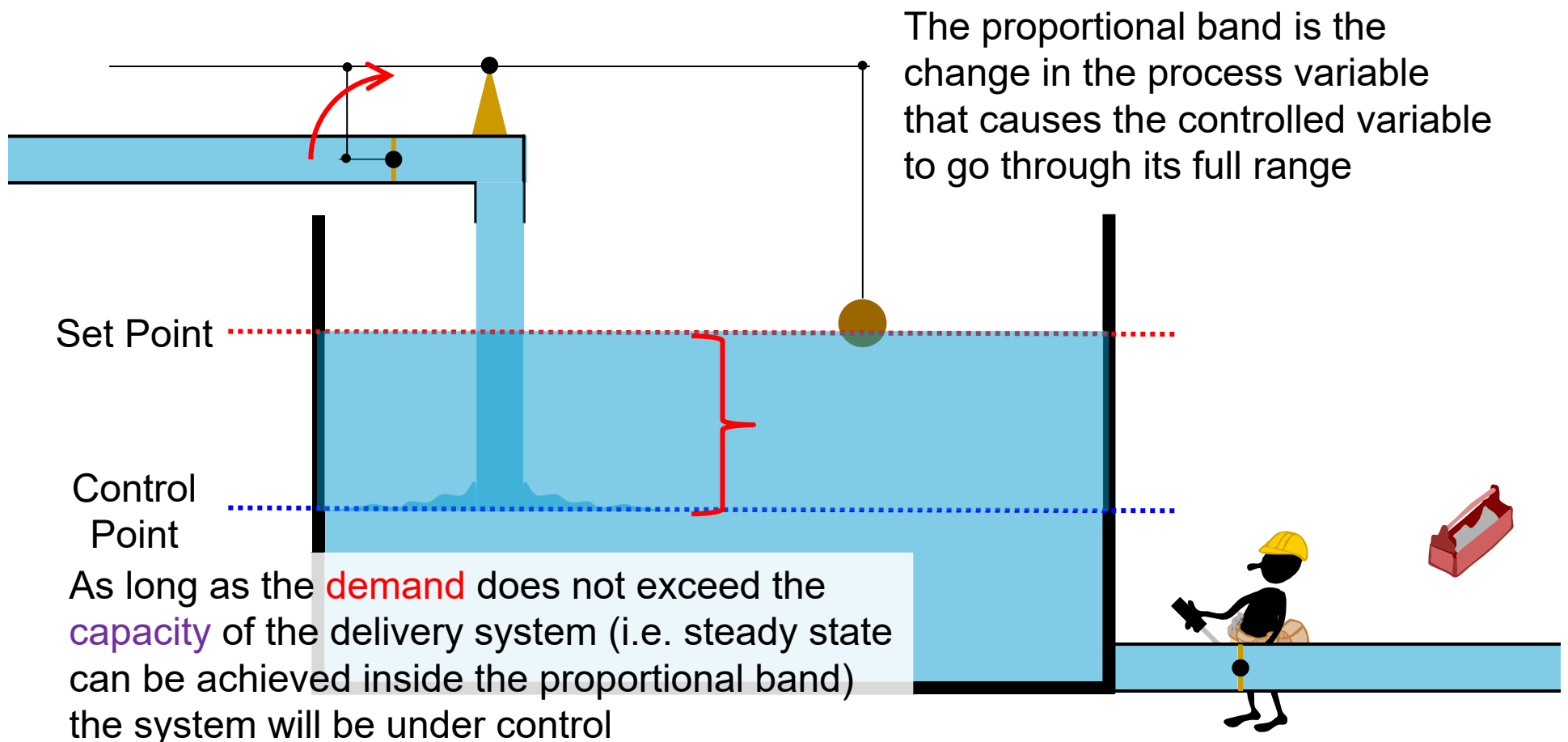
A Simple Proportional Control System



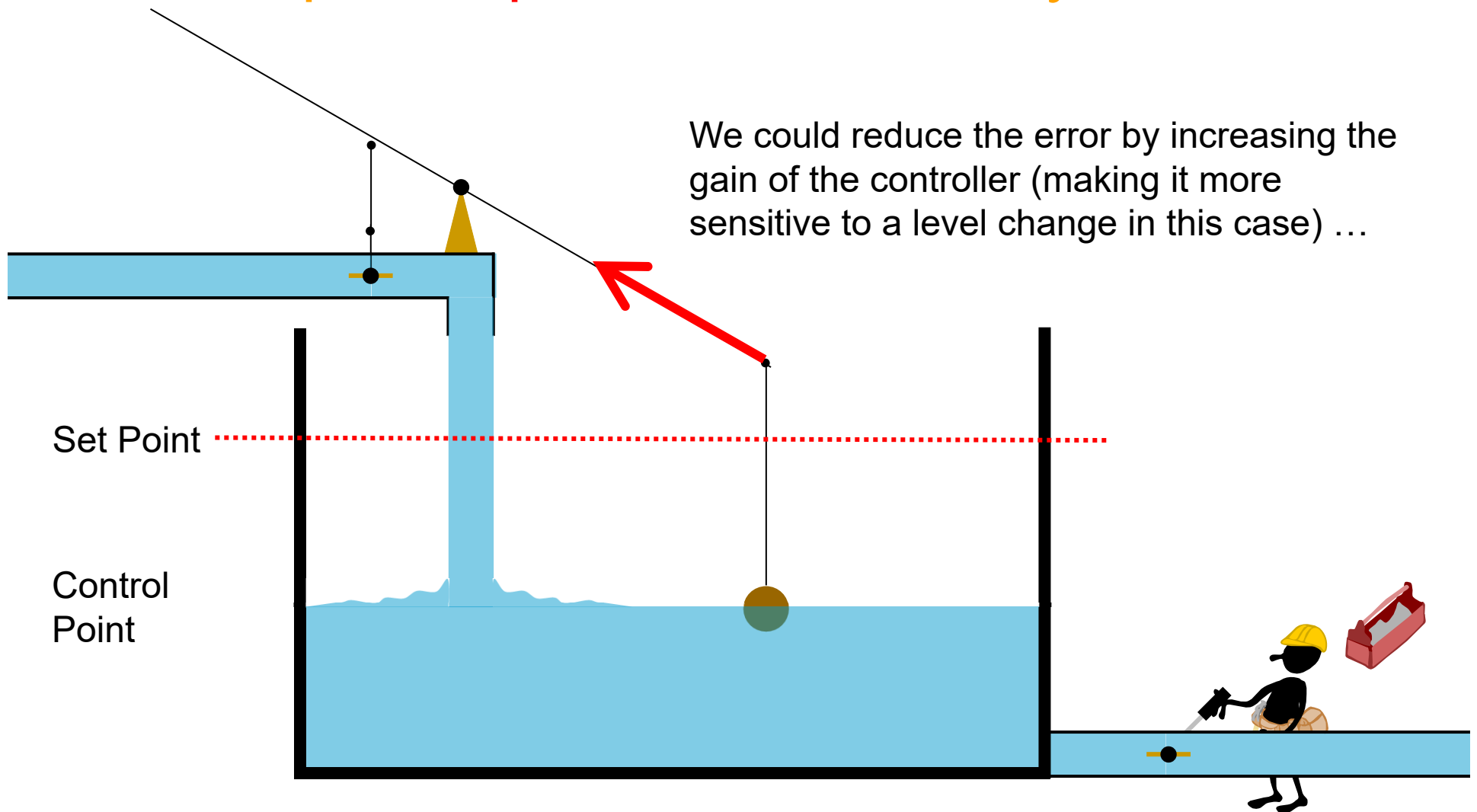
A Simple Proportional Control System



A Simple Proportional Control System

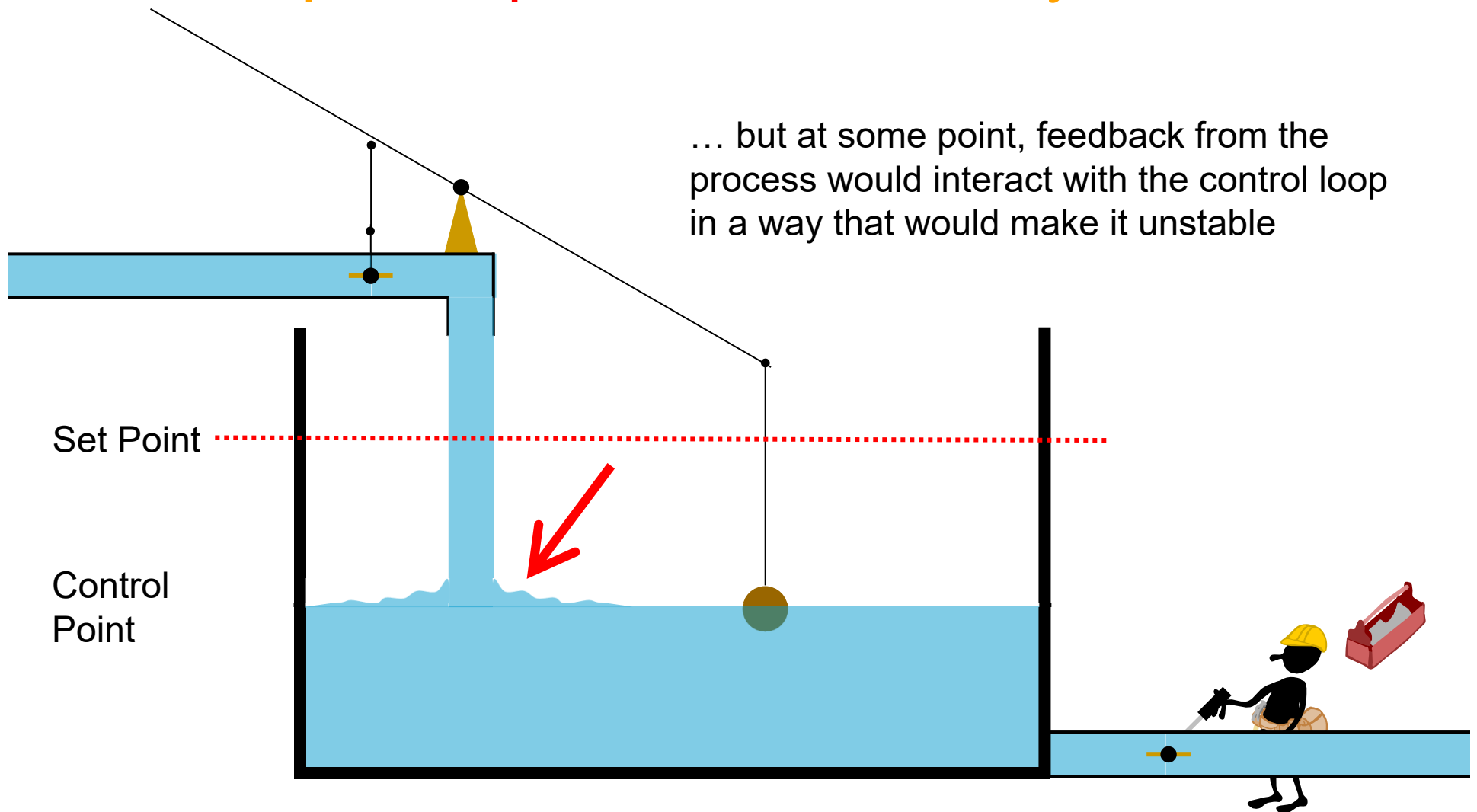


A Simple Proportional Control System



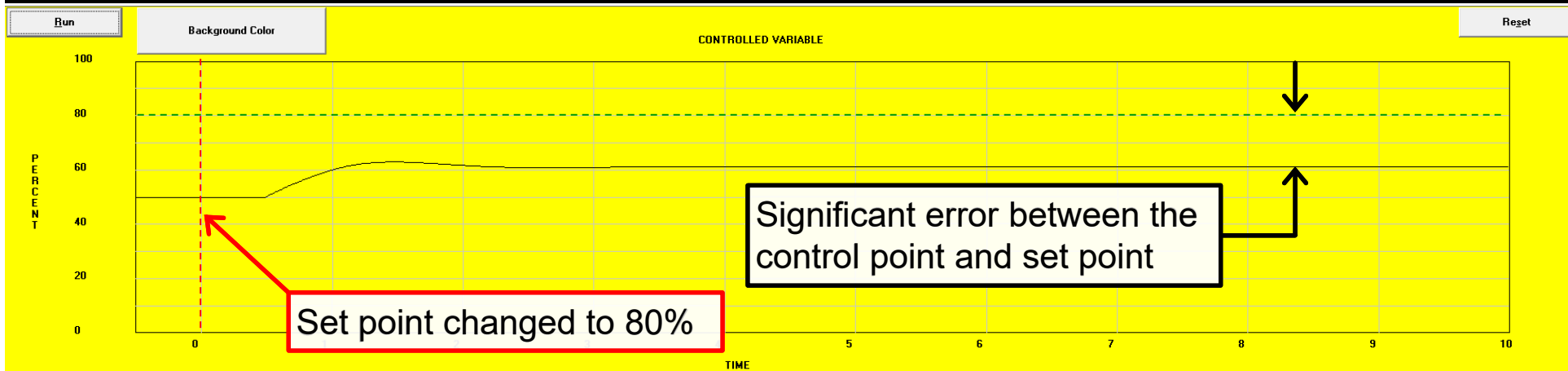
A Simple Proportional Control System

... but at some point, feedback from the process would interact with the control loop in a way that would make it unstable



The Impact of Narrowing Throttling Range

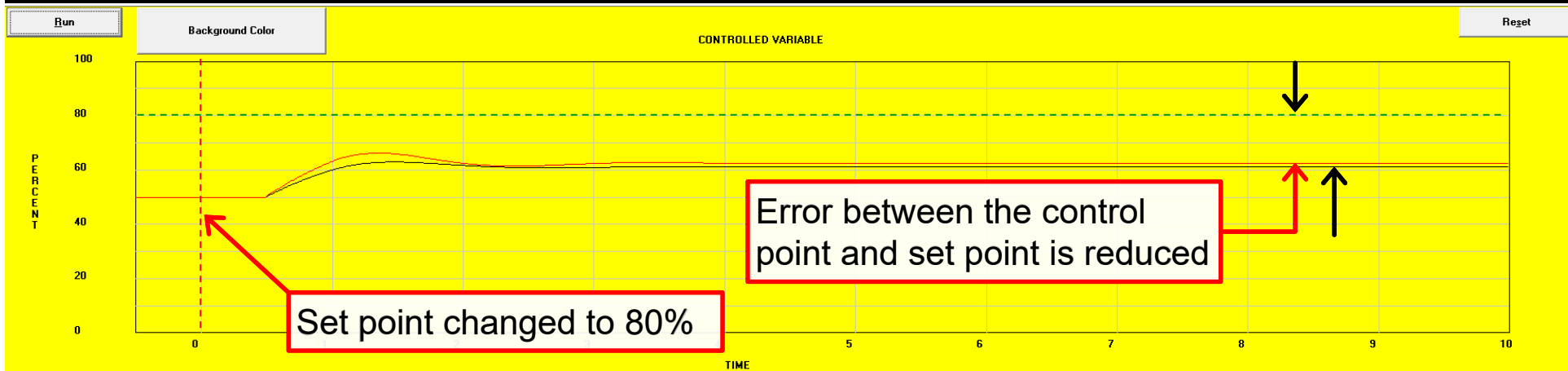
Proportional band = 400% and set point changed to 80%
(black line)



The Impact of Narrowing Throttling Range

Proportional band = 400% (black line)

Proportional band = 300% and set point changed to 80% (red line)

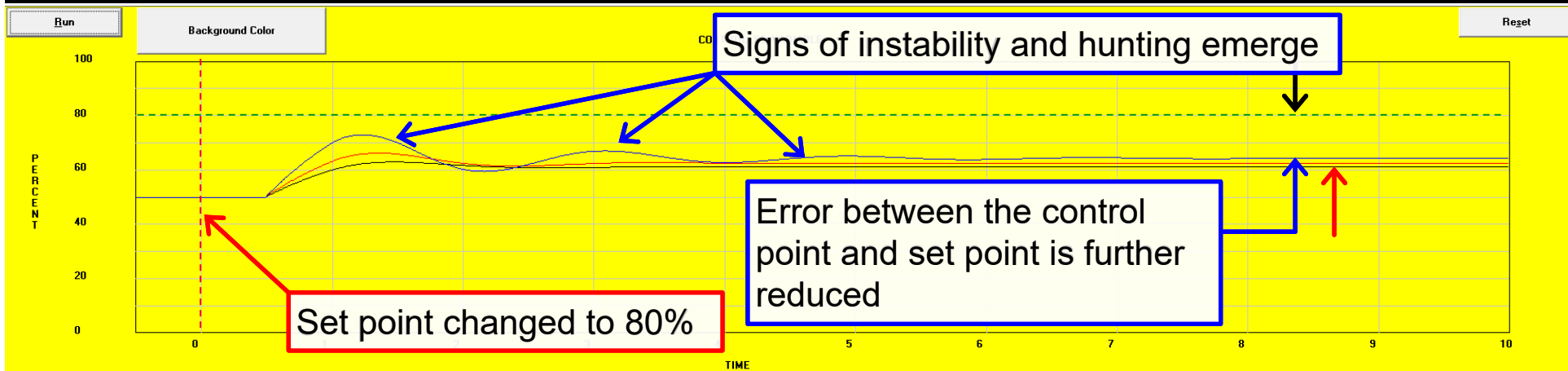


The Impact of Narrowing Throttling Range

Proportional band = 400% (black line)

Proportional band = 300% (red line)

Proportional band = 200% and set point changed to 80% (blue line)



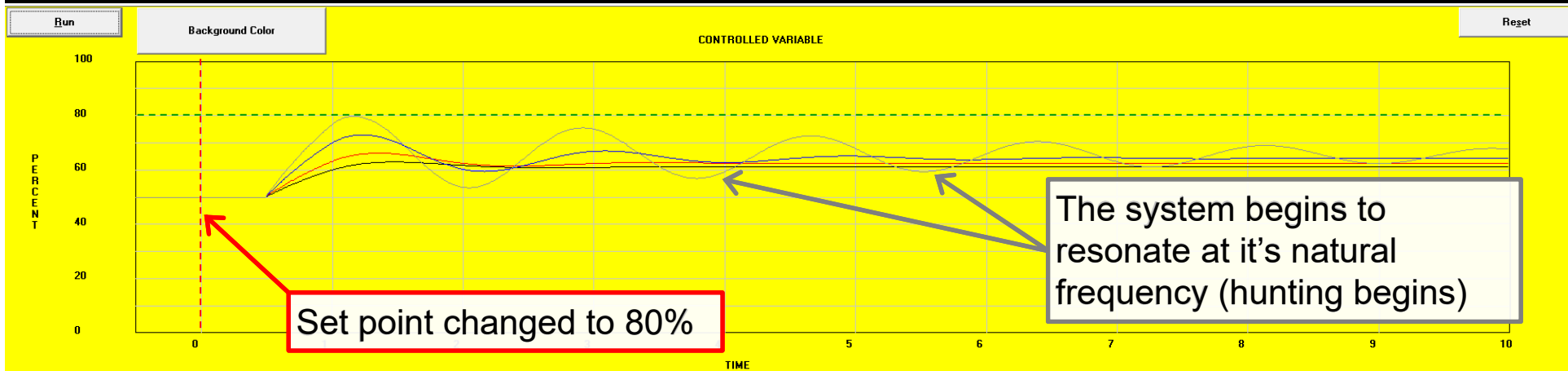
The Impact of Narrowing Throttling Range

Proportional band = 400% (black line)

Proportional band = 300% (red line)

Proportional band = 200% (blue line)

Proportional band = 150% and set point changed to 80% (gray line)



The Impact of Narrowing Throttling Range

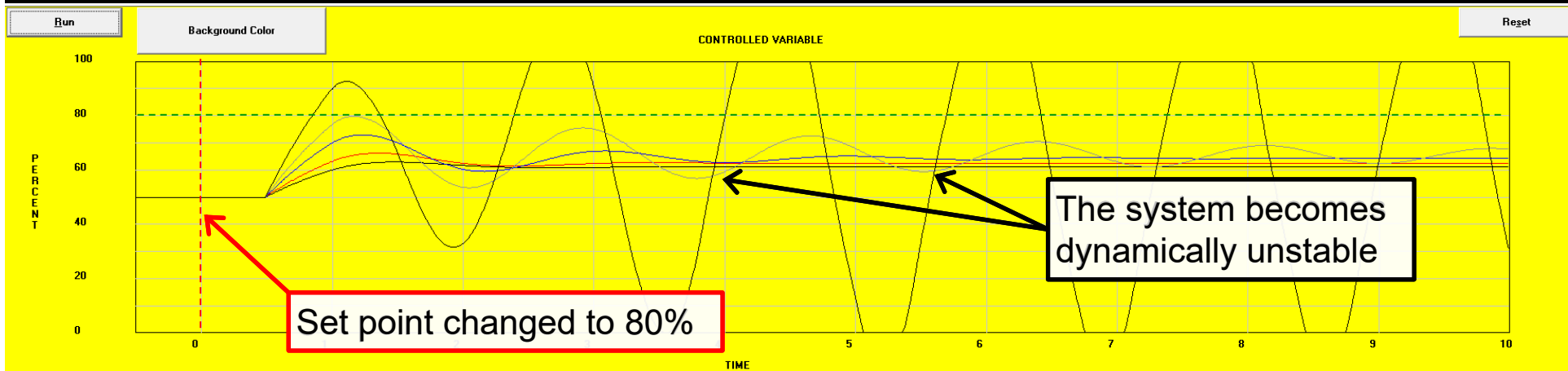
Proportional band = 400% (black line)

Proportional band = 300% (red line)

Proportional band = 200% (blue line)

Proportional band = 150% (gray line)

Proportional band = 100% and set point changed to 80% (second black line)



Bottom Lines On Proportional Control

1. All proportional control processes will show a difference between set point and control point (a.k.a. error) under all operating conditions other than one very specific condition
2. The error can be reduced by narrowing down the throttling range
3. There is a limit to how much you can narrow the throttling range without hunting
4. The limit is a function of the physics of the control system; things like lags, play in the linkage system, the nature of the process, etc.

Bottom Lines On Proportional Control

Integral and Derivative (the I and D in PID) can help address proportional error and large swings from set point during transients

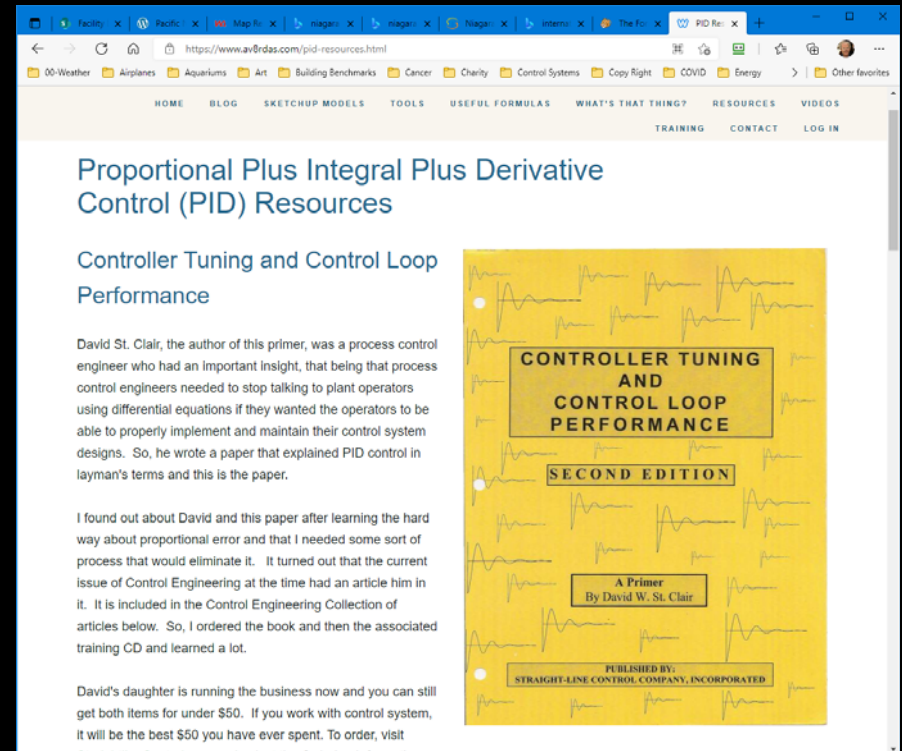
- There are pneumatic PID controllers



Bottom Lines On Proportional Control

Integral and Derivative (the I and D in PID) can help address proportional error and large swings from set point during transients

- There are pneumatic PID controllers
- Additional information on PID can be found at <https://www.av8rdas.com/pid-resources.html>





Set Points

Control System Building Blocks

*Automatically **adjust a piece of machinery** to give us what we want by comparing **what is going on** to **what we want** to go on and **making appropriate adjustments** to the process we want to control*

Inputs

Outputs

Control Process

Set Point

Measure the process variable

Adjust the controlled variable

Logic and algorithms that tries to bring the controlled variable into agreement with the set point

Our requirements for the process that is under control, which can be fixed or variable

Control System Building Blocks

*Automatically **adjust a piece of machinery** to give us what we want by comparing **what is going on** to **what we want** to go on and **making appropriate adjustments** to the process we want to control*

Inputs

Outputs

Control Process

Set Point

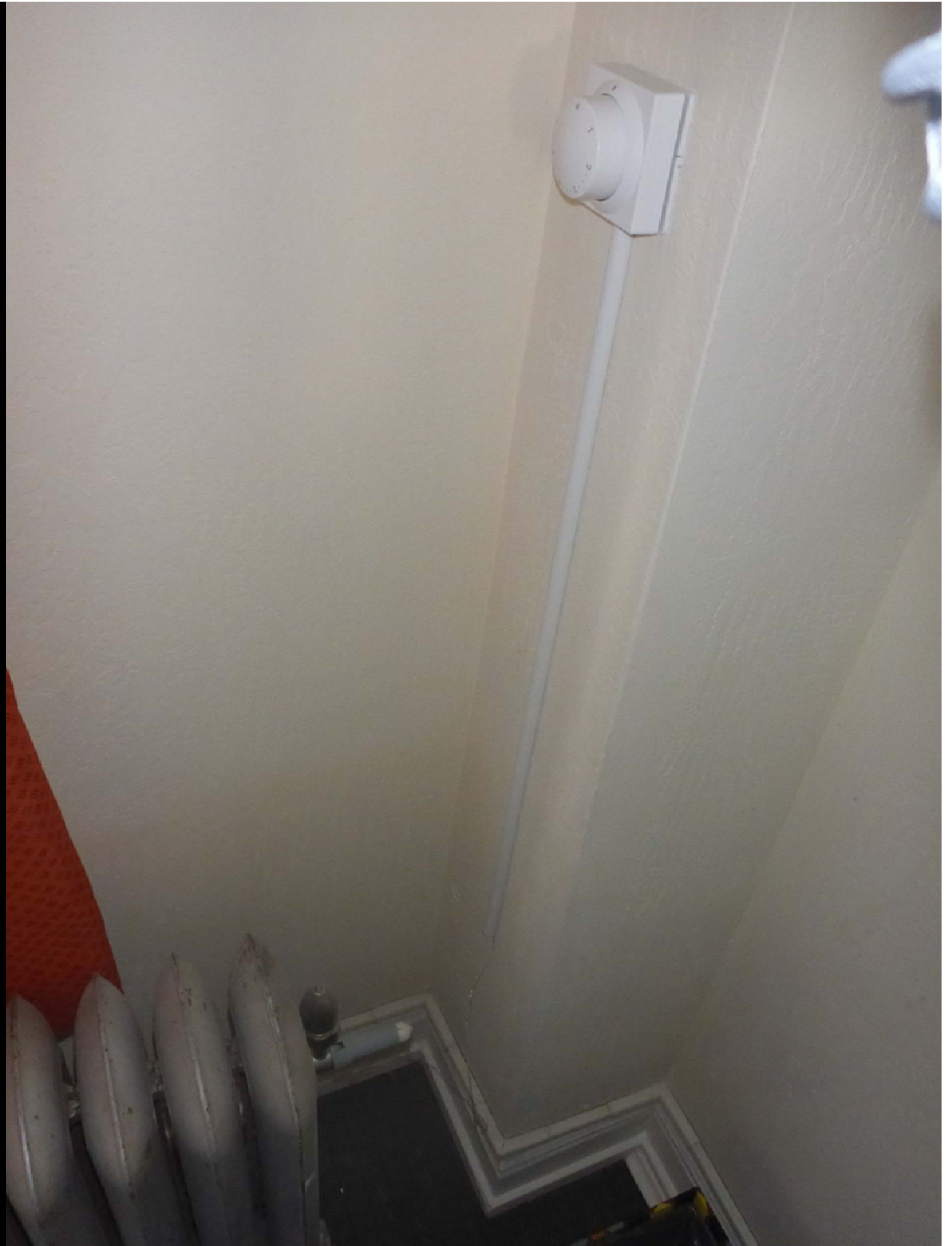
Measure the process variable

Adjust the controlled variable

Logic and algorithms that tries to bring the controlled variable into agreement with the set point

Our requirements for the process that is under control, which can be fixed or variable

A Set Point Adjustment



A Set Point Adjustment







Set Points

Are They Appropriate for the Climate?

ALTITUDE: 7 FEET
BAROMETRIC PRESSURE: 29.915 in. HG
ATMOSPHERIC PRESSURE: 14.693 psia

Set Points; Are They Appropriate For the Climate?

The dry bulb economizer
high limit set point that
works great for a given
indoor condition in San
Francisco, CA...

Weather Data Location:
SAN_FRANCISCO_INTL_AP, CALIFORNIA, USA

Weather Hours

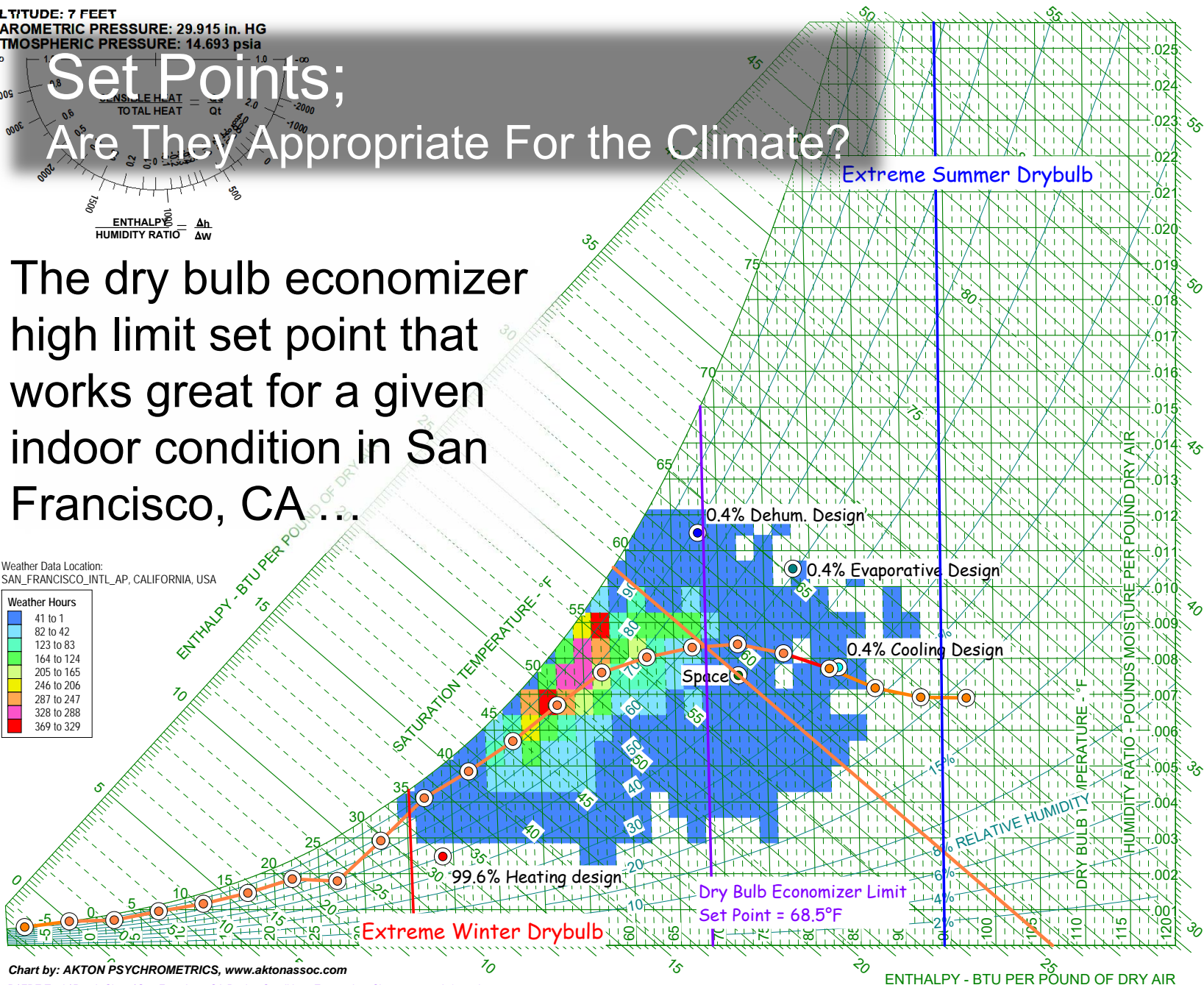
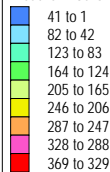


Chart by: AKTON PSYCHROMETRICS, www.aktonassoc.com

D:\FDE Tools\Ppsych Charts\San Francisco, CA Design Conditions Economizer Change-over 72 45.aad

ALTITUDE: 568 FEET
BAROMETRIC PRESSURE: 29.313 in. HG
ATMOSPHERIC PRESSURE: 14.397 psia

Set Points; Are They Appropriate For the Climate?

... may be totally
wrong for the same
indoor condition in
St. Louis, MO

Weather Data Location:
ST_LOUIS_LAMBERT_INT'L_ARPT, MISSOURI, USA

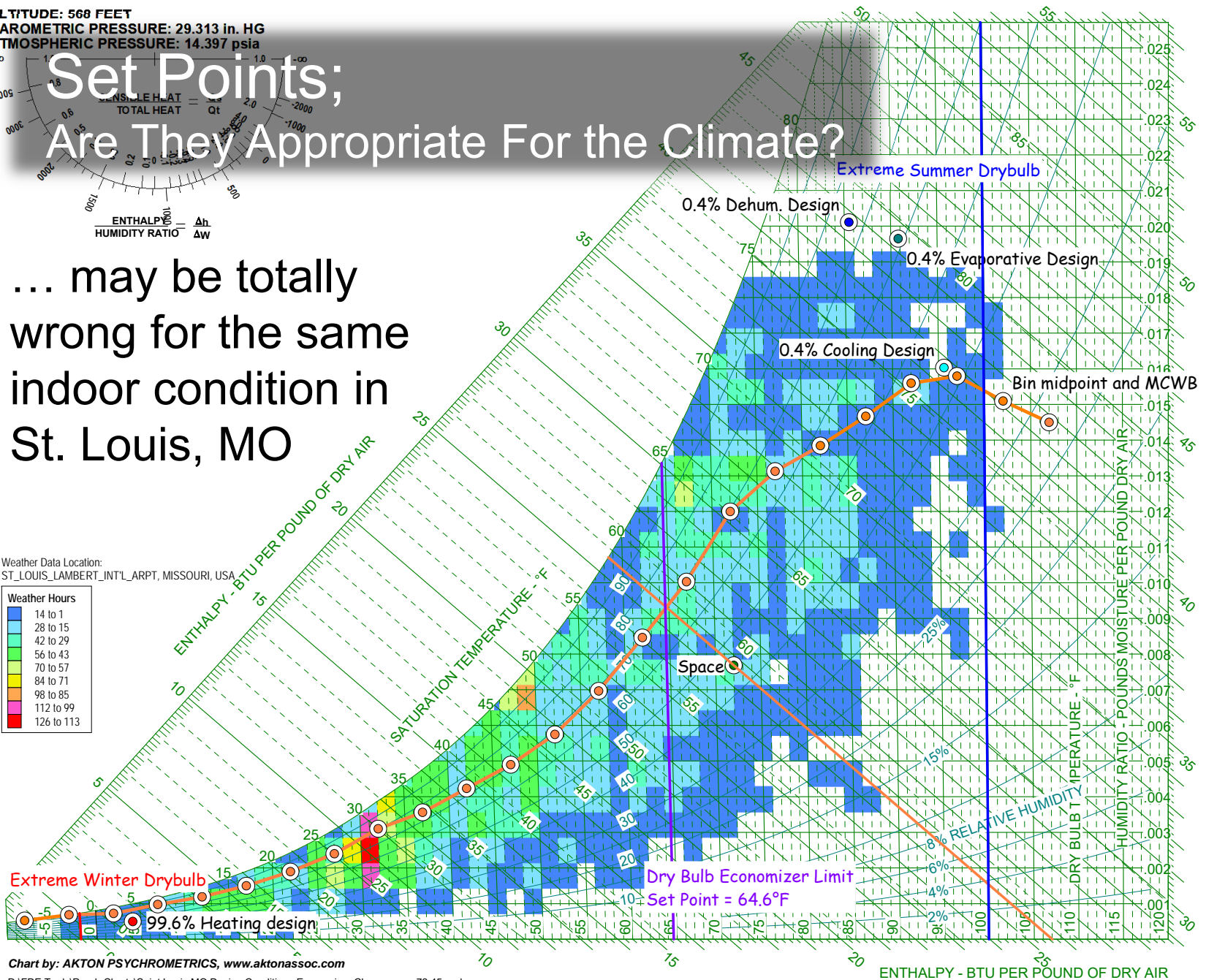
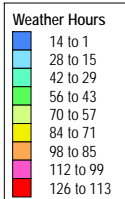


Chart by: AKTON PSYCHROMETRICS, www.aktonassoc.com

D:\FDE Tools\Psych Charts\Saint Louis MO Design Conditions Economizer Change-over 72 45.aad



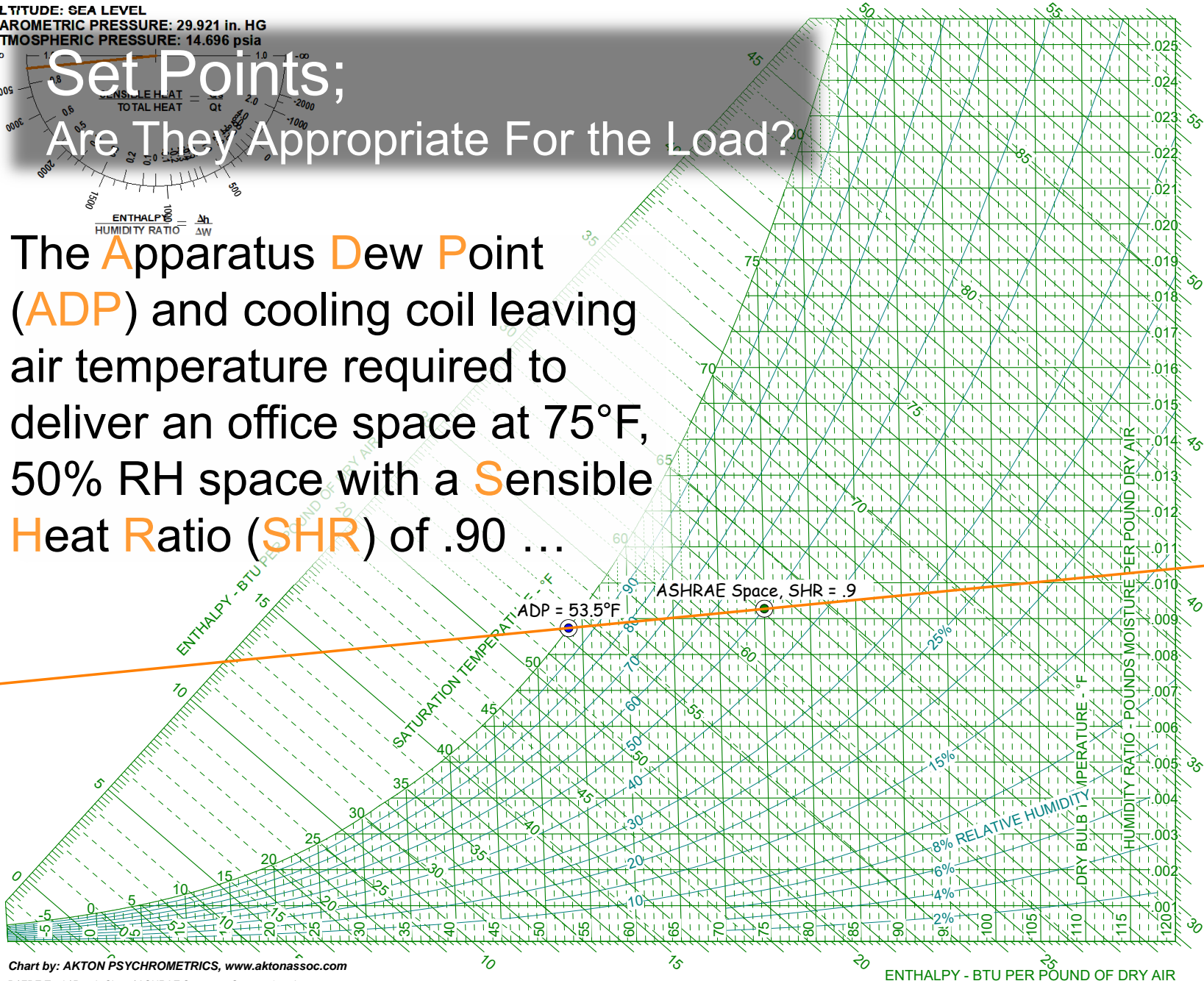
Set Points

Are They Appropriate for the Load?

ALTITUDE: SEA LEVEL
BAROMETRIC PRESSURE: 29.921 in. HG
ATMOSPHERIC PRESSURE: 14.696 psia

Set Points; Are They Appropriate For the Load?

The Apparatus Dew Point (ADP) and cooling coil leaving air temperature required to deliver an office space at 75°F, 50% RH space with a Sensible Heat Ratio (SHR) of .90 ...



ALTITUDE: SEA LEVEL
BAROMETRIC PRESSURE: 29.921 in. HG
ATMOSPHERIC PRESSURE: 14.696 psia

Set Points; Are They Appropriate For the Load?

... will be much different from
what is required to deliver a
surgery with the same SHR but
at 65°F/60% RH

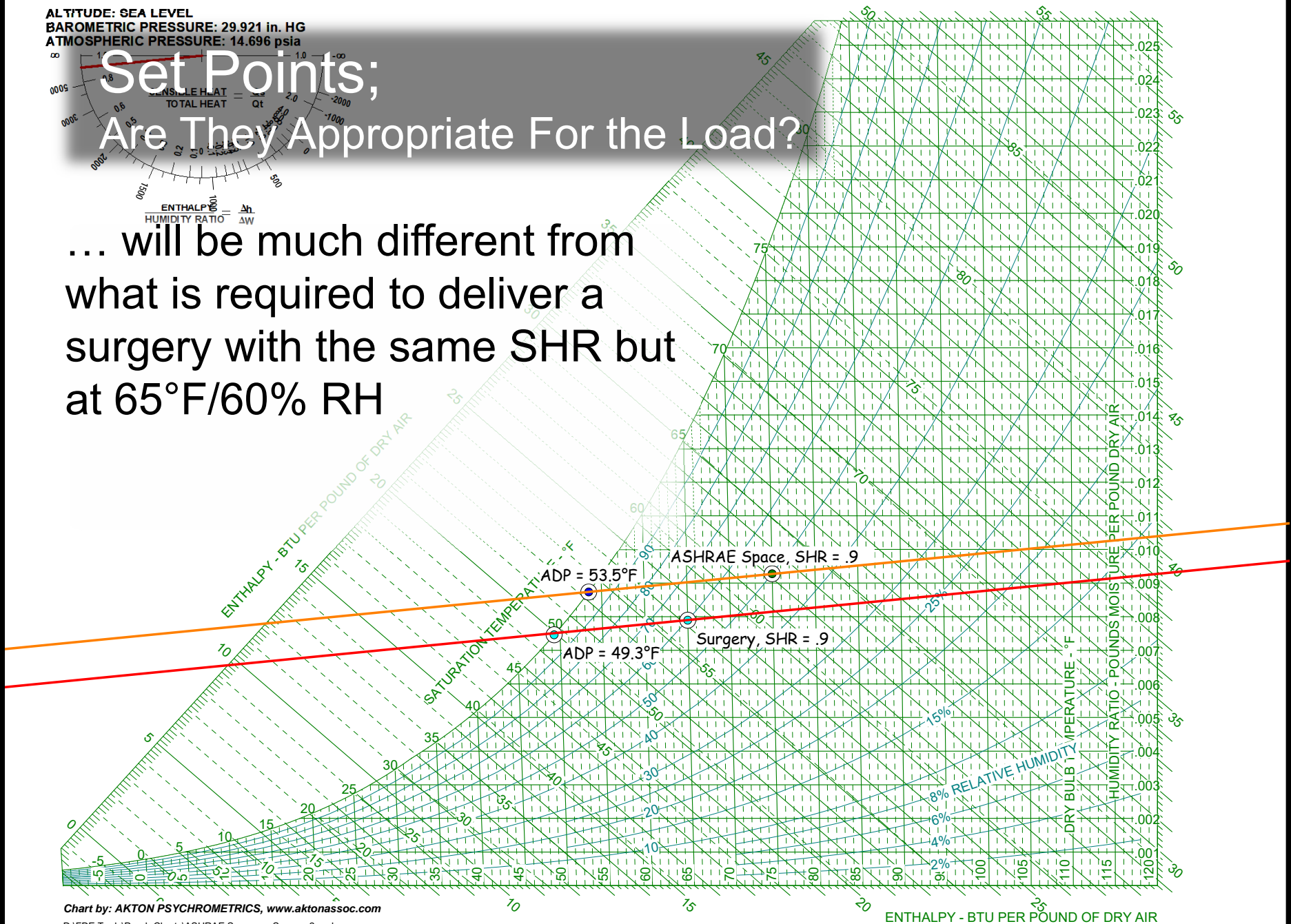


Chart by: AKTON PSYCHOMETRICS, www.aktonassoc.com

D:\FDE Tools\Ppsych Charts\ASHRAE Space vs. Surgery 2.aad

Set Points;

Set Point Reset; Not 1 Size Fits All?

- In the San Francisco Bay area, it is not uncommon to see Air Handling Unit (AHU) Leaving Air Temperature (LAT) reset schedules that reset the LAT to 65°F (or higher) under low load conditions
- The same reset schedule may be a really bad idea in hot and humid climates like St. Louis, Missouri or Honolulu Hawaii



Set Points

Are They Appropriate for the Equipment Selections?

Set Points; Are They Appropriate for the Equipment Selection?

Two Cooling Towers Selected for the Same Load Requirement

- Best first cost tower
 - 60 bhp
 - 69.5 gpm/hp
 - \$7,230 per year for fan energy
- Best life cycle cost tower
 - 40 bhp
 - 105.8 gpm/hp
 - \$4,810 per year for fan energy
 - Fan energy savings = \$2,420 per year

UPDATE™ Version 5.2.0
Product Data: 11/14/2016 (Current)

© 2016 SPX Cooling Technologies, Inc.
11/26/2016 12:54:44 PM

Job Information

Region North America
Product Type Cooling Towers
Electrical Source 60 Hz
Labor Rate 50 USD/h

Selected By

Facility Dynamics Engineering David Sellers
NW Satellite Office Tel 503-286-1494
8560 North Buchanan Avenue
DSellers@FacilityDynamics.com

SPX Cooling Technologies Contact

TraneOregon
7257 SW Kable Lane Tel 503-620-8031
Portland, OR
ddriver@trane.com

Design Conditions

Solve For Capacity
Tolerance Under Design 5 %
Number of Cells 2
Tower Water Flow 3450 gpm
Hot Water Temperature 86 °F
Cold Water Temperature 76 °F
Total Heat Load 17216000 Btu/h
Wet-Bulb Temperature 66 °F

Evaluation Parameters

Energy Cost 0.08 \$/kWh
Annual Operating Time 2000 h
Evaluation Period 1 years
Interest Rate 10 %
Cold Water Set Point 76 °F
Average Wet-Bulb 66 °F
Range at Avg. Wet-Bulb 10 °F
Maximum Wet-Bulb 66 °F
Wet-Bulb Profile Linear
Fan Operation Single-Speed
Motor Efficiency 90 %

Advanced

Sound Requirements

Calculation Single Cell
Location Air Inlet
Distance from Product 5 ft
Maximum SPL NA

Product

NC Steel

Sound Location

Air Inlet Face

Selections

Model	Cells	Status	Fan Motor Output BHp	Total Fan Motor Output BHp	Capacity	Cost Ratio	ASHRAE 90.1 Perf. gpm/hp	Fan Energy Cost \$	Pump Energy Cost \$	dBA Single Cell
NC8405UAN2	2	Caution	50.0	100.0	99.2%	0.92	41.5	12050	1667	84
NC8405ULN2	2	Caution	50.0	100.0	97.9%	0.92	41.0	12050	1667	82
NC8405TAS2	2	Caution	40.0	80.0	99.0%	1.00	51.7	9640	1667	84
NC8405UAS2	2	CTI	50.0	100.0	103.5%	1.00	43.2	12010	1667	84
NC8405TSL2	2	Caution	40.0	80.0	97.2%	1.00	50.9	9640	1667	81
NC8405ULS2	2	CTI	50.0	100.0	102.3%	1.01	42.7	12020	1667	82
NC8407SAN2	2	CTI	30.0	60.0	100.0%	1.03	70.2	7230	1667	81
NC8407SLN2	2	Caution	40.0	80.0	99.2%	0.92	41.5	12050	1667	82
NC8407TAN2	2	CTI	40.0	80.0	109.2%	1.04	57.3	9520	1667	83
NC8407UAN2	2	CTI	50.0	100.0	117.4%	1.05	49.2	11790	1667	85
NC8407TLN2	2	CTI	40.0	80.0	105.3%	1.06	55.3	9570	1667	80
NC8407ULN2	2	CTI	50.0	100.0	115.6%	1.06	48.4	11810	1667	83
NC8407VAN2	2	CTI	60.0	120.0	123.1%	1.10	42.9	14070	1667	86
NC8407RAS2	2	Caution	25.0	50.0	98.8%	1.11	83.1	6030	1667	80
NC8407VLN2	2	CTI	60.0	120.0	121.2%	1.11	42.2	14090	1667	84
NC8407SAS2	2	CTI	30.0	60.0	104.8%	1.11	73.4	7180	1667	81
NC8407RLS2	2	Caution	25.0	50.0	97.4%	1.12	81.9	6030	1667	75
NC8407SLS2	2	CTI	30.0	60.0	106.0%	1.12	74.0	7170	1667	78
NC8407TAS2	2	CTI	40.0	80.0	114.2%	1.13	59.8	9470	1667	83
NC8409QAN2	2	CTI	20.0	40.0	100.2%	1.13	105.8	4810	1667	82

Set Points;

Are They Appropriate for
the Equipment Selection?

Two Cooling Towers Selected for
the Same Load Requirement

- Best first cost tower
 - 60 bhp
 - 69.5 gpm/hp
 - \$7,230 per year for fan energy
- Best life cycle cost tower
 - 40 bhp
 - 105.8 gpm/hp
 - \$4,810 per year for fan energy
 - Fan energy savings = \$2,420 per year

Its likely that capturing the energy savings will require different set points for control processes related to the cooling tower fan operation

Set Point Bottom Lines

Control logic may be a *one size fit's all* proposition for similar system types and configurations

- The decision tree for operating a large VAV system can probably be applied to any similar system
- The decision tree for staging up the cooling towers for a variable flow, water cooled, primary only chiller plant can probably be applied to any similar system

Set Point Bottom Lines

The set points used by the *one size fit's all* decision tree will need to be tailored to the climate, load characteristics and equipment characteristics for each application

- The economizer high limit set point associated with the logic for a large VAV system in San Francisco, CA will be different for that same logic applied in St. Louis, MO
- The cooling tower staging and condenser water reset schedule will be different for a for a variable flow, water cooled, primary only chiller plant that has a mix of chiller types and sizes as compared to a plant with identical machines

Control System Building Blocks

*Automatically **adjust a piece of machinery** to give us what we want by comparing **what is going on** to **what we want** to go on and **making appropriate adjustments** to the process we want to control*

Inputs

Outputs

Control Process

Set Point

Measure the process variable

Adjust the controlled variable

Logic and mechanisms that tries to bring the controlled variable into agreement with the set point

Our requirements for the process that is under control, which can be fixed or variable

Control System Building Blocks

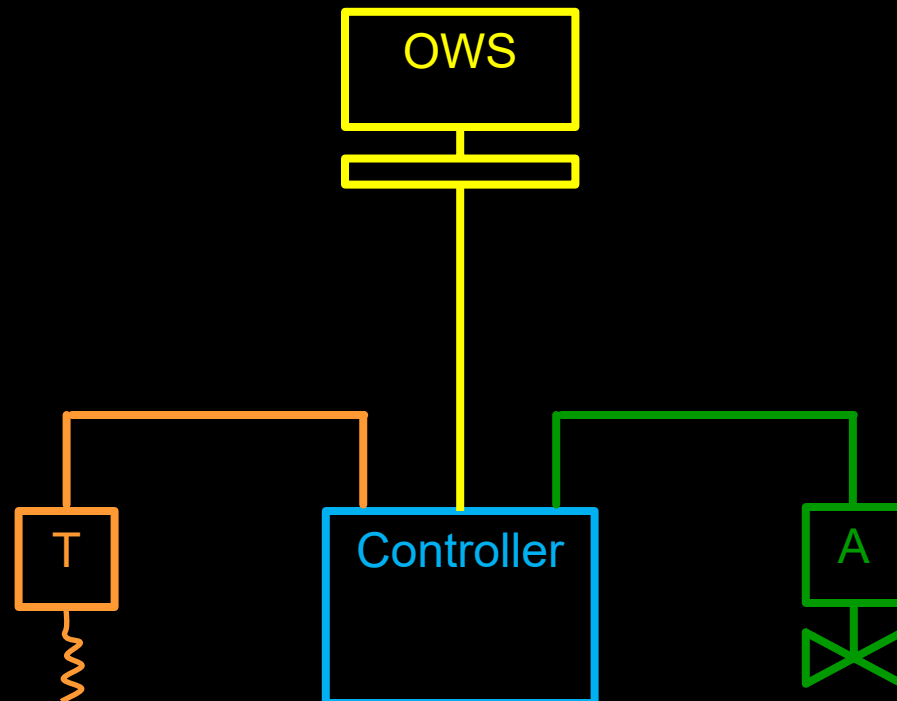
Automatically *adjust a piece of machinery* to give us what we want by comparing *what is going on* to *what we want* to go on and *making appropriate adjustments* to the process we want to control

Inputs

Outputs

Control Process

Set Point



Control System Building Blocks

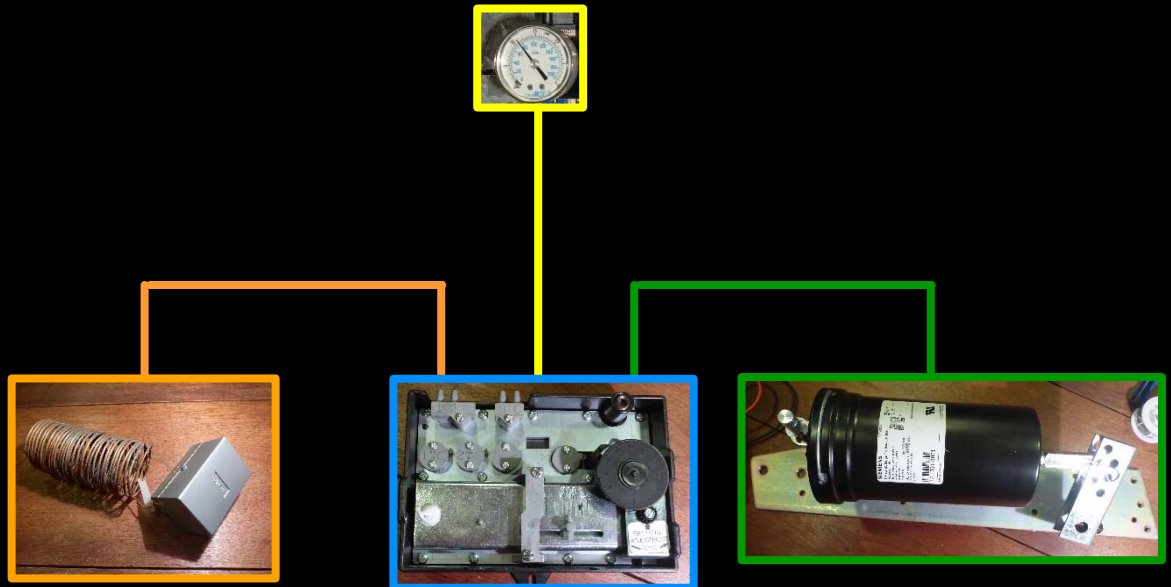
Automatically *adjust a piece of machinery* to give us what we want by comparing *what is going on* to *what we want* to go on and *making appropriate adjustments* to the process we want to control

Inputs

Outputs

Control Process

Set Point

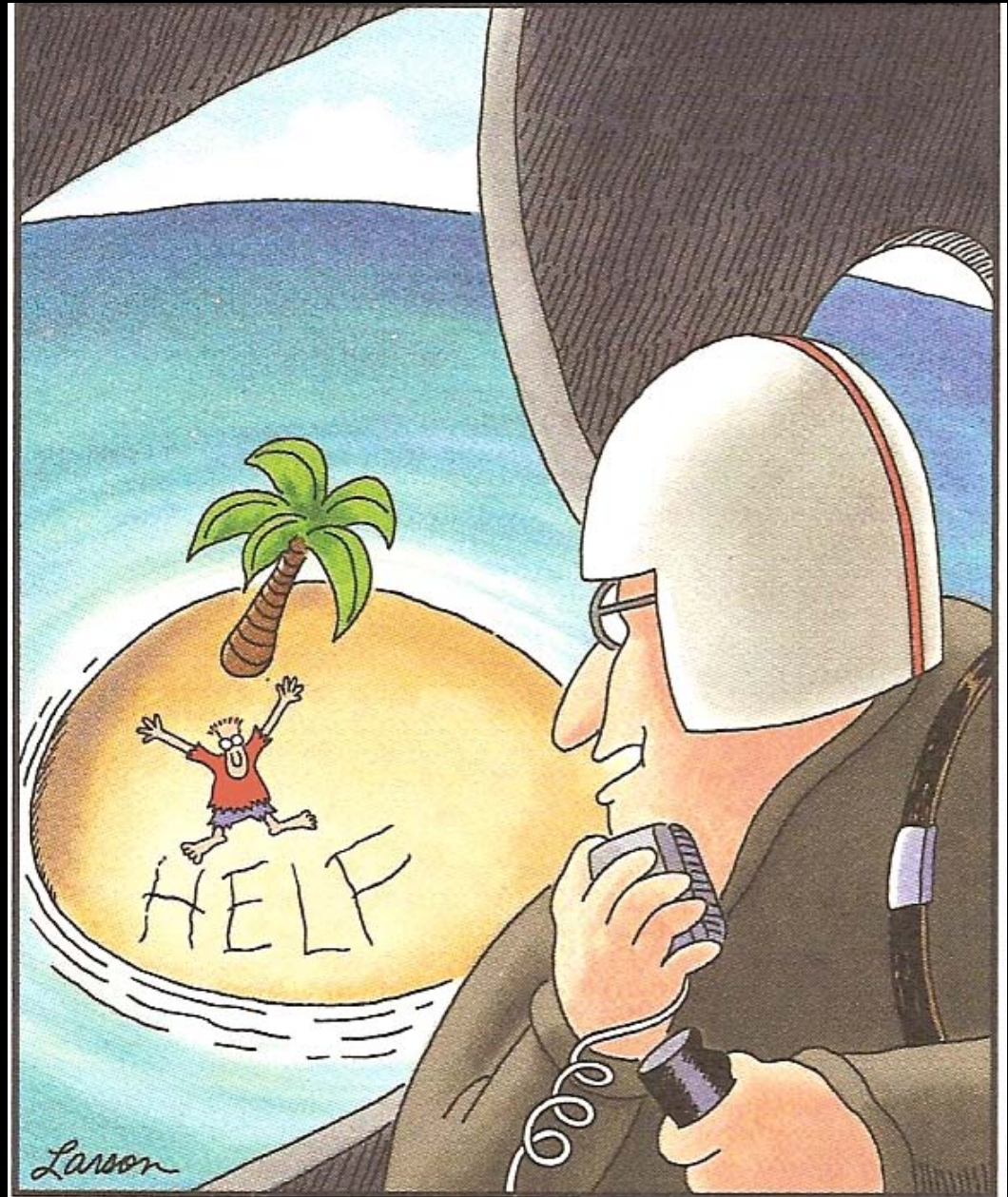


Bottom Lines

- Repeatable, Reliable, Robust control sequences and logic are essential to successfully capturing the design intent
- To be successful:
 - Capture all of the details associated with the design intent
 - Support the logic with repeatable, reliable, robust hardware
 - Support the logic with a physical configuration that will allow it to work as intended

Writing it All Down

- Documenting your sequence is an Excellent idea
- Using the English language to do it may provide a few challenges



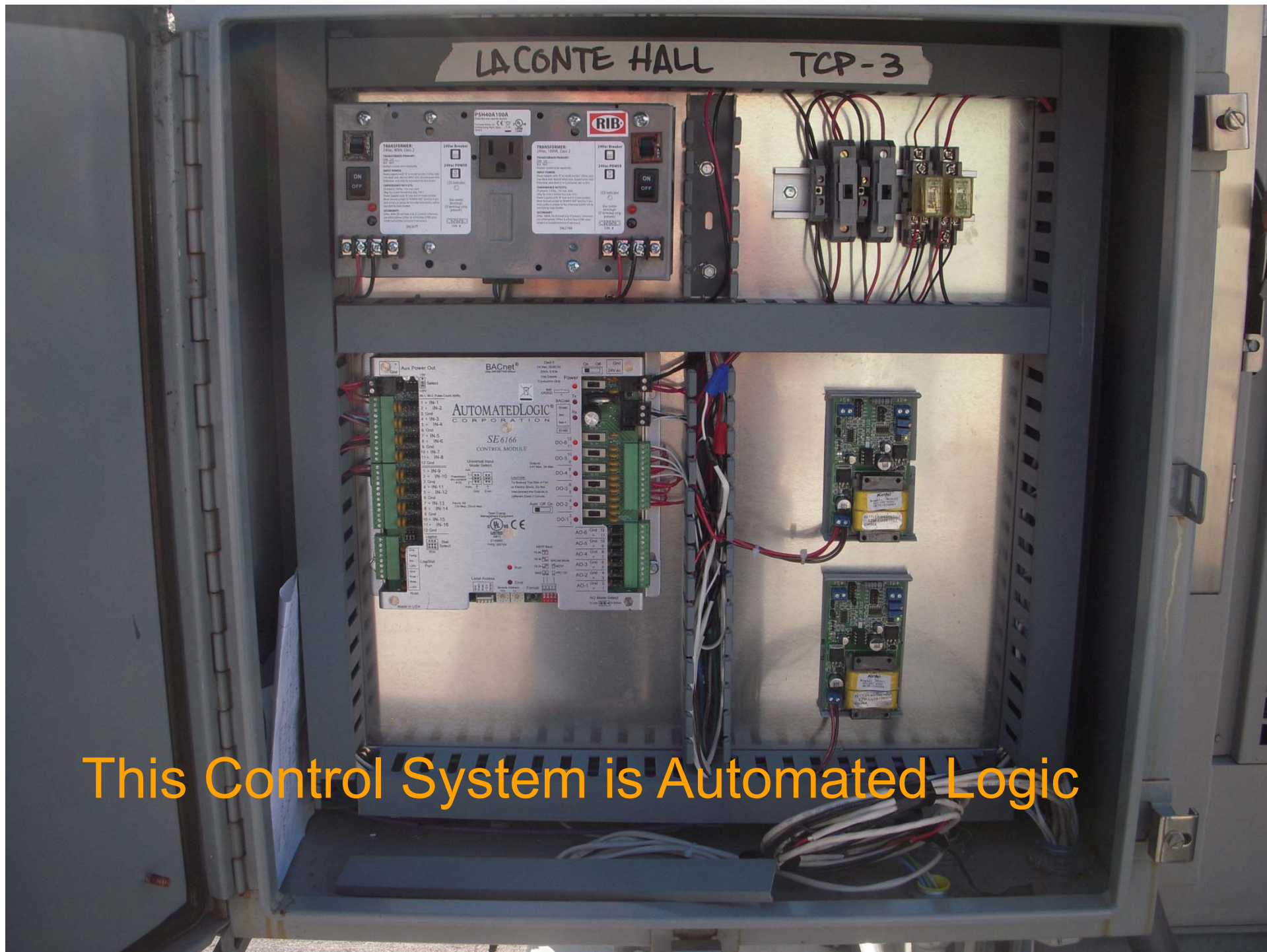
“Wait! Wait! Cancel that. ... I guess it says ‘helf.’”

xpoe#ilpmx

Does the text to the left say
Molly Poom
or
Wood Hollow?



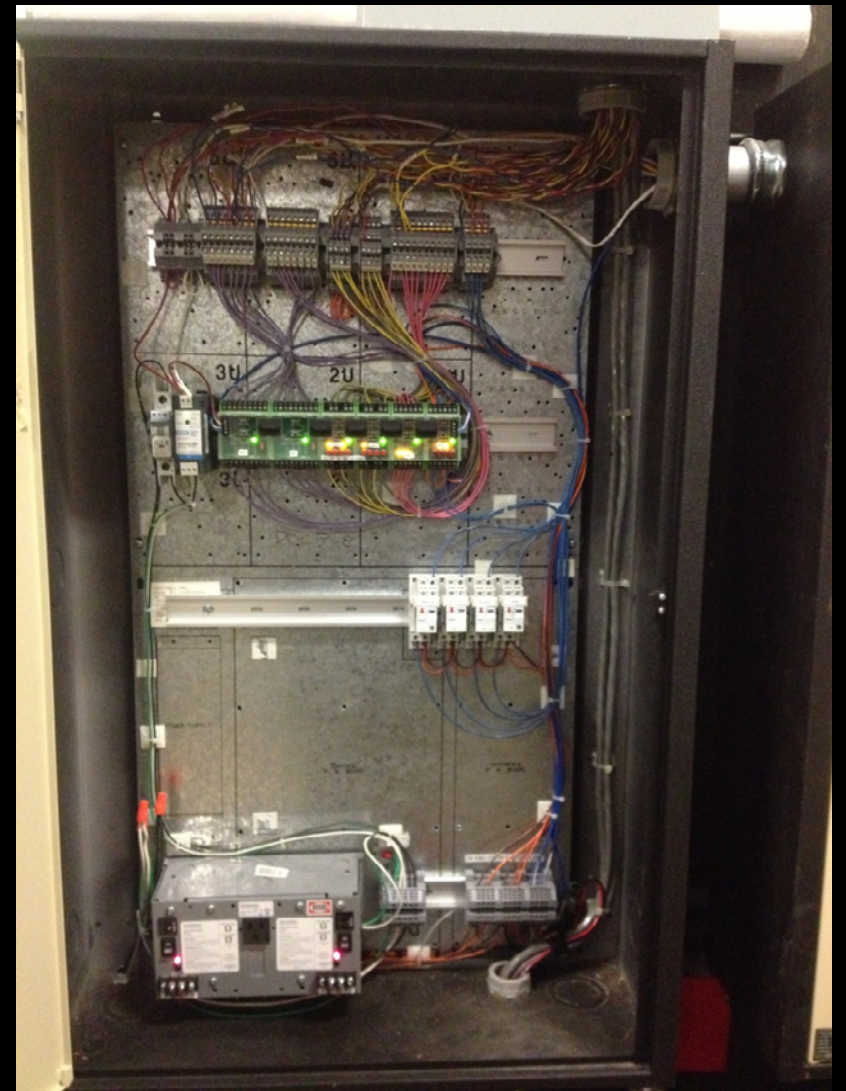
Clear Communication is Important



This Control System is Automated Logic



But in the general sense, so is this one



But in the general sense, so is this one, and this one

A Few Resources

Articles on Developing Control System Design and Logic Sequences

<https://www.av8rdas.com/magazine-articles.html#Controls>

<https://www.av8rdas.com/magazine-articles.html#Lessons>

Logic Diagram Tool with Examples

<https://www.av8rdas.com/logic-diagram-tool.html>

Examples of Control and Logic Standards

<https://www.av8rdas.com/control-and-logic-diagram-standards.html>

Logic Diagram Tools with Simulation Capability

<https://www.av8rdas.com/eikon-for-educators-and-windlgc.html>

Preparing for Next Geeks Class

Preparing for Next Weeks Class

Preparing for Next Weeks Class

1. Read through the article Jay Santos wrote about how to develop a control sequence. It is the file named CSE (02-2008_-_writing_control_sequences_vweb.pdf) which is located with several other articles at the first link in the previous slide.
2. Using the techniques Jay discusses:
 - a. Consider a VAV reheat terminal
 - b. Consider an air handling system with an air side economizer
3. Put together a bullet point or outline sequence of how you would go about controlling them
 - a. What is the primary input required?
 - b. What other inputs are required?
 - c. What needs to be sequenced and how?
 - d. Are there any interlocks required?

Preparing for Next Weeks Class

(Continued)

4. If you need a refresher on how a VAV reheat terminal works, you can review the *Terminal Unit Basics* slide module that is included with the Variable Air Volume Systems; Design Performance and Commissioning Issues class materials at this location.

<https://www.av8rdas.com/pacific-energy-center-design-performance-and-commissioning-issues-classes.html#VAV>

5. If you need a refresher on how an air side economizer works, you will find several modules in the Economizers; Design Performance and Commissioning Issues class materials that will bring you up to speed. The files are located at this location.

<https://www.av8rdas.com/pacific-energy-center-design-performance-and-commissioning-issues-classes.html#Economizers>

You may also find these blog posts to be helpful:

<https://av8rdas.wordpress.com/category/economizers/page/2/>